

HANDSIGHT: A TOUCH-BASED WEARABLE SYSTEM TO INCREASE INFORMATION ACCESSIBILITY FOR PEOPLE WITH VISUAL IMPAIRMENTS

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Chair / Advisor

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Member

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Member

Dr. Gregg Vanderheiden
Dean's Representative



COMPUTER SCIENCE
UNIVERSITY OF MARYLAND



ACTIVITIES OF DAILY LIVING



Getting dressed



Preparing food



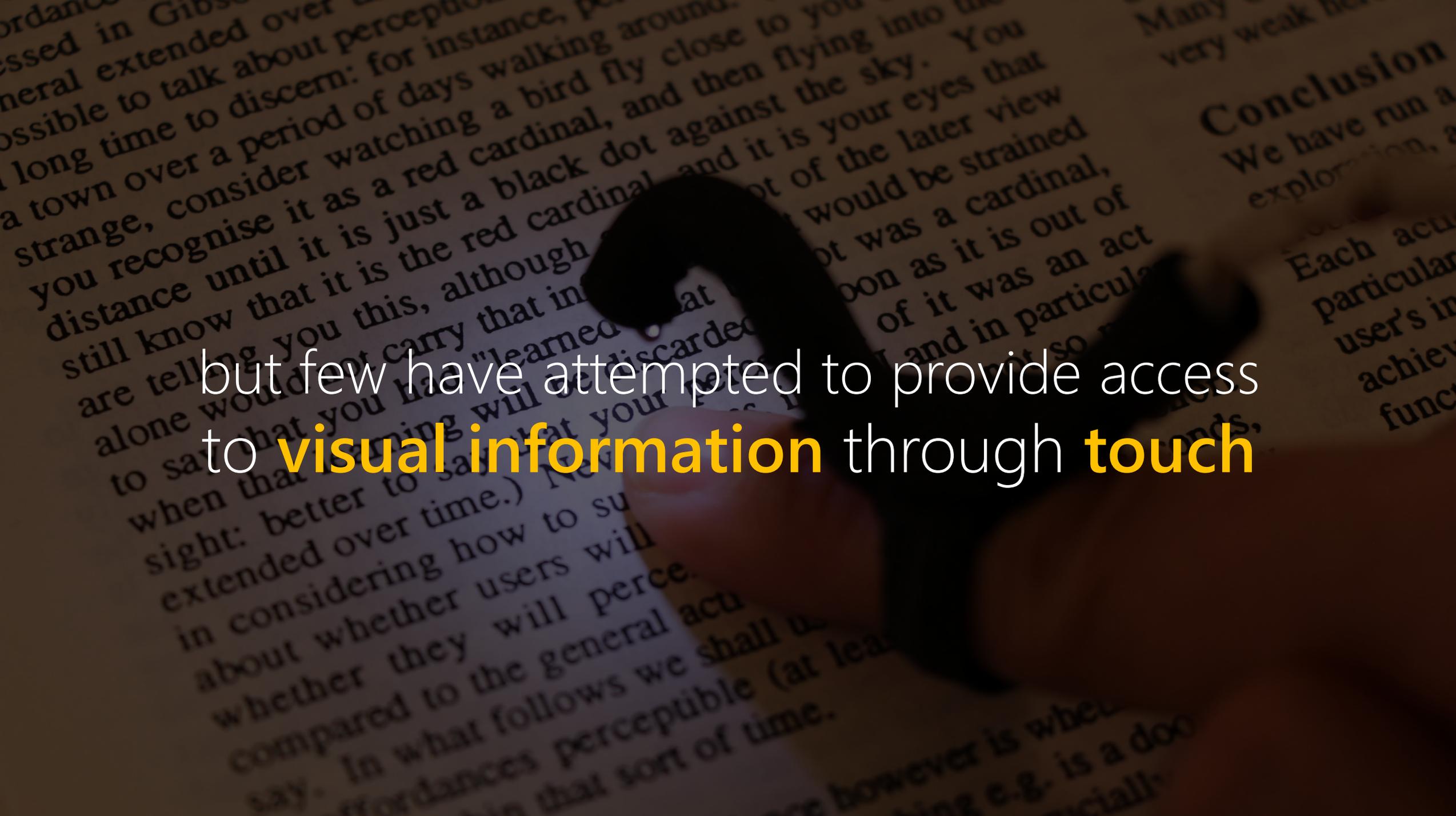
Wayfinding



Shopping



Previous research has used mobile cameras and computer vision for **at-a-distance tasks**

A close-up photograph of a hand touching a page of text. The background text is blurred and appears to be a philosophical or scientific passage. Overlaid on the center of the image is a large text block. The words 'visual information' and 'touch' are highlighted in yellow, while the rest of the text is white.

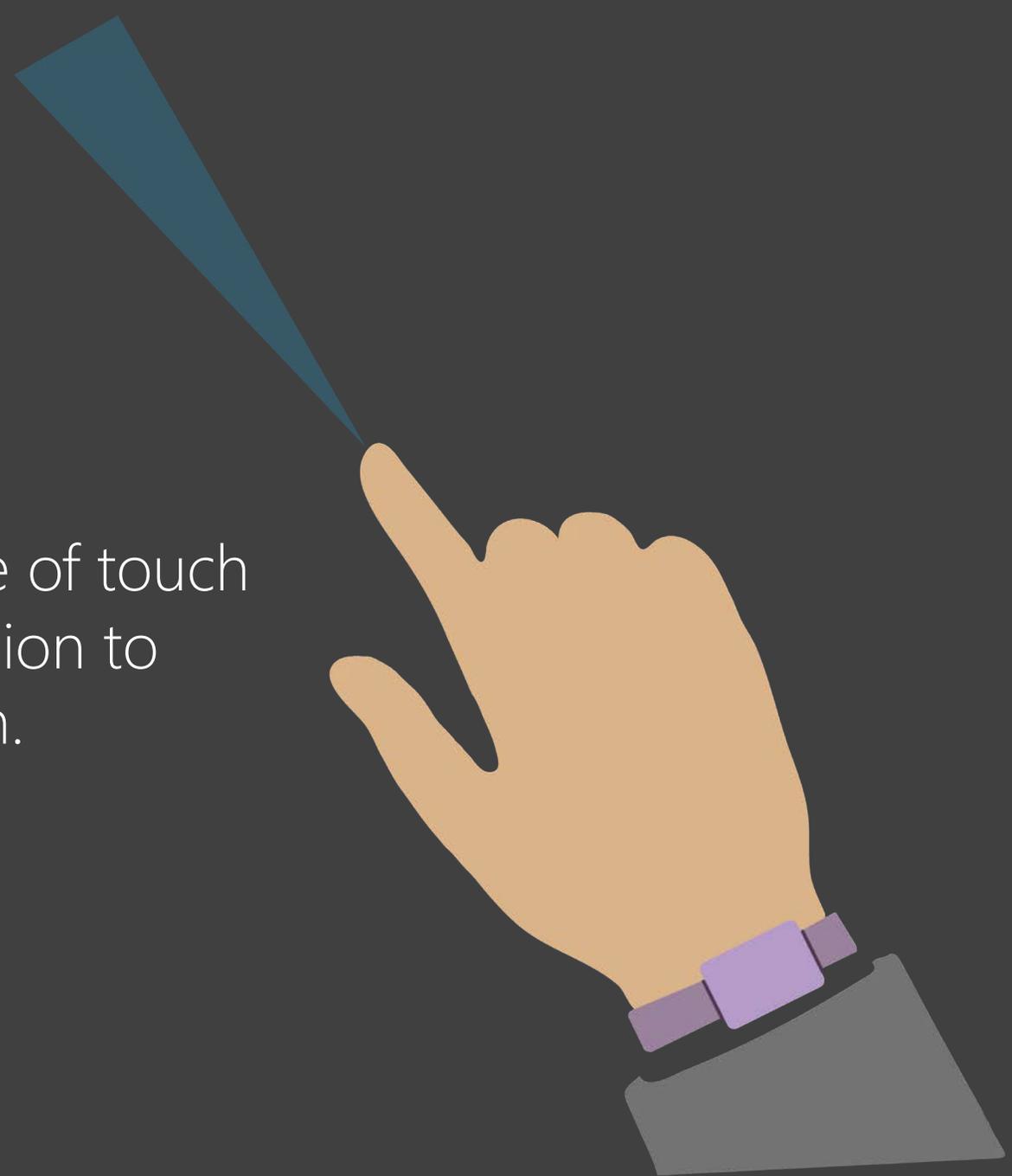
but few have attempted to provide access
to **visual information** through **touch**



For people with visual impairments, touch is a **primary means** of obtaining information about the **physical world**

RESEARCH GOAL

Augment visually impaired users' sense of touch with interactive, real-time computer vision to improve the accessibility of information.





Category #2: access to **digital information** by controlling computers or mobile devices

OPEN QUESTIONS

What is the best method to recognize the content that the user is touching, and how should information about that content be conveyed to the user?

HANDSIGHT

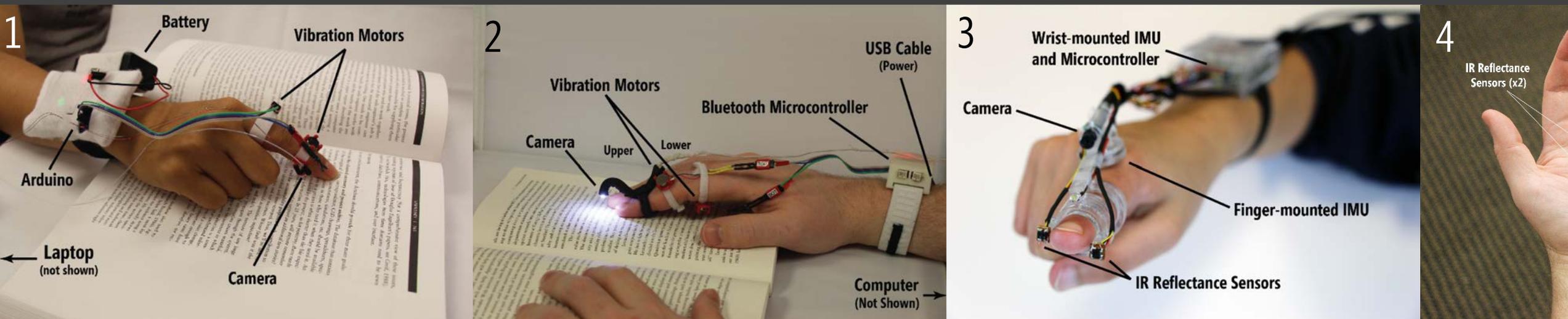
Key aspects:

1. Physical hardware
2. Real-time algorithms
3. Interactive interface
4. Usability evaluations



SUMMARY OF CONTRIBUTIONS

Development and iterative refinement of **HandSight**, a novel wearable system to assist visually impaired users.

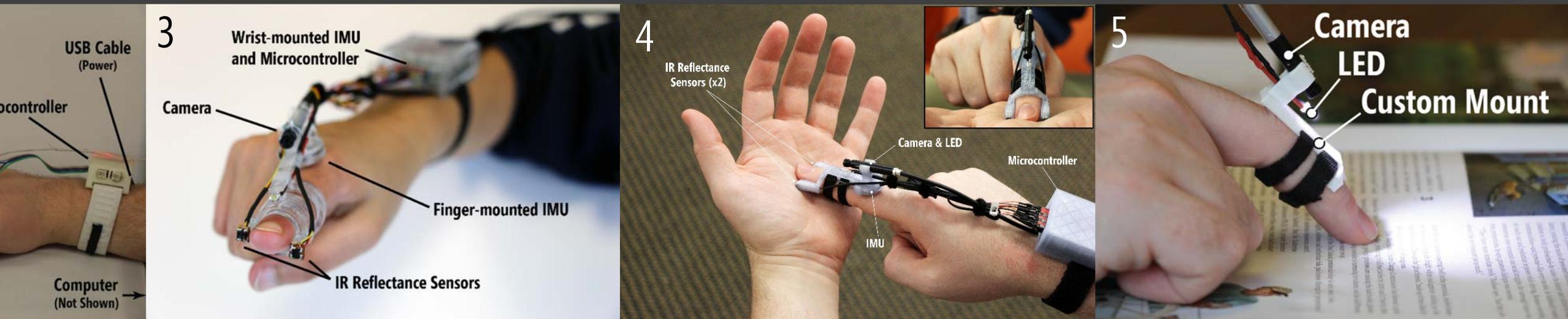


Reading and exploring
printed documents

Controlling mobile devices
through on-body input

SUMMARY OF CONTRIBUTIONS

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Controlling mobile devices
through on-body input

AR Magnification &
Identifying Colors/Patterns

SUMMARY OF CONTRIBUTIONS

Development and iterative refinement of **HandSight**, a novel wearable system to assist visually impaired users.

Findings from **user evaluations** across a diverse set of tasks, which demonstrate advantages and disadvantages of our **finger-worn approach**.

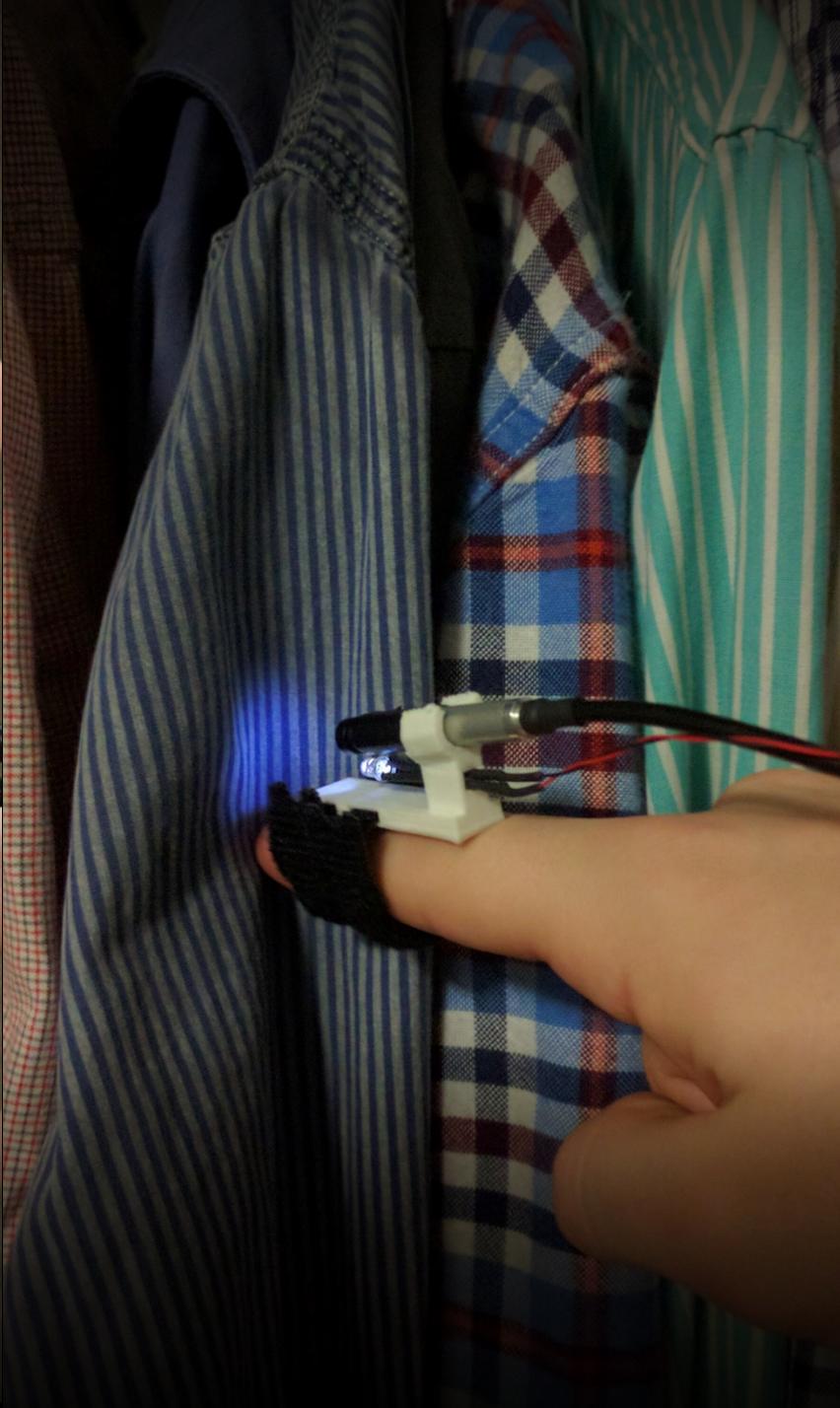
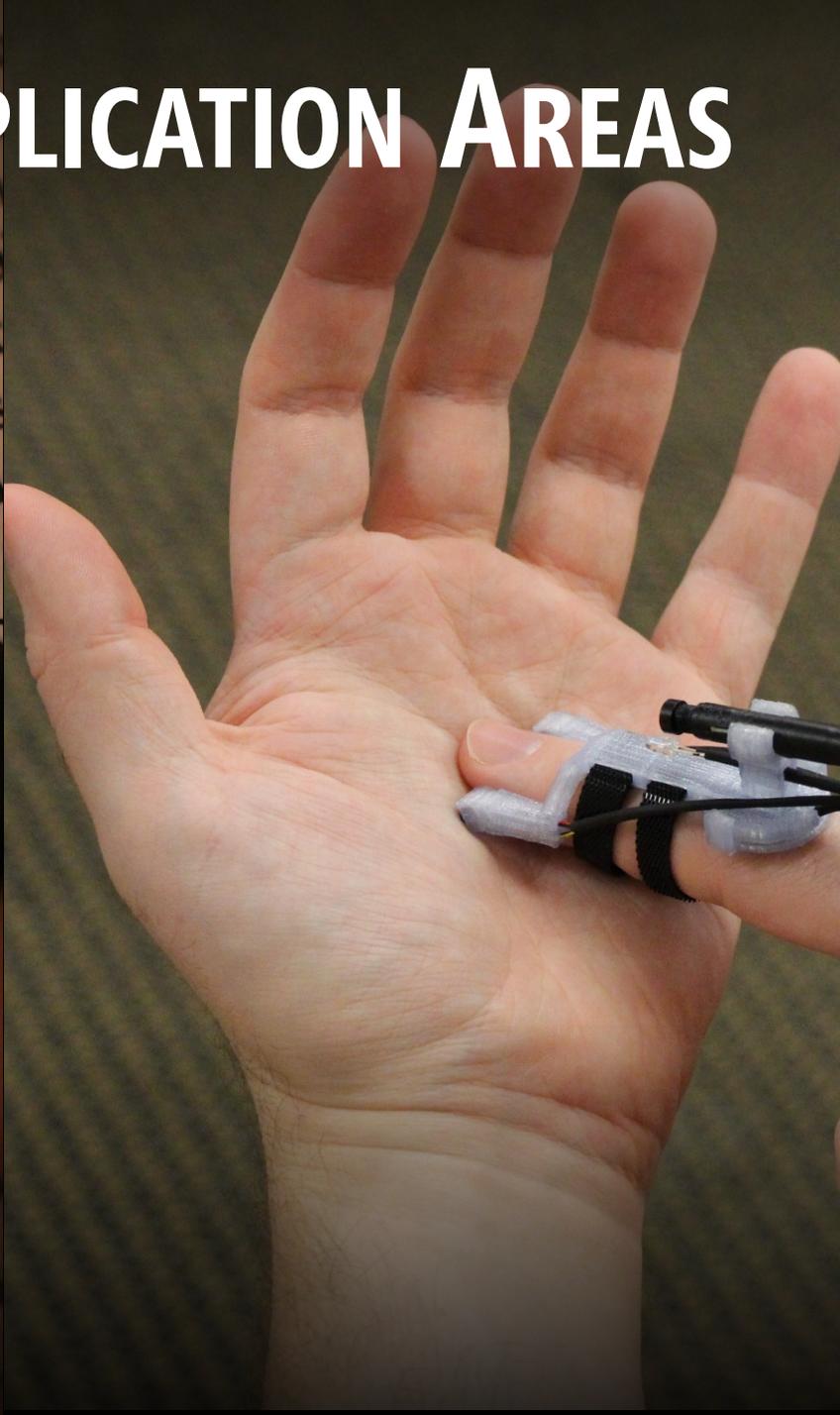
SUMMARY OF CONTRIBUTIONS

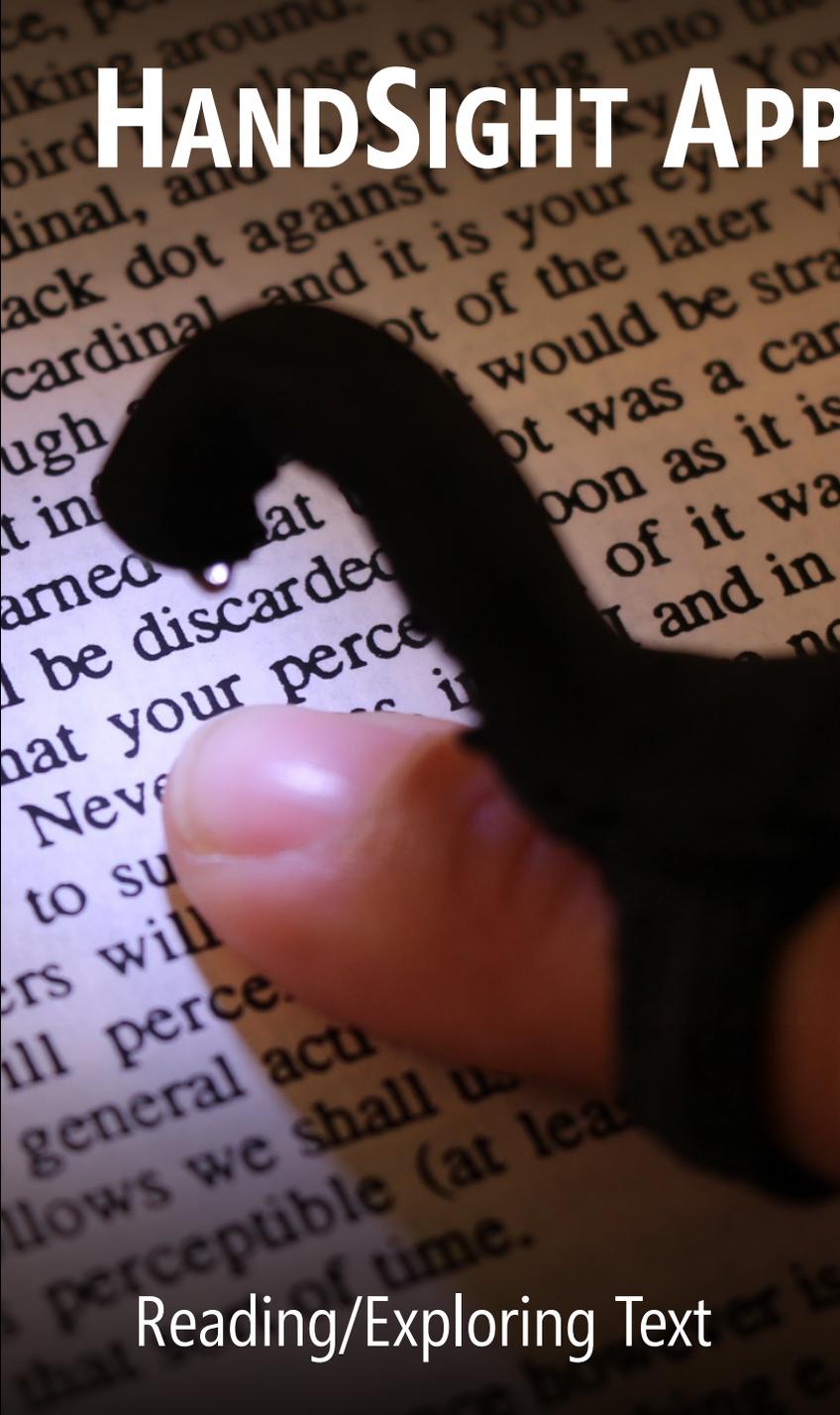
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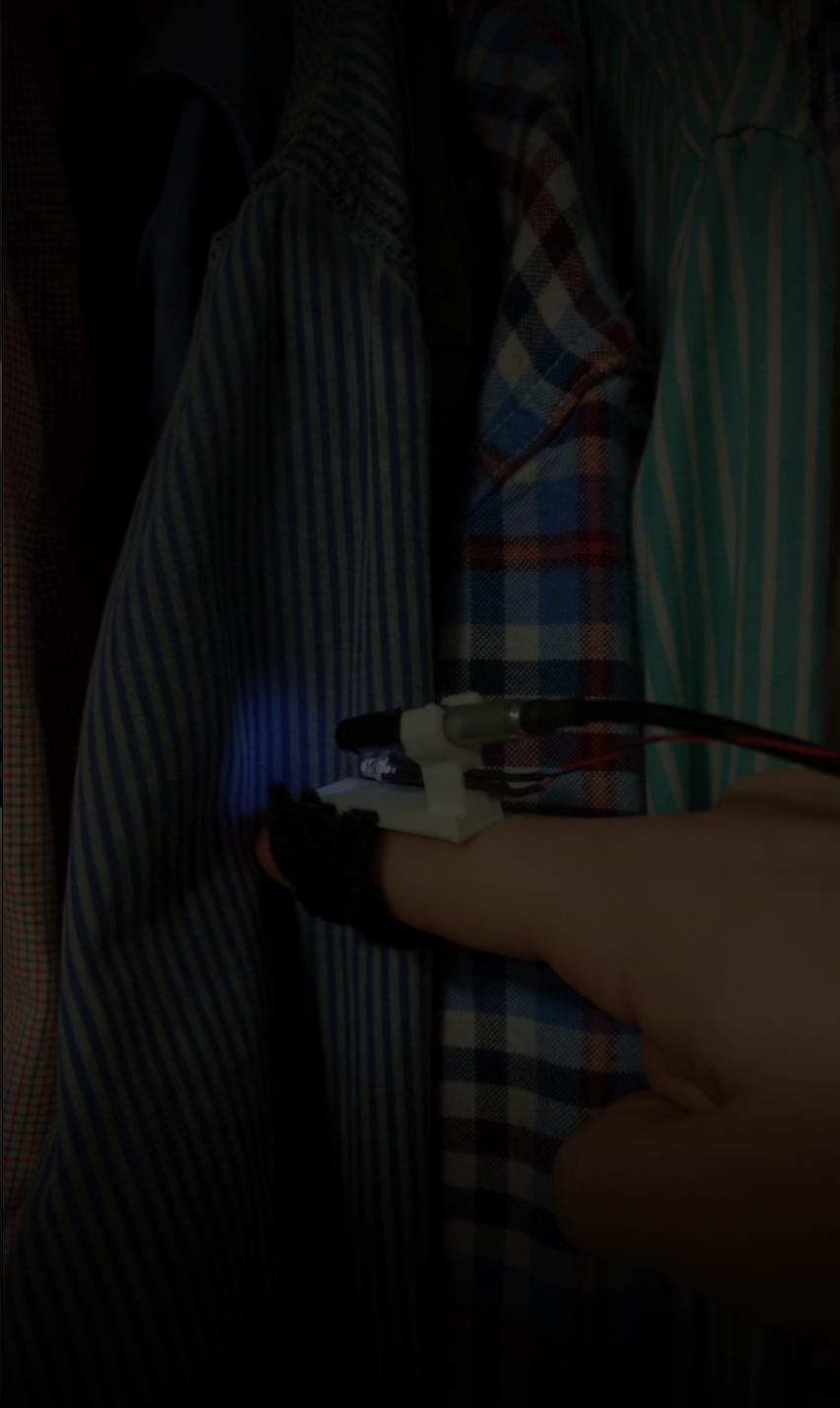
Design Implications for **future wearable assistive systems** and for the fields of accessibility, computer vision, AR and VR, and human-computer interaction.

HANDSIGHT APPLICATION AREAS



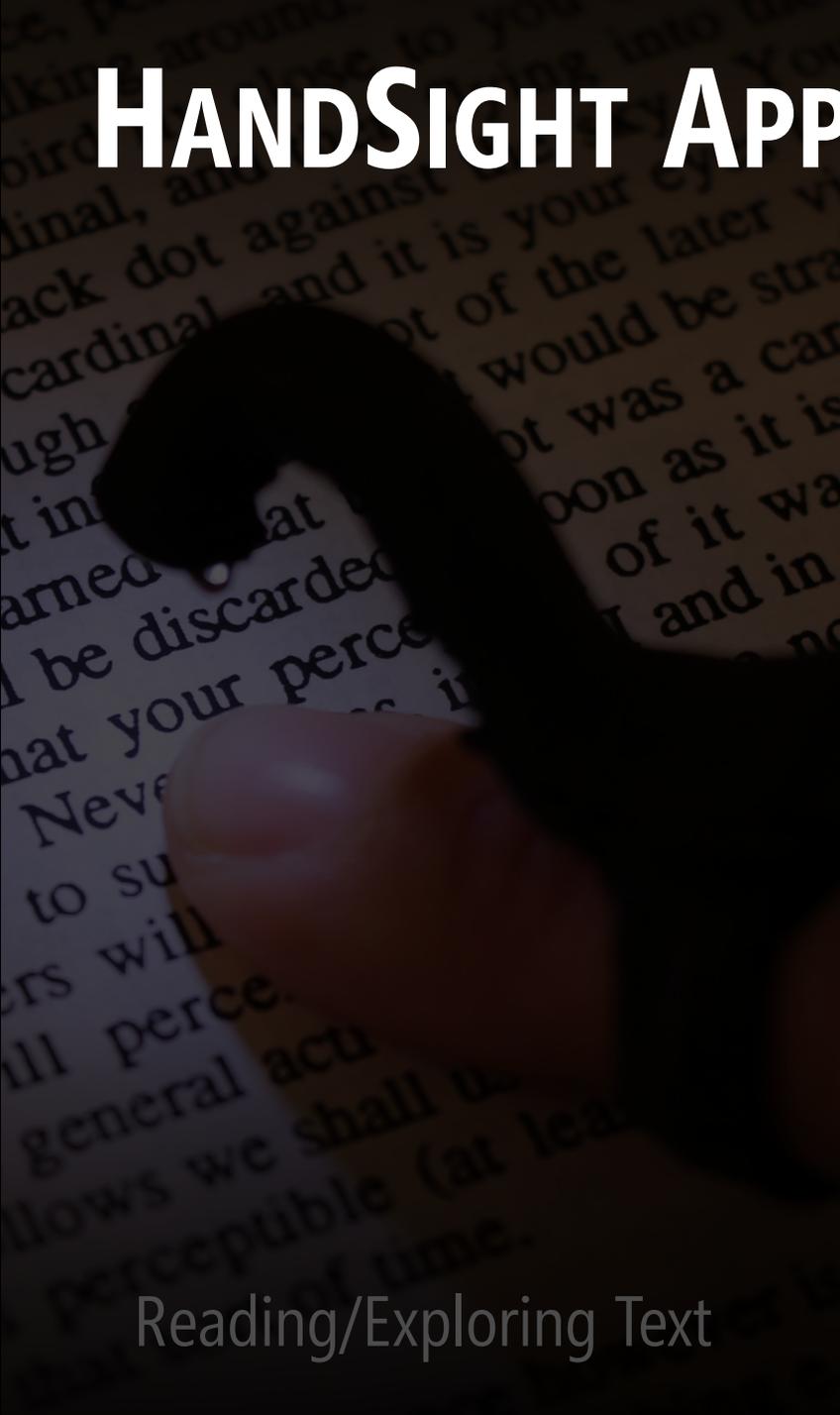


HANDSIGHT APPLICATION AREAS

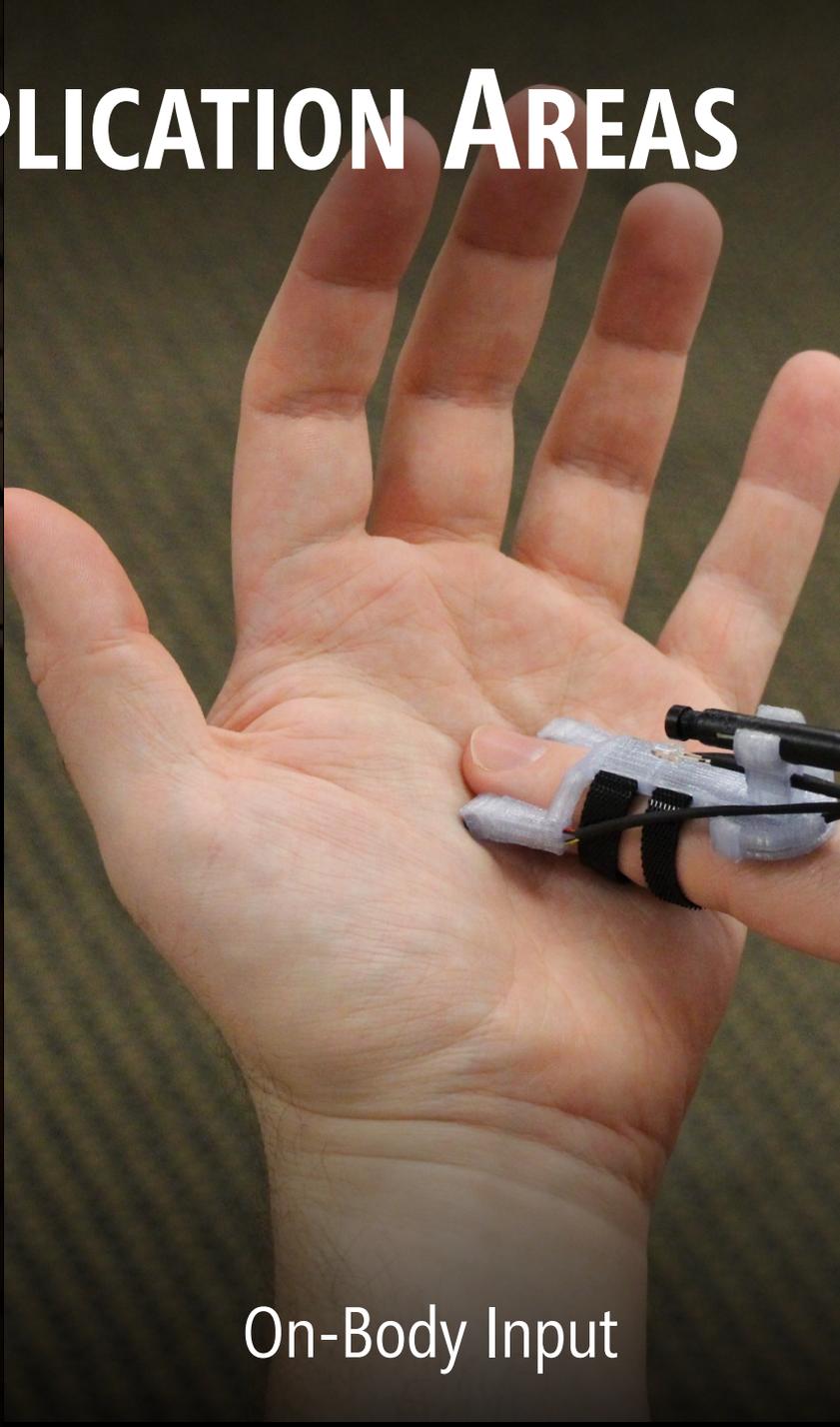


Reading/Exploring Text

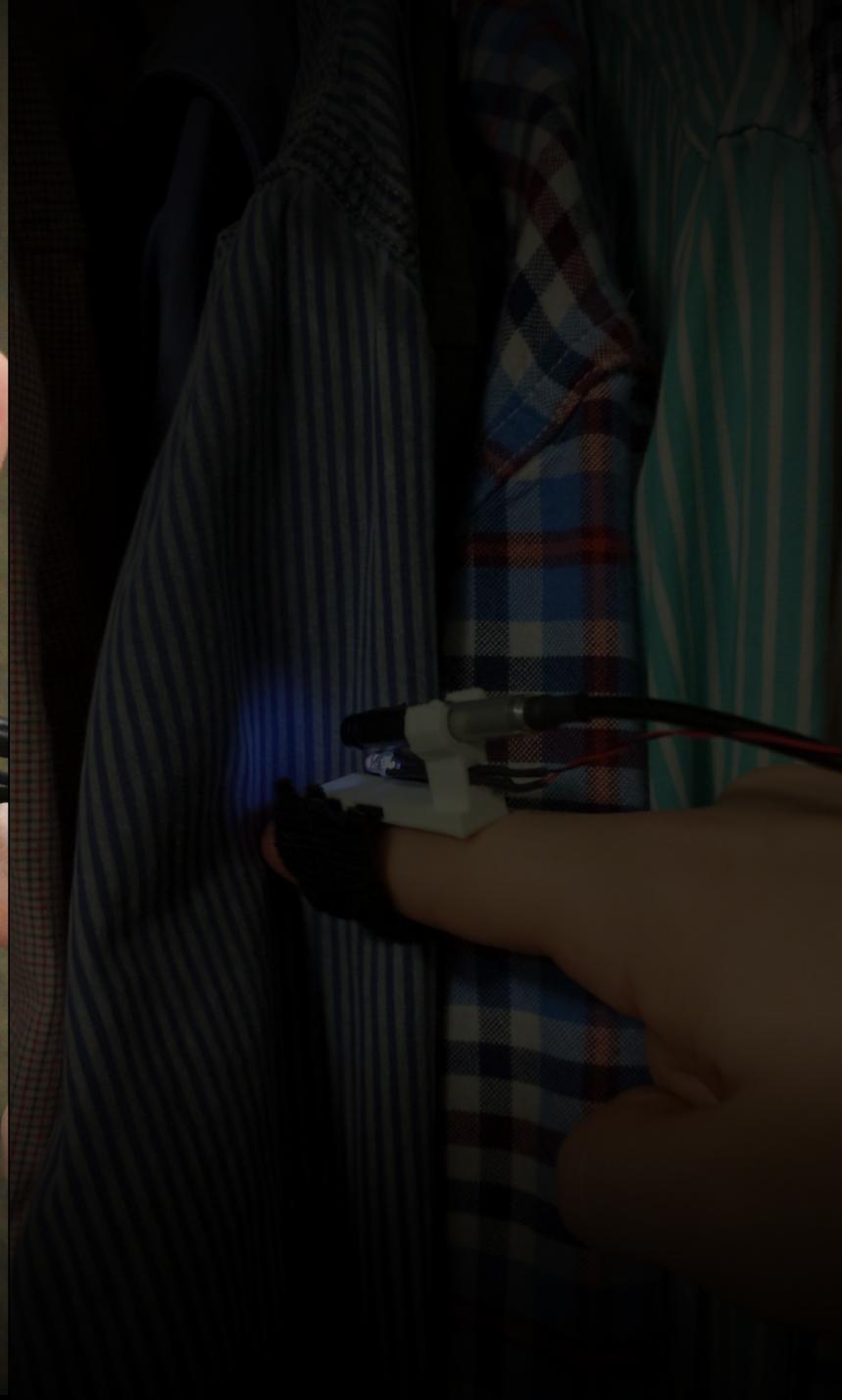
HANDSIGHT APPLICATION AREAS



Reading/Exploring Text



On-Body Input



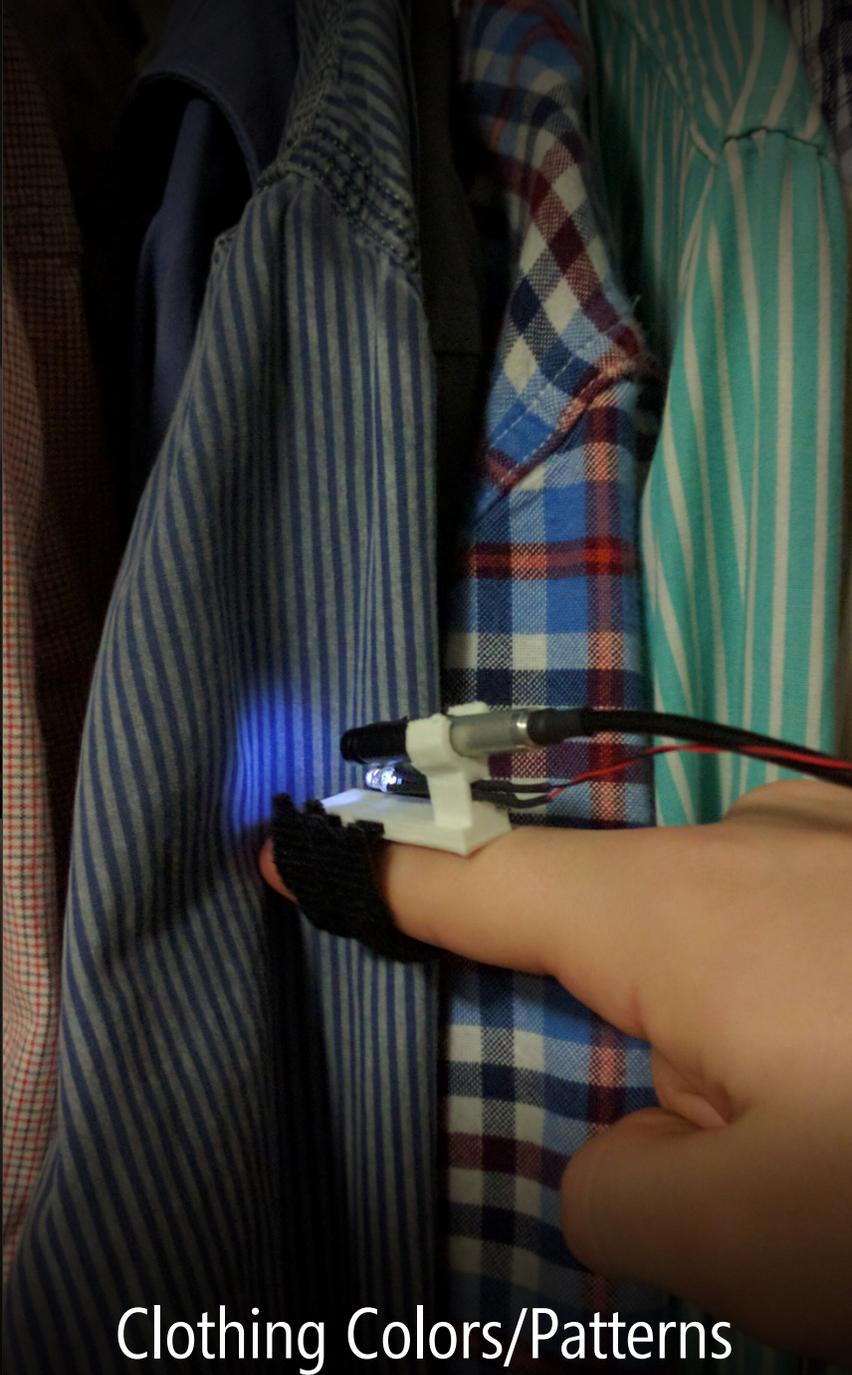
HANDSIGHT APPLICATION AREAS



Reading/Exploring Text

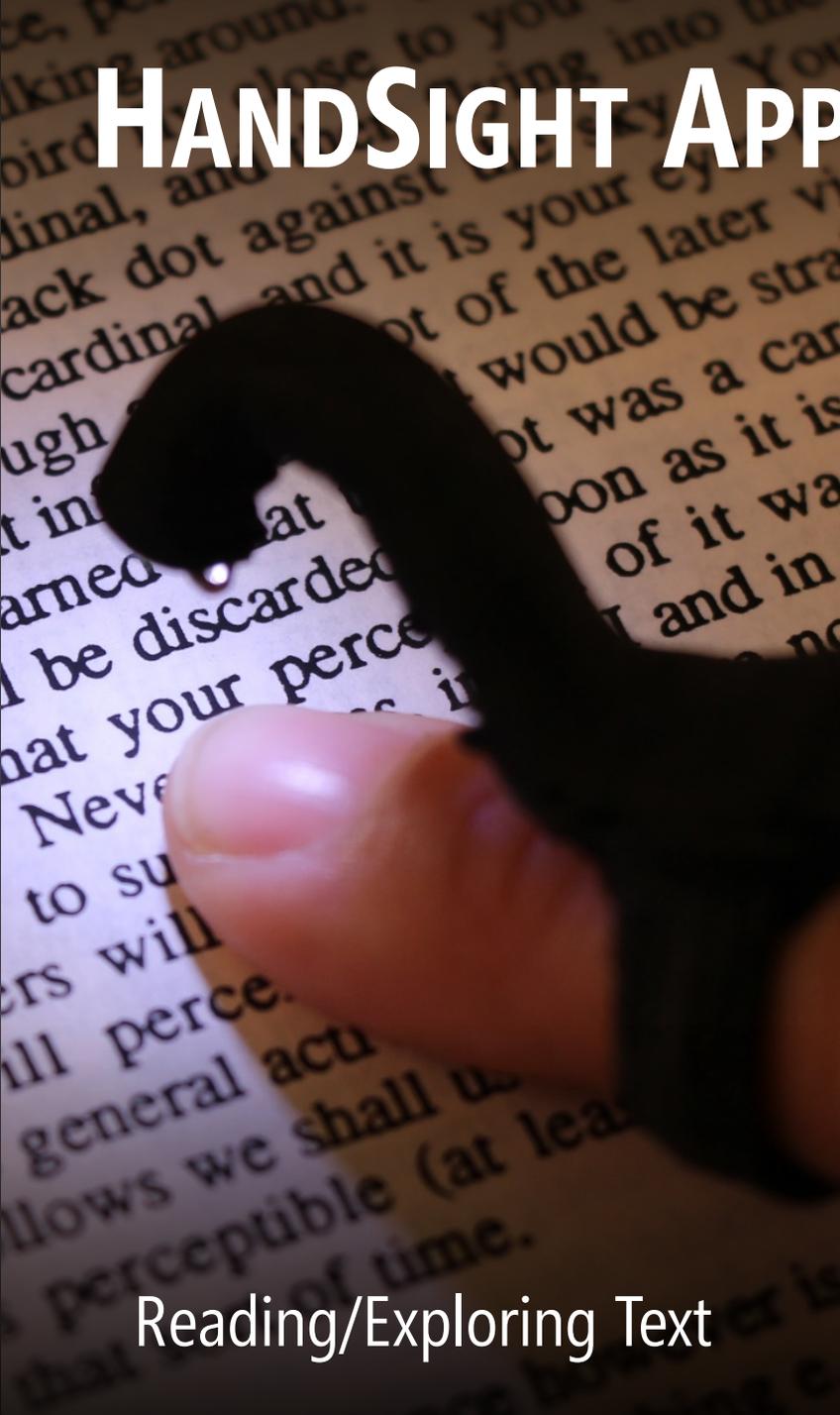


On-Body Input

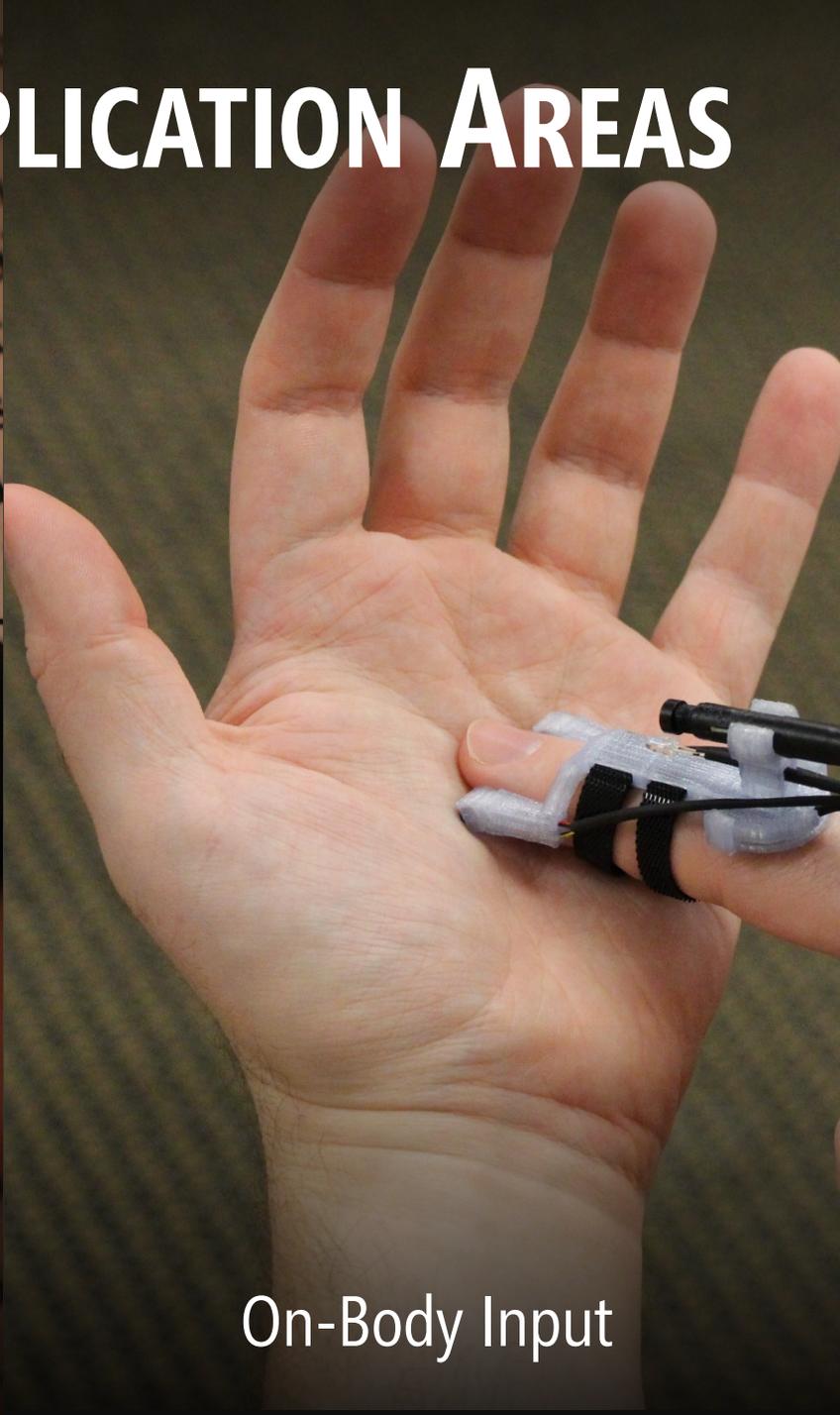


Clothing Colors/Patterns

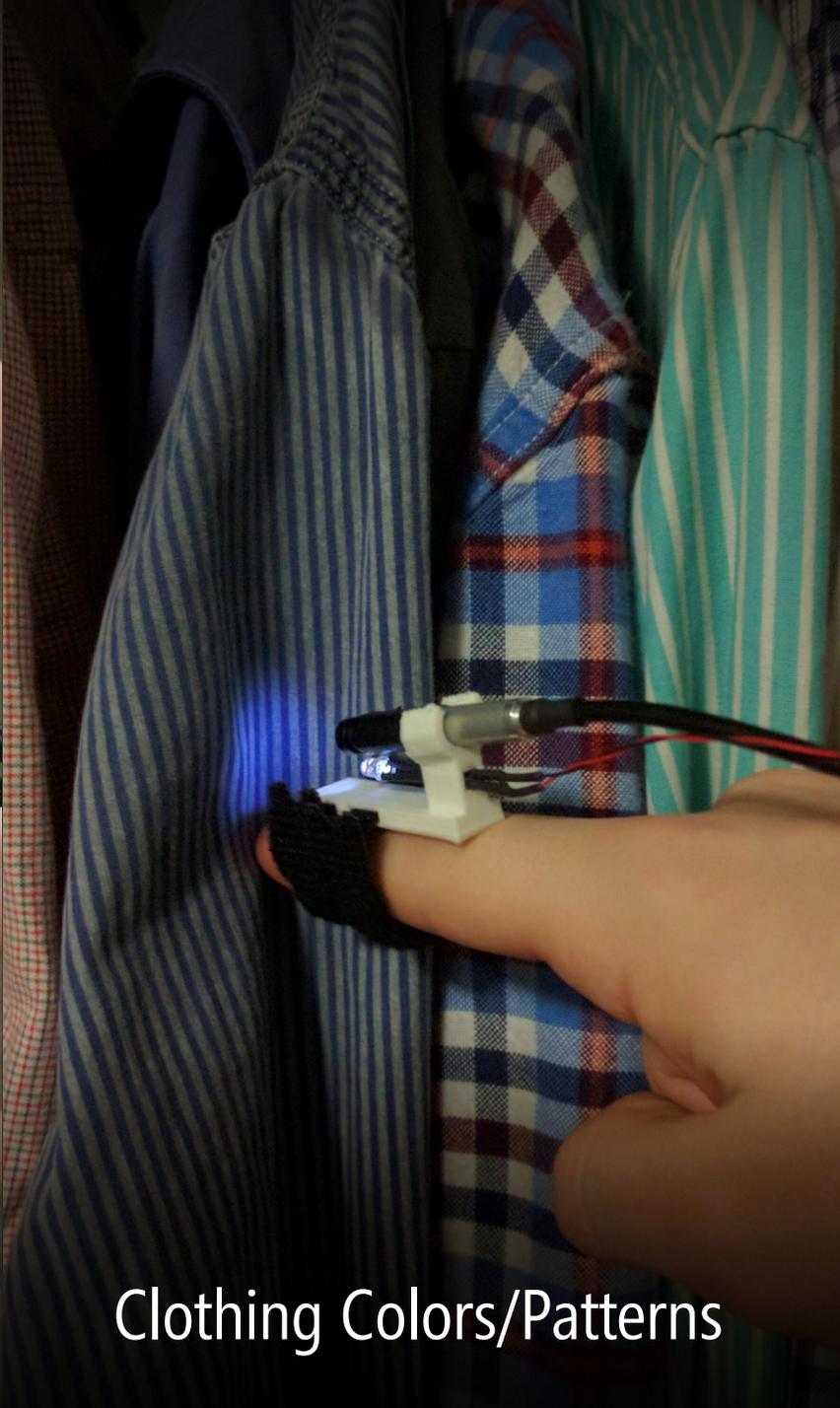
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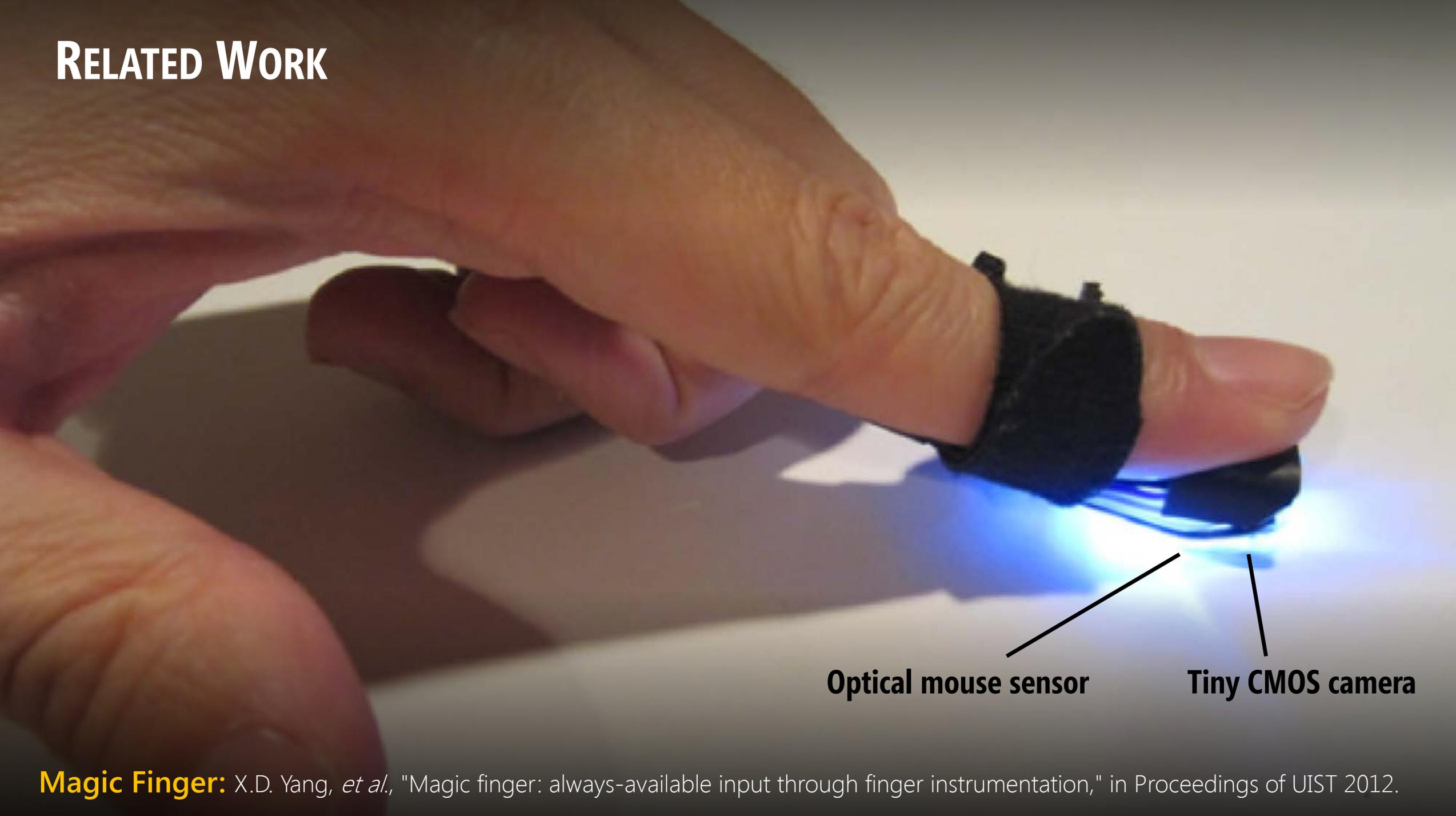


Clothing Colors/Patterns

RELATED WORK



RELATED WORK

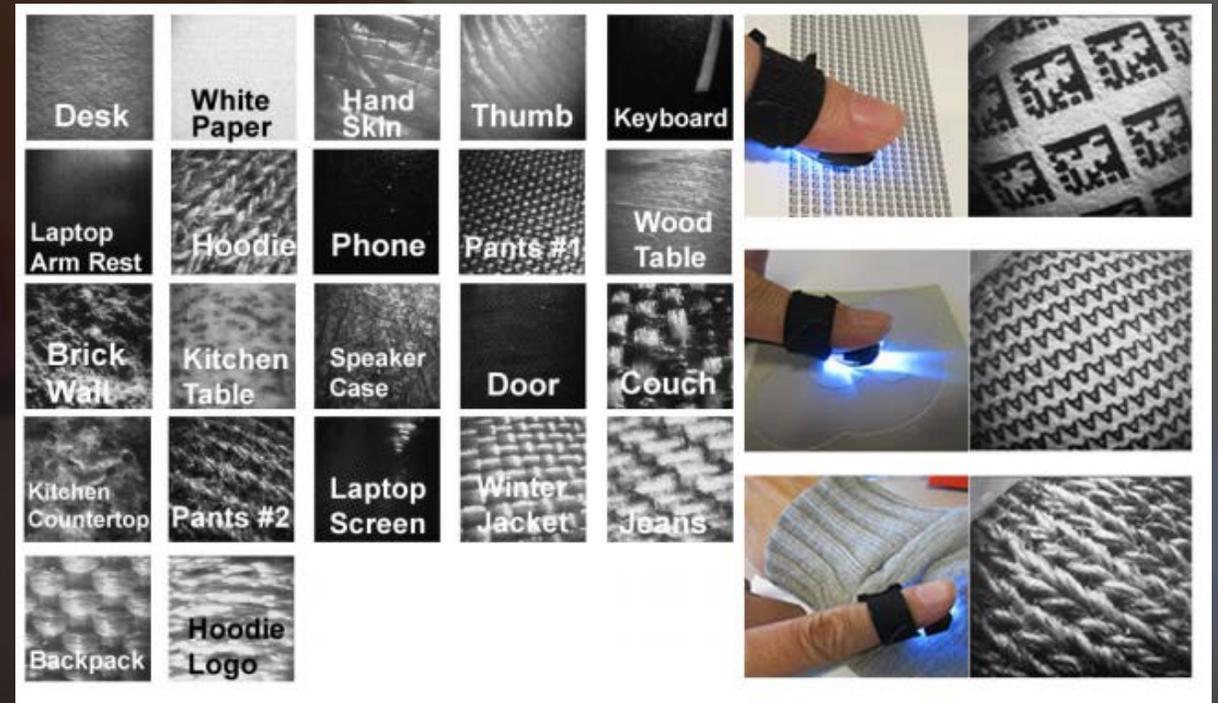
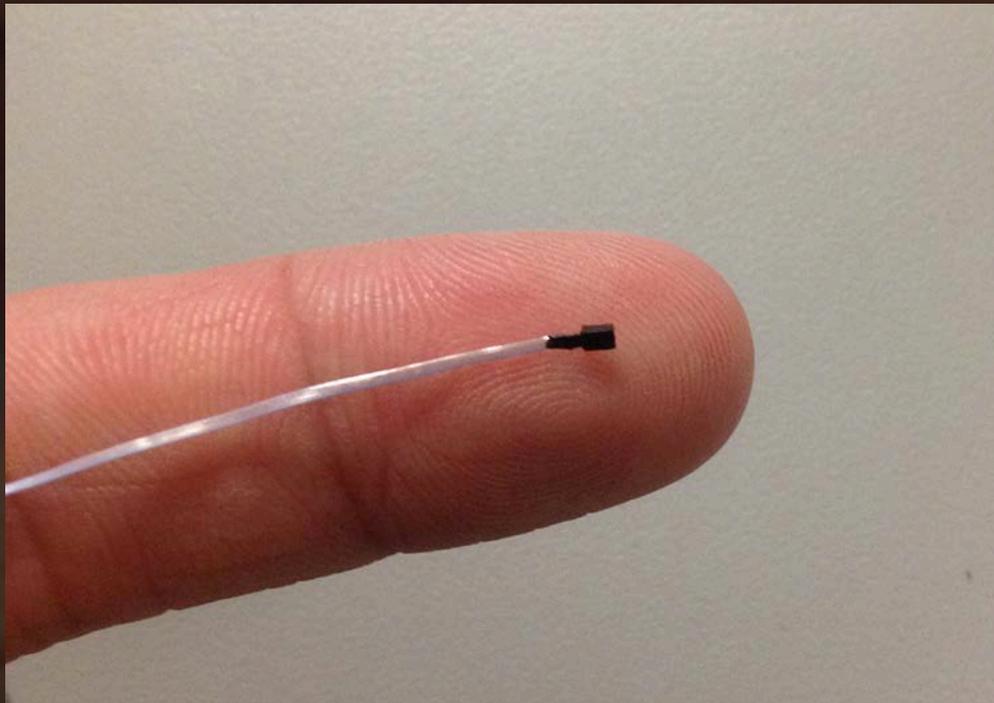


Optical mouse sensor

Tiny CMOS camera

Magic Finger: X.D. Yang, *et al.*, "Magic finger: always-available input through finger instrumentation," in Proceedings of UIST 2012.

RELATED WORK



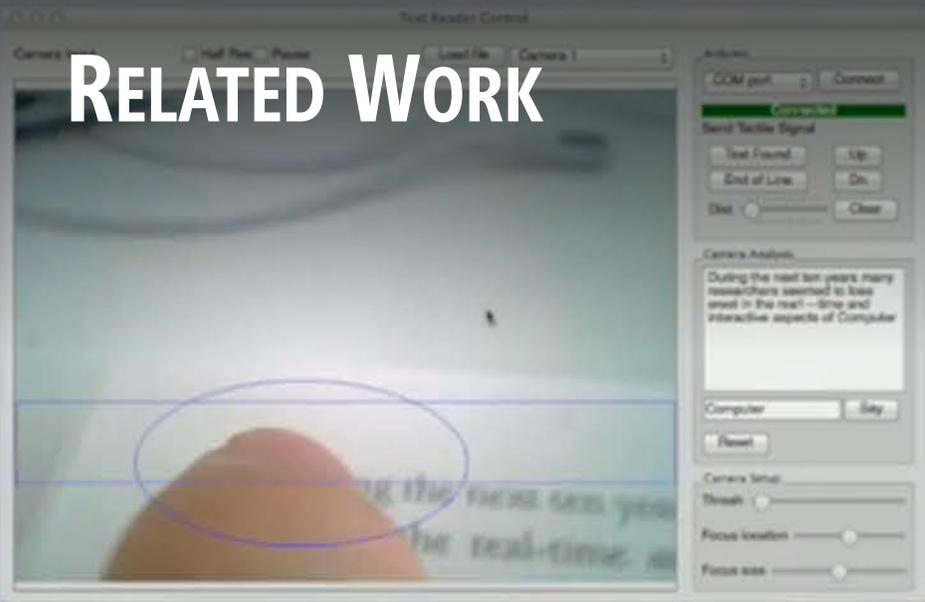
Magic Finger: X.D. Yang, *et al.*, "Magic finger: always-available input through finger instrumentation," in Proceedings of UIST 2012.

RELATED WORK

Finger-mounted camera

Haptic vibration motors

RELATED WORK

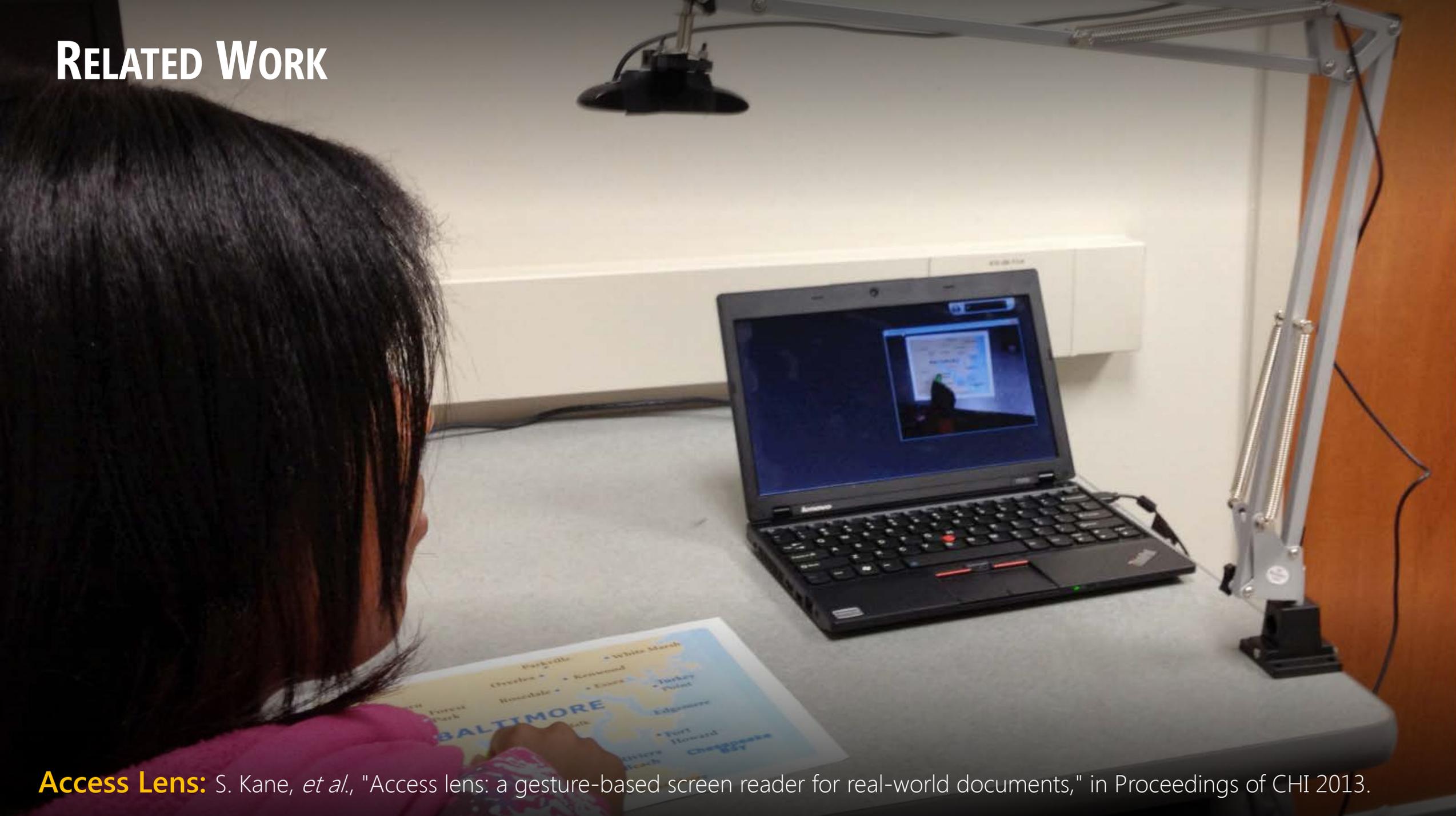


RELATED WORK

Glasses-mounted camera



RELATED WORK



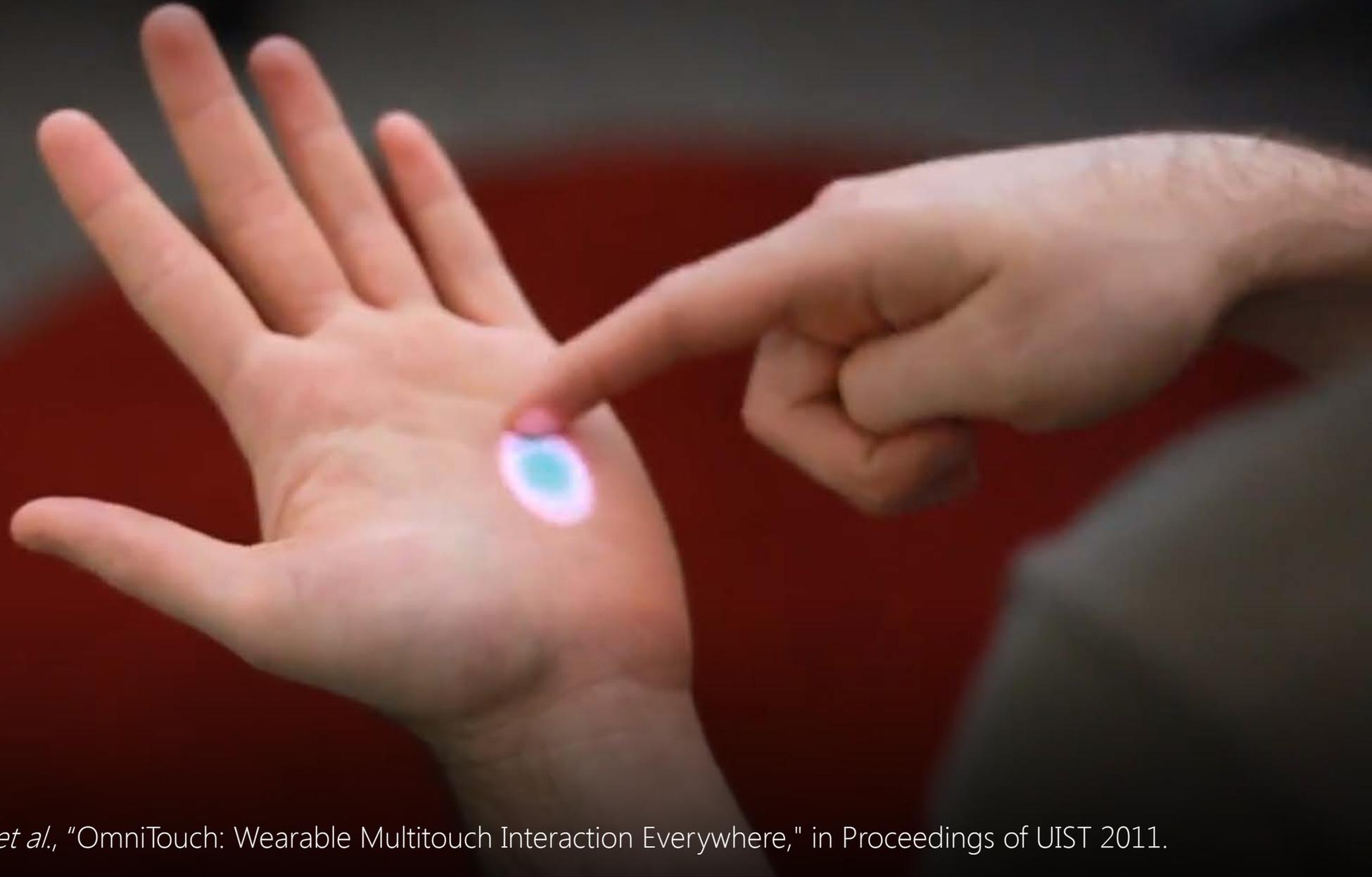
Access Lens: S. Kane, *et al.*, "Access lens: a gesture-based screen reader for real-world documents," in Proceedings of CHI 2013.

RELATED WORK



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RELATED WORK



OmniTouch: C. Harrison, *et al.*, "OmniTouch: Wearable Multitouch Interaction Everywhere," in Proceedings of UIST 2011.

RELATED WORK

8.99	-0.08
11.72	0.00
14.44	-0.04
17.16	-0.17
19.88	-0.21
22.61	-0.33
25.33	-0.45

Table 3 - Touch Biases for X axis for a 30 degree monitor angle (in cm).
Negative bias means touch was to the left of the target.

Y Position (cm)	Mean Bias (cm)
1.24	+0.54
4.13	+0.54
7.01	+0.49
9.90	+0.45
12.79	+0.41
15.68	+0.41
18.56	+0.41

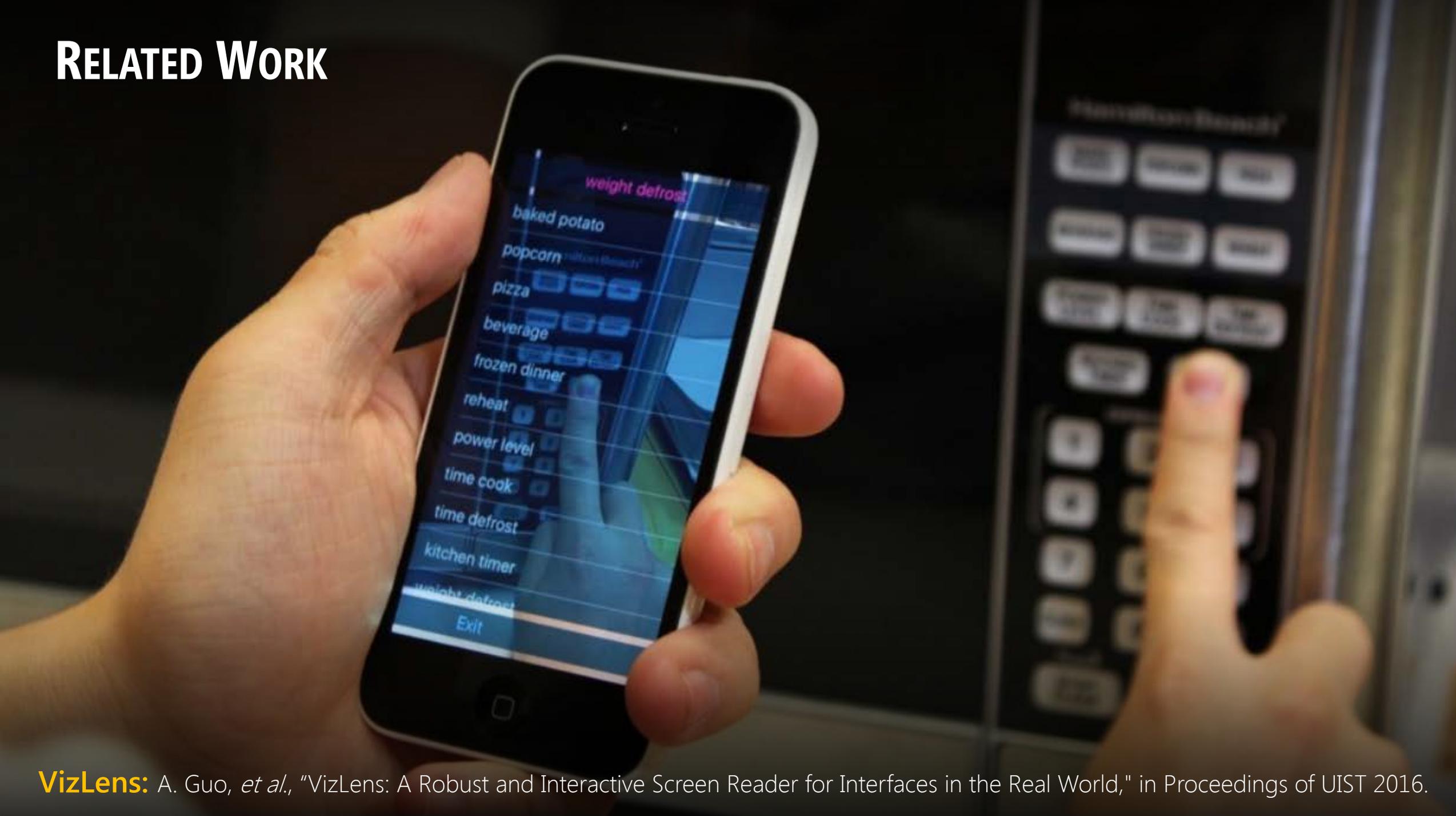
Table 4 - Touch Biases for Y axis for a 30 degree monitor angle (in cm).
Positive bias means touch was below target.

Ranges

Range data appears in Tables 5 and 6. X position represents how far from the left of the screen subjects were touching. Y position represents how far from the top of the screen subjects were touching. Ranges represent the extreme misses on either side of a target anyone missed to the right of the target minus the farthest the

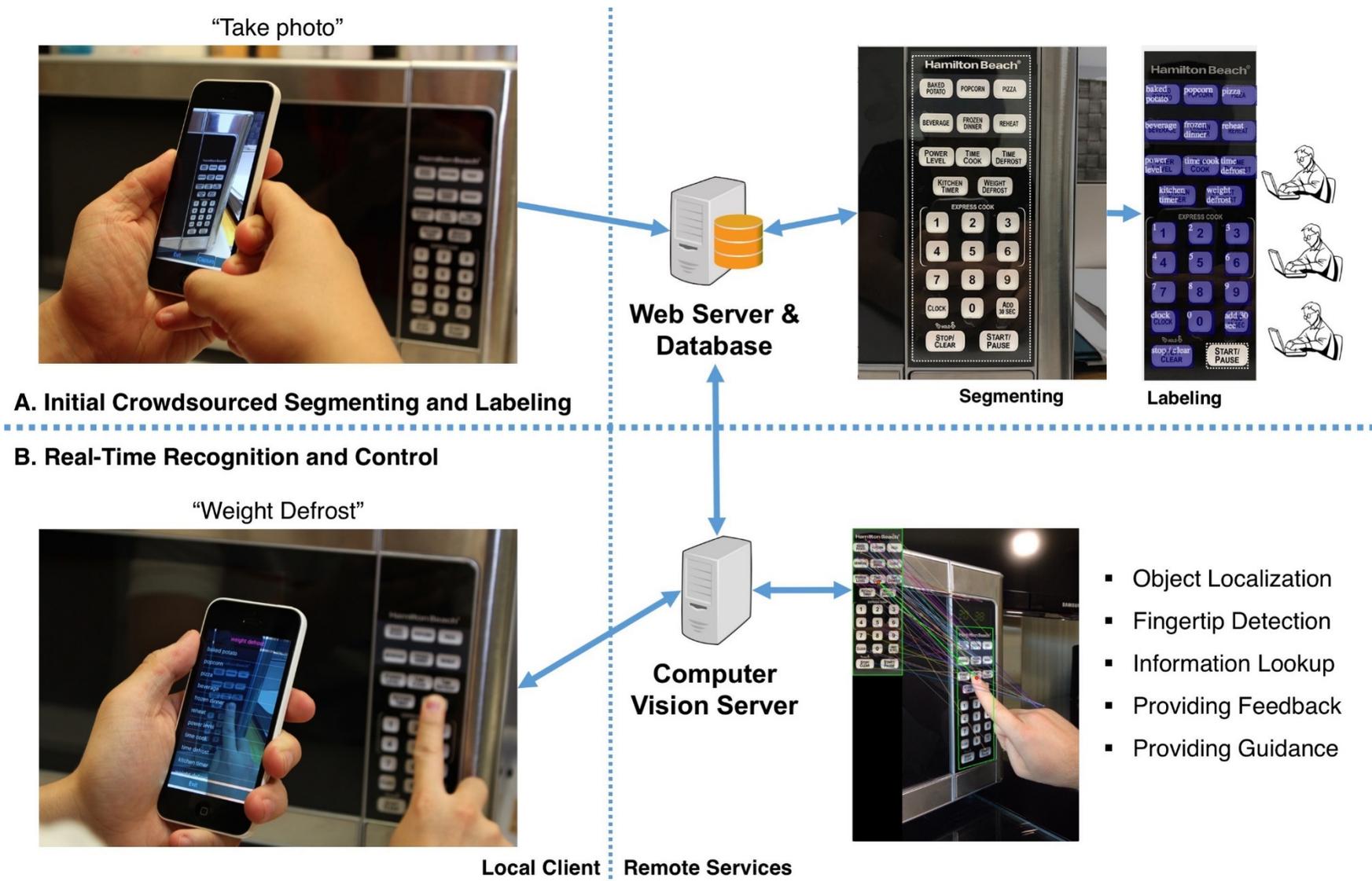
X Position (cm)	Range (cm)
0.83	1.28
3.55	2.48
6.27	1.32
8.99	1.44
11.72	1.36
14.44	1.40
17.16	1.77

RELATED WORK

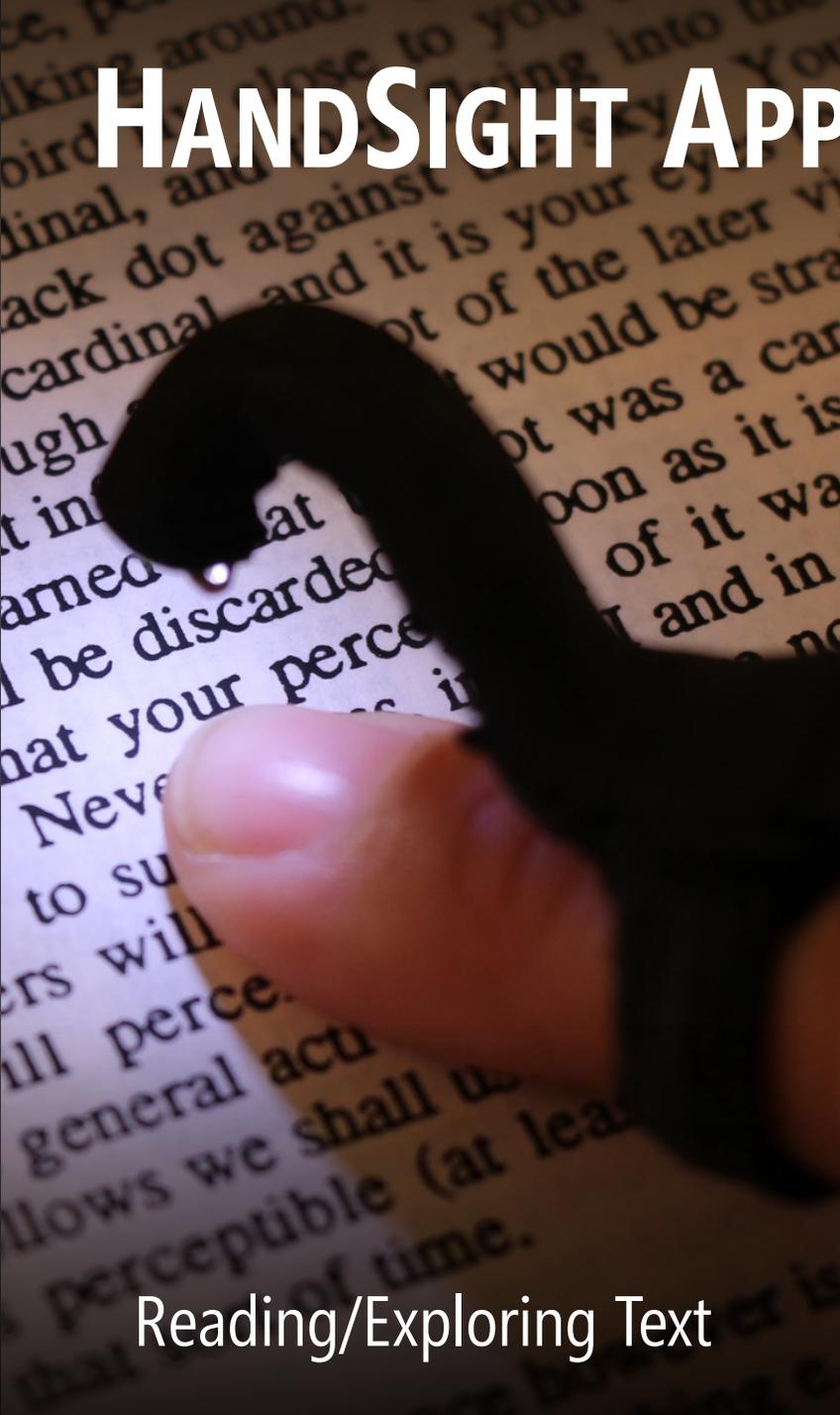


VizLens: A. Guo, *et al.*, "VizLens: A Robust and Interactive Screen Reader for Interfaces in the Real World," in Proceedings of UIST 2016.

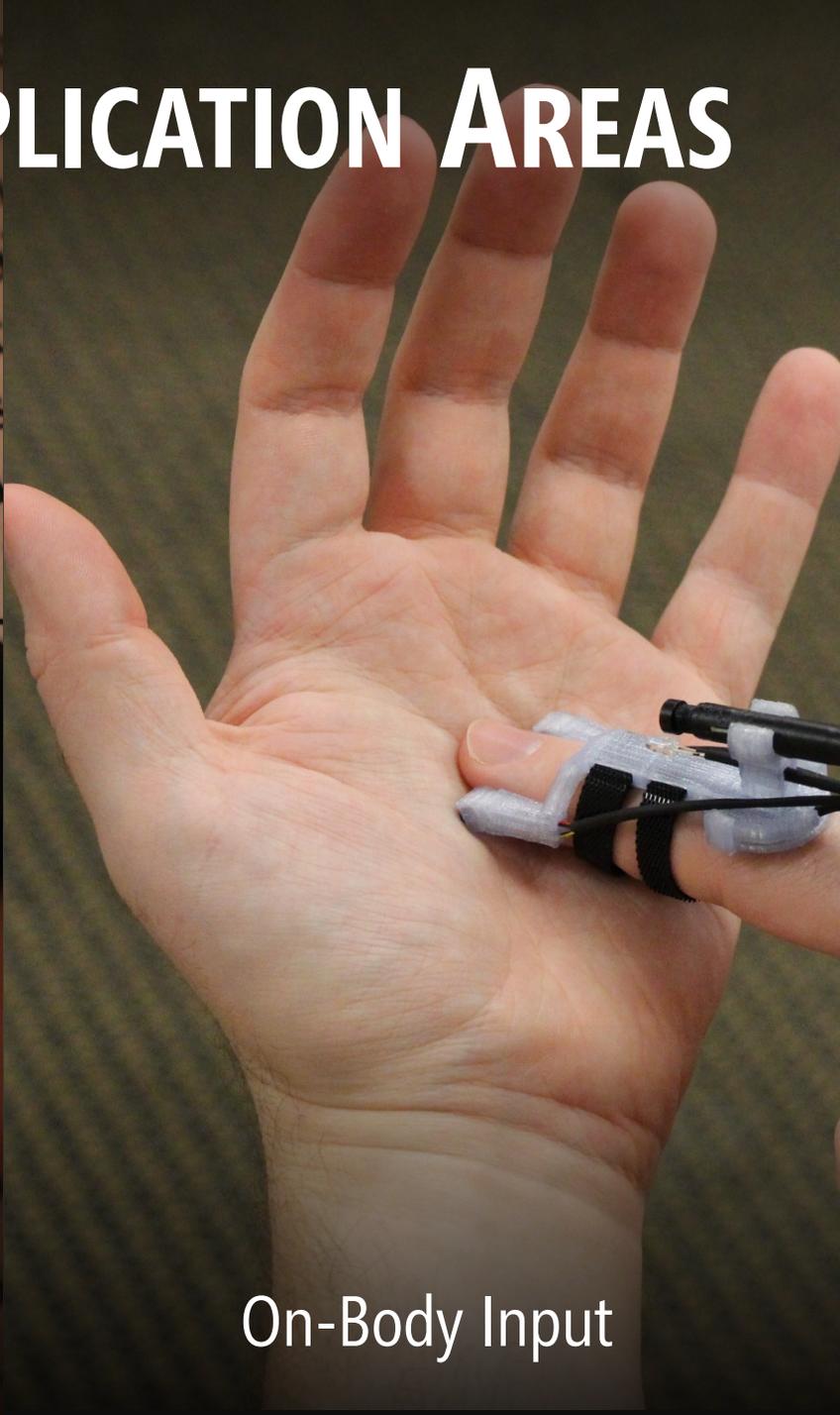
RELATED WORK



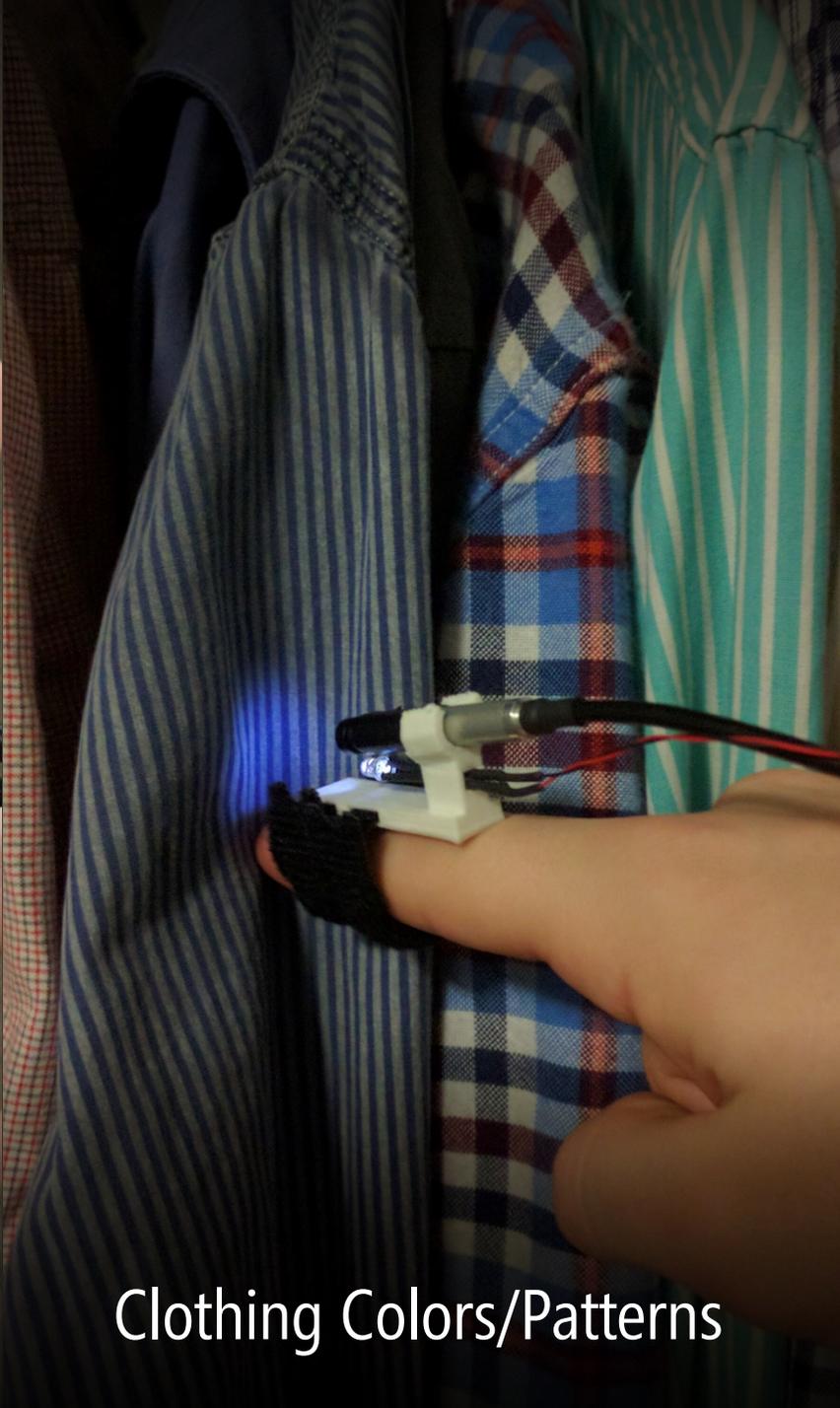
HANDSIGHT APPLICATION AREAS



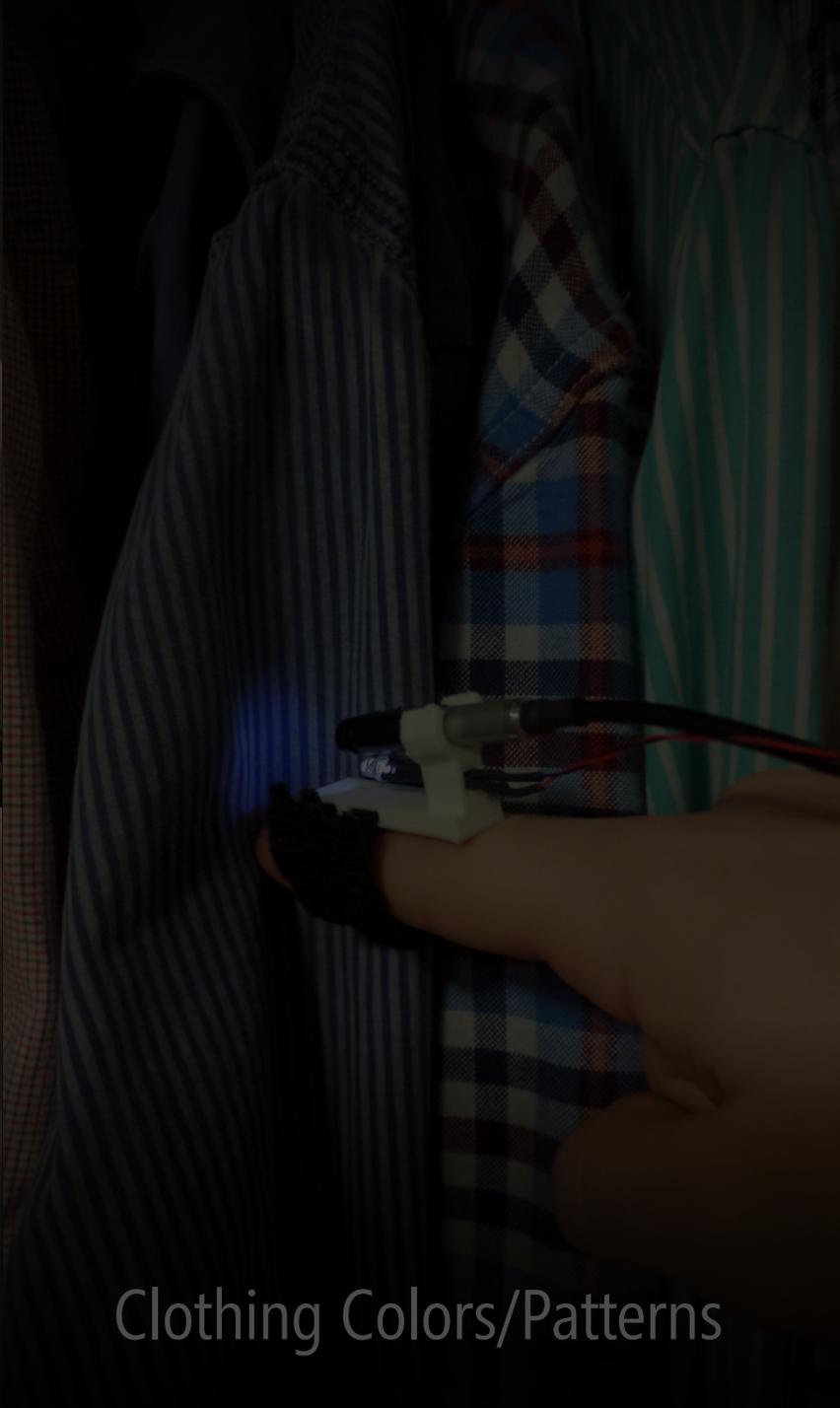
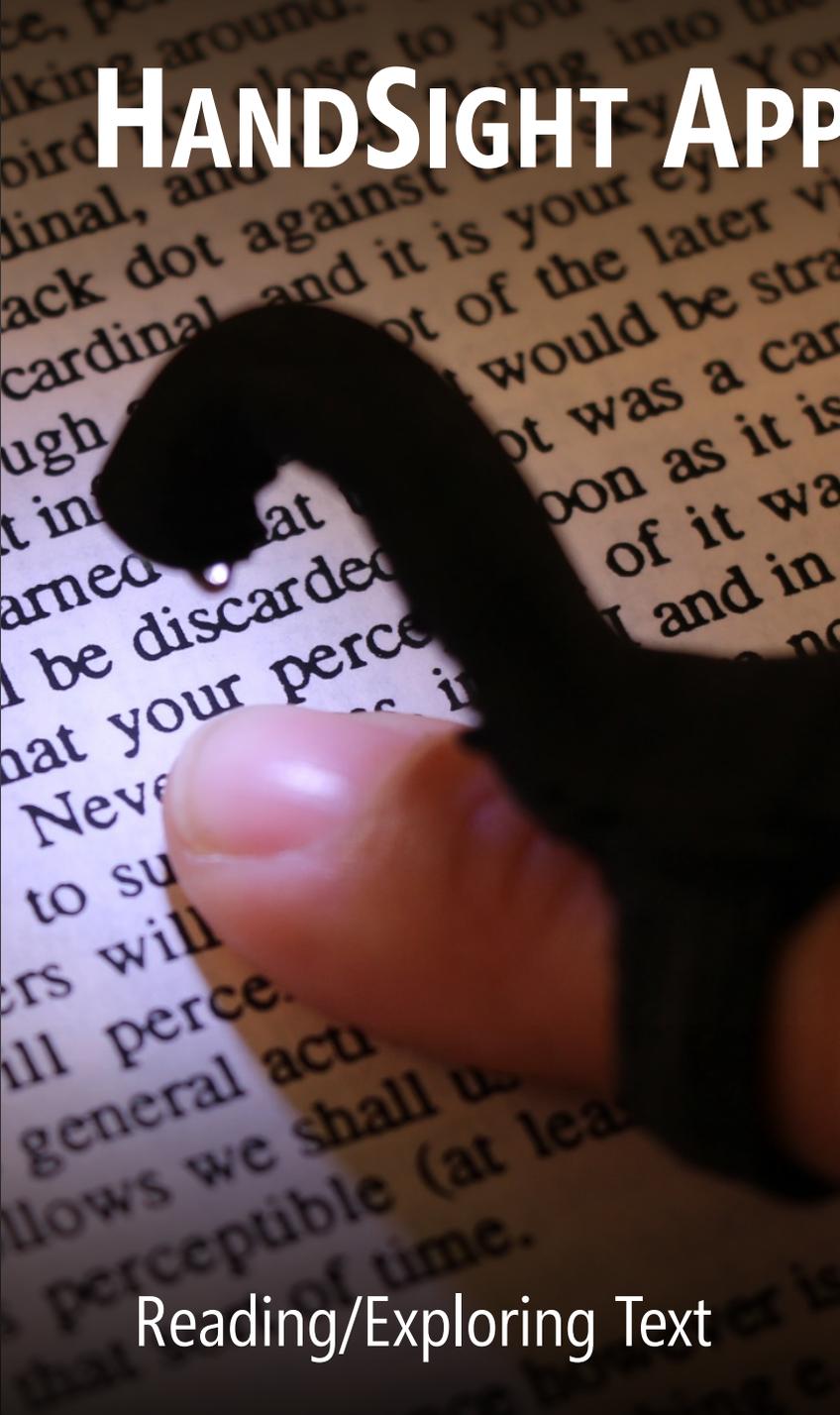
Reading/Exploring Text



On-Body Input



Clothing Colors/Patterns



HANDSIGHT APPLICATION AREAS

Reading/Exploring Text

On-Body Input

Clothing Colors/Patterns

Advantages of Touch-Based Reading

1. Does not require framing an overhead camera

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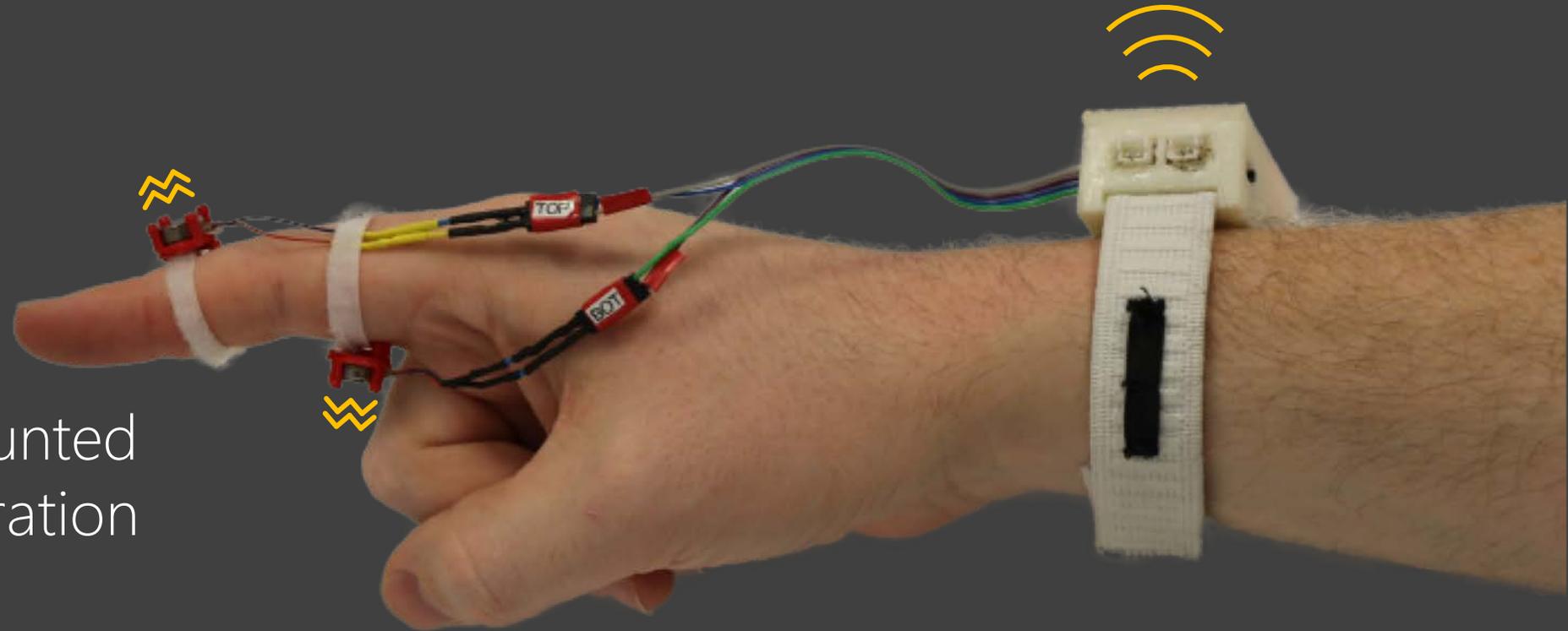
New Challenges

1. How to precisely trace a line of text?
2. How to support physical navigation?

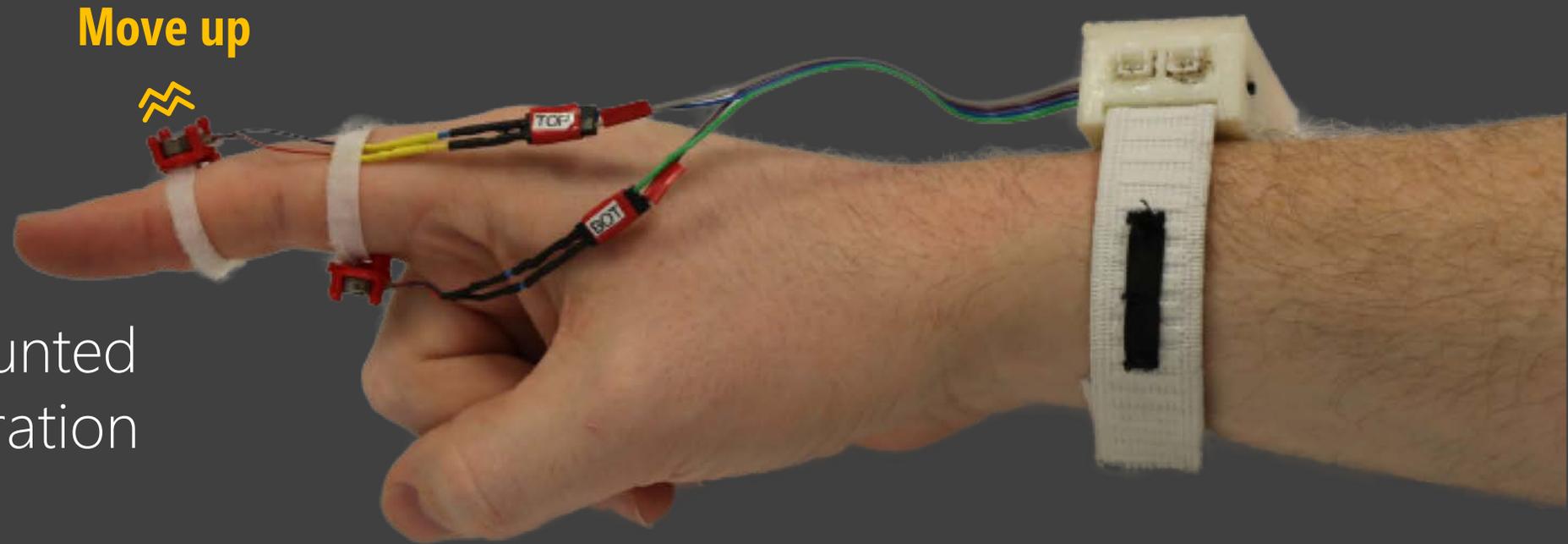
COMPARING TWO TYPES OF DIRECTIONAL FINGER GUIDANCE

2. **Audio** via built-in or external speakers

1. Finger-mounted **haptic** vibration



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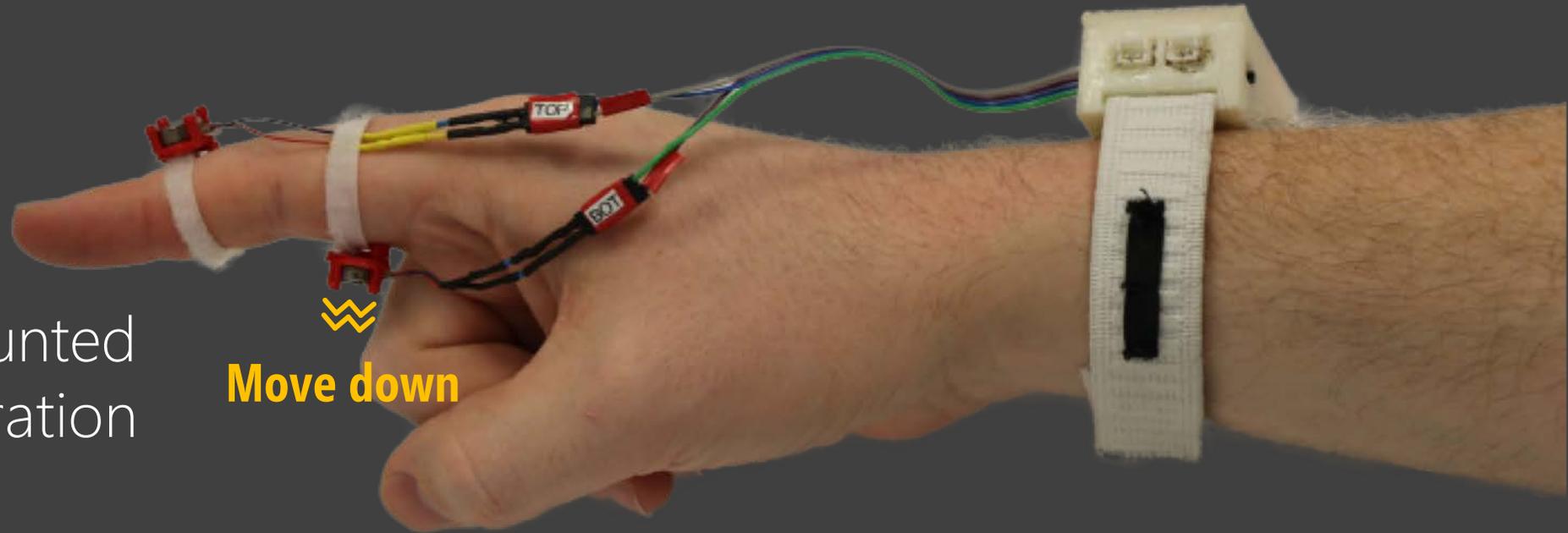


1. Finger-mounted **haptic** vibration

COMPARING TWO TYPES OF DIRECTIONAL FINGER GUIDANCE

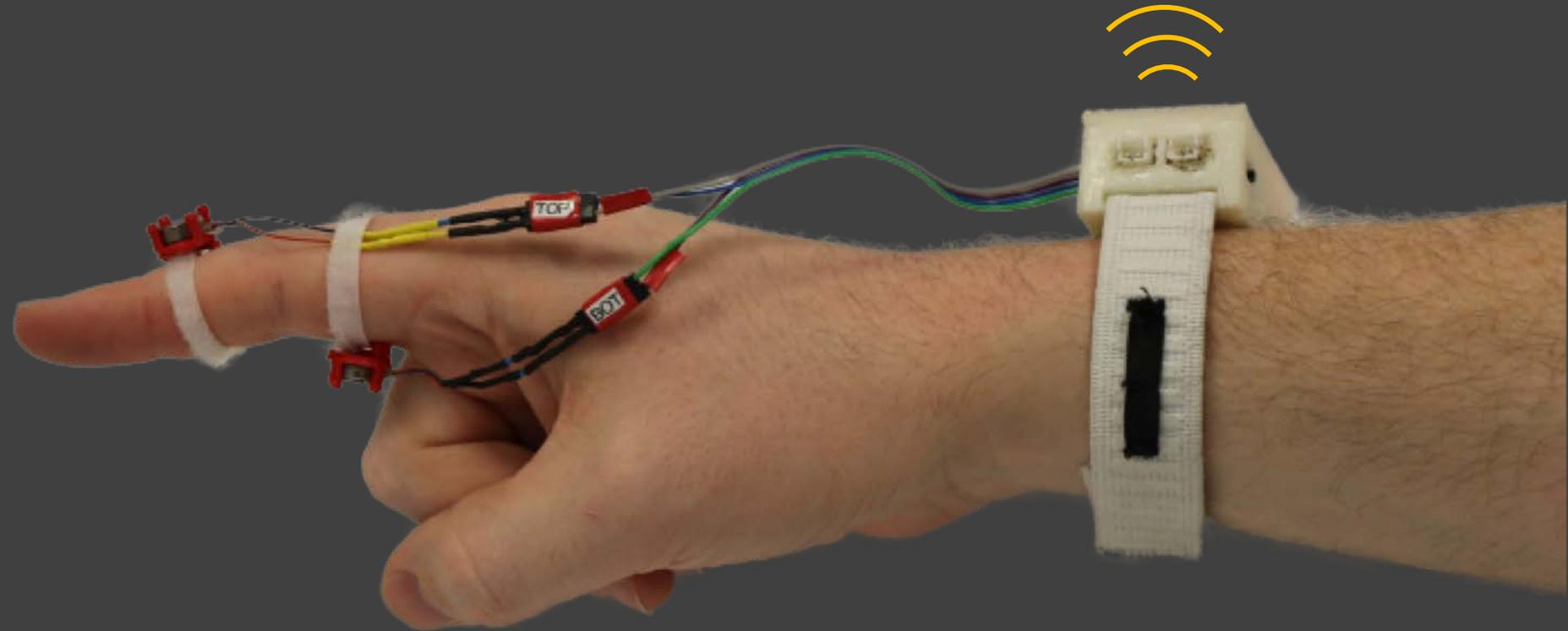
1. Finger-mounted
haptic vibration

Move down



COMPARING TWO TYPES OF DIRECTIONAL FINGER GUIDANCE

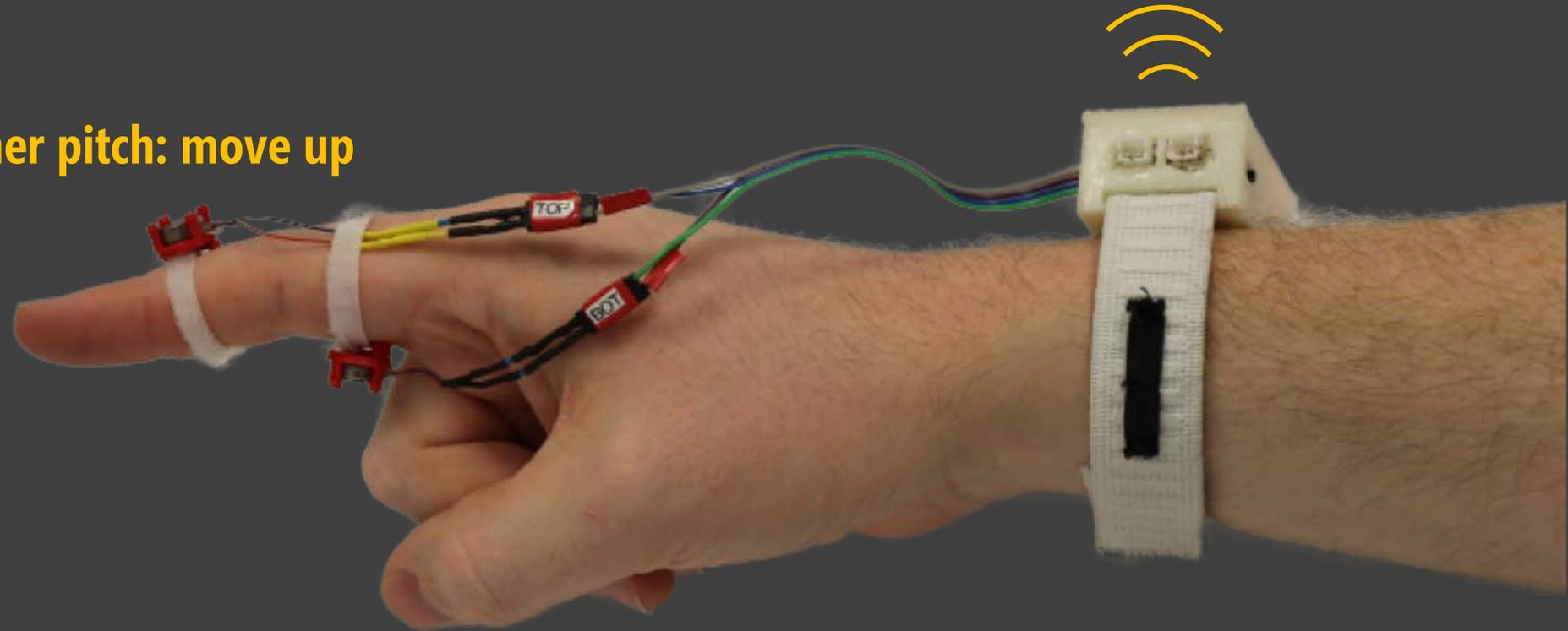
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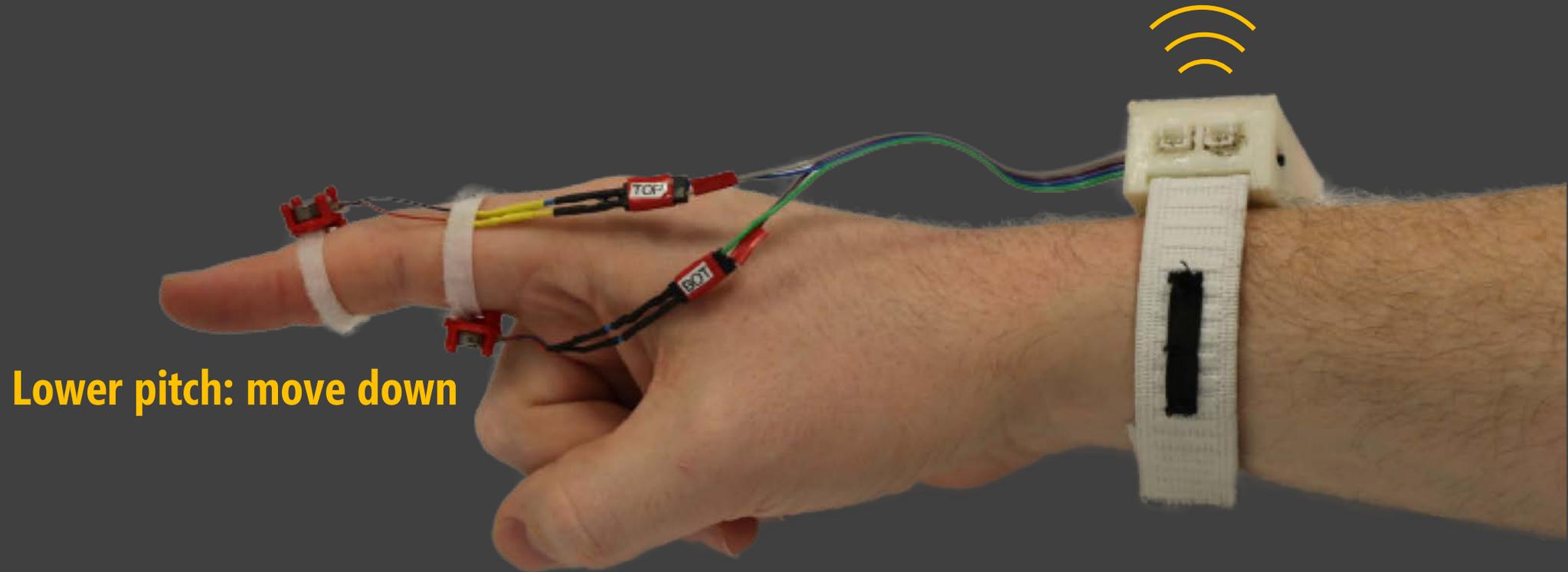
2. **Audio** via built-in or external speakers

Higher pitch: move up



COMPARING TWO TYPES OF DIRECTIONAL FINGER GUIDANCE

2. **Audio** via built-in or external speakers



Lower pitch: move down

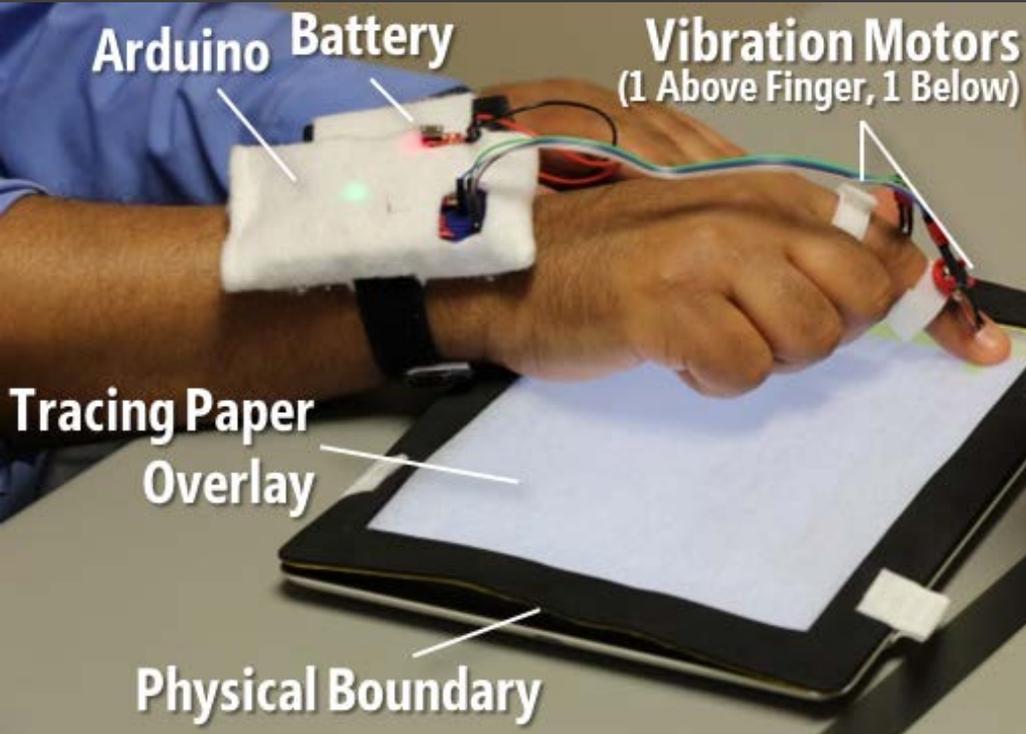
READING PILOT STUDY

METHODS

4 Participants

3 female, 1 male, ages 43-64

3 totally blind, 1 severe low vision



Lee Stearns, Ruofei Du, Uran Oh, Yumeng Wang, Leah Findlater, Rama Chellappa, and Jon E. Froehlich, "The Design and Preliminary Evaluation of a Finger Mounted Camera and Feedback System to Enable Reading of Printed Text For the Blind," in *Proceedings of ECCV 2014 (ACVR Workshop)*.

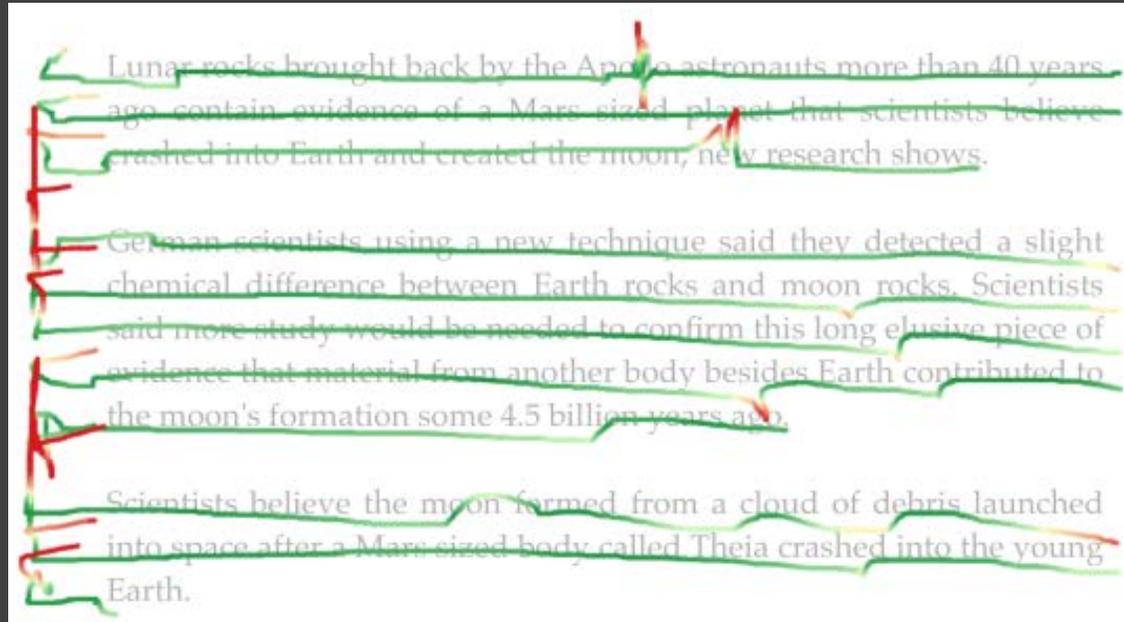
READING PILOT STUDY FINDINGS

4 Participants

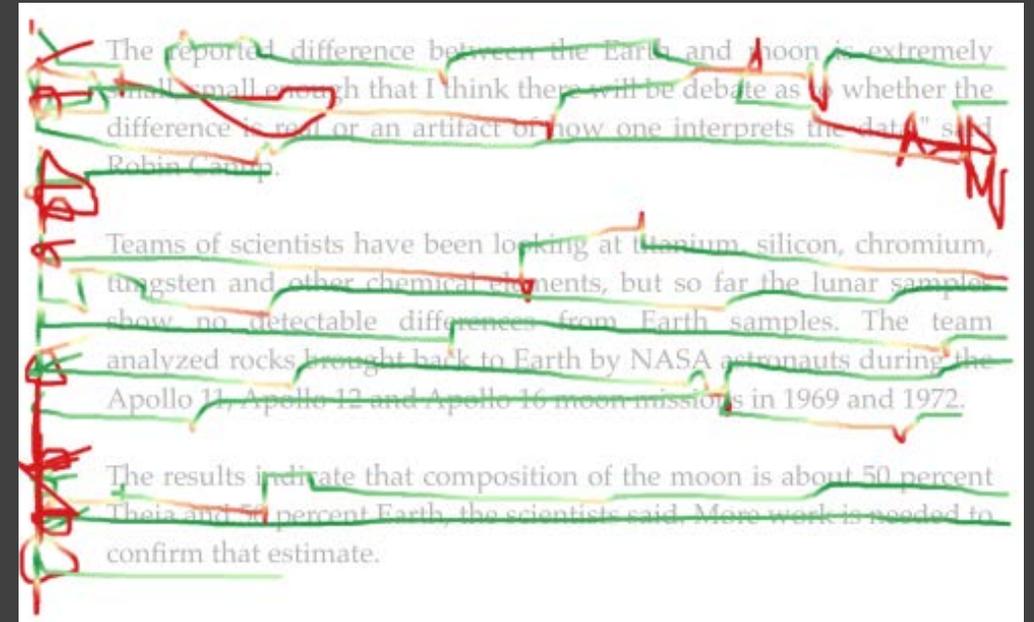
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audio-only



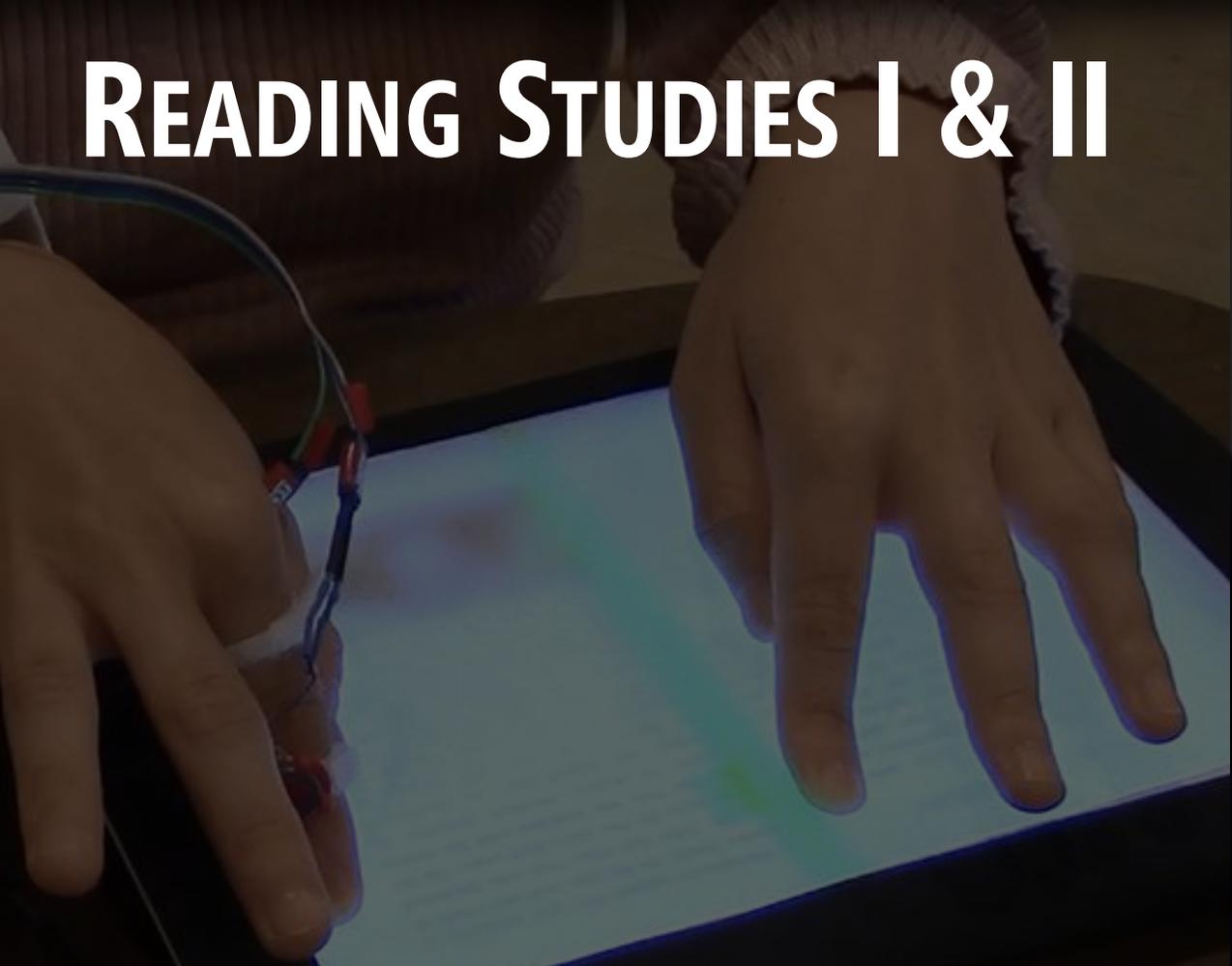
haptic-only



Example finger traces—**Red lines** mark drift off of the line

Audio was more accurate, about twice as fast, and preferred by 3 out of 4 participants

READING STUDIES I & II



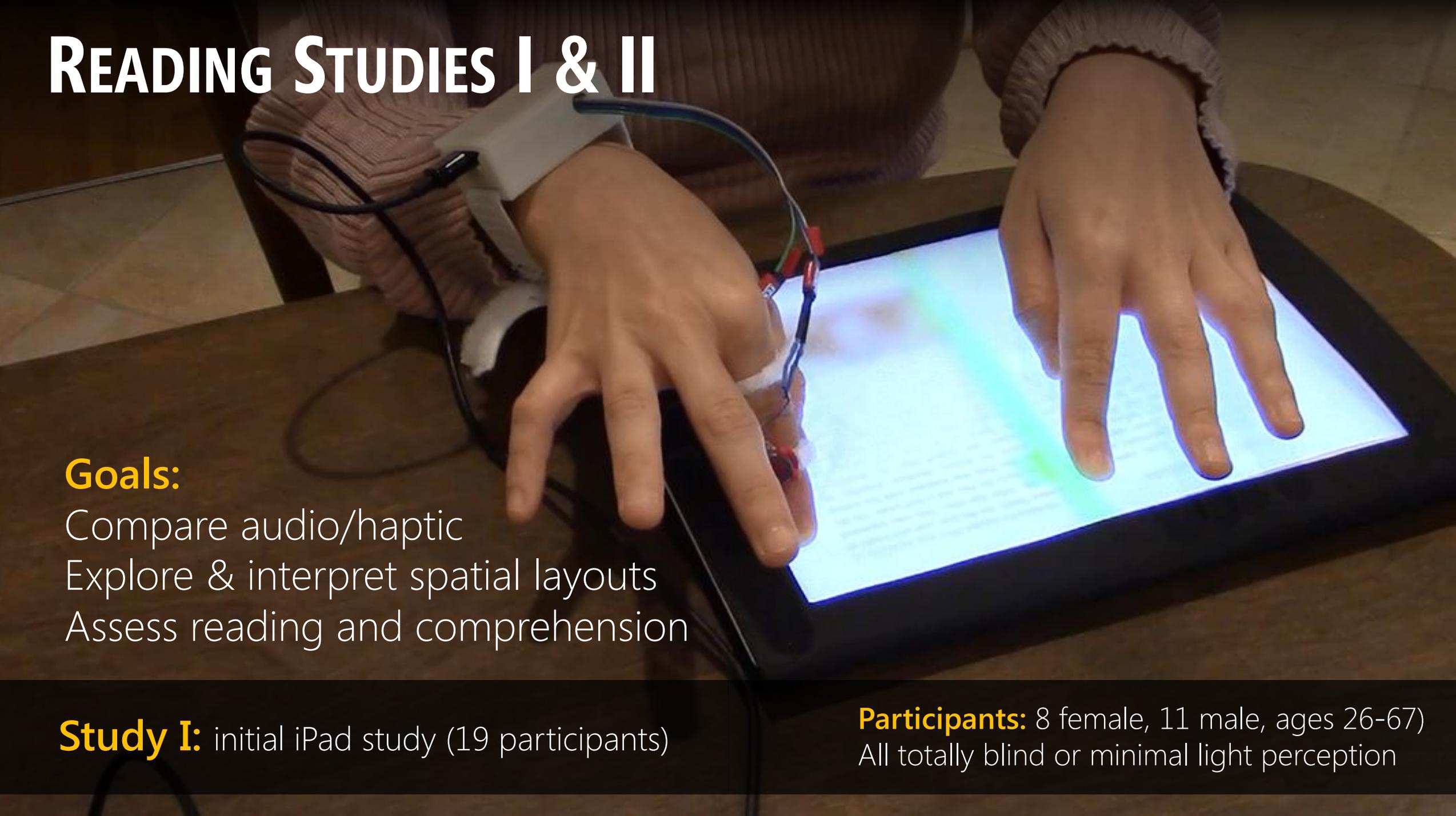
Lee Stearns, Ruofei Du, Uran Oh, Catherine Jou, Leah Findlater, David Ross, and Jon E. Froehlich, "Evaluating Haptic and Auditory Directional Guidance to Assist Blind People in Reading Printed Text Using Finger-Mounted Cameras," in *ACM Transactions on Accessible Computing*, October 2016.

Study I: initial iPad study (19 participants)



Study II: physical prototype study (4 participants)

READING STUDIES I & II



Goals:

Compare audio/haptic
Explore & interpret spatial layouts
Assess reading and comprehension

Study I: initial iPad study (19 participants)

Participants: 8 female, 11 male, ages 26-67)
All totally blind or minimal light perception

READING STUDY I



Used an iPad to focus on **user experience**, gather **finger trace** data

SYSTEM DESIGN

EXPLORATION AND READING MODES

Animals also have emotions

Lorem ipsum dolor sit amet, consectetur adipiscing elit. Nam malesuada augue at venenatis vestibulum. Fusce non dapibus orci, in vestibulum nisi. Sed eu elit nec ex posuere dictum. Sed sed libero rutrum, dictum leo at, tempus elit. Integer porta egestas nibh, quis mollis erat dignissim non. Nulla nec luctus nisl. Sed ultrices. Sed ultrices libero a pellentesque sagittis. Sed ultrices libero a pellentesque sagittis.

Despite the stubborn, widespread opinion that animals don't feel emotions in the same way that humans do, many animals have been observed to demonstrate a capacity for joy. People have often seen animals evincing behavior that can only be taken to mean they are pleased with what life has brought them in that particular moment.

A chimpanzee named Nim was raised by a human family for the first year and a half of his life. After that time, Nim was separated from them for two and a half years. On the day that Nim was reunited with his human family, he smiled, shrieked, pounded the ground, and looked from one member of the family to the next. Still smiling and shrieking, Nim went around hugging each member of the family. He played with and groomed each member of the family for almost an hour before the family had to leave. People who were familiar with Nim's behavior said they had never seen him smile for such a long period of time.



Exploration Mode

history and buried for safekeeping. Because stores of coins gathered and hidden in this manner lie untouched for many years, they can reveal a great deal about a given culture.

Coins are useful in revealing many aspects of a culture. They can provide clues about when a given civilization was wealthy and when it was experiencing a depression. Wealthy nations tend to produce a greater number of coins made from richer materials. The distribution of coins can also reflect the boundaries of an empire and the trade relationships within it. Roman imperial gold coins found in India, indicate the Romans purchased goods from the East.

The way the coins themselves are decorated sometimes provides key information about a culture. Many coins are stamped with a wealth of useful historical evidence, including portraits of political leaders, important buildings and sculptures, mythological and religious figures, and useful dates. Some coins, such as many from ancient Greece, can be considered works of art themselves and reflect the artistic achievement of the civilization as a whole.

Information gathered from old coins by historians is most useful when placed alongside other historical documents, such as written accounts or data from archeological digs. Combined

Reading Mode

SYSTEM DESIGN

EXPLORATION MODE

Continuous audio feedback to identify content beneath finger

Flute sound: text

Cello sound: picture

Silence: empty space

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Lorem ipsum dolor sit amet, consectetur adipiscing elit. Nam malesuada augue at venenatis vestibulum. Fusce non dapibus orci, in vestibulum nisi. Sed eu elit nec exposuere dictum. Sed sed libero rutrum, dictum leo at, tempus elit. Integer portae gestas nibh, quis mollis erat dignissim non. Nulla nec luctus nisl. Sed ultrices. Sed ultrices libero a pellentesque sagittis. Sed ultrices libero a pellentesque sagittis.

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Silence: empty space

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Cello sound: picture

SYSTEM DESIGN

READING MODE

Right index finger to read, **left** to anchor start of line

Two directional guidance conditions: **audio** or **haptic**

Used to stay on the line or find the start of the next line

Audio: pitch of continuous audio

Haptic: strength and position of vibration

Additional **audio cues** (same for both conditions)

Start/end of line or paragraph

Synthesized speech

Above the line: downward guidance

(low pitch or lower vibration motor)

Coins are useful in revealing many aspects of a culture. They can provide clues about when a given civilization was wealthy and when it was experiencing a depression. Wealthy nations

Below the line: upward guidance

(high pitch or upper vibration motor)

Start/end of line or paragraph

(short but distinctive audio cues)

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STUDY I

FINDINGS

Haptic vs. Audio: Quantitative Performance (n=19)

audio

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haptic

made up of long mountain ranges and deep valleys and troughs. Another surprise finding in the Atlantic was the existence of basalt, a volcanic rock thought only to exist in the Pacific Ocean. The presence of basalt in the Atlantic was a clue that volcanic activity occurs at the bottom of the sea. This and other discoveries, many of them

Example finger traces—**Dashed red lines** mark drift off of the line

STUDY I

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0.21cm

Absolute error from line center

haptic

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0.28cm

Absolute error from line center

STUDY I

FINDINGS

Overall Reading Experience

Pros

Low learning curve

Flexible

Direct control over speed

STUDY I

FINDINGS

Overall Reading Experience

Pros

Low learning curve

Flexible

Direct control over speed

Cons

Hard to use for reading

High cognitive load may affect comprehension

STUDY I

FINDINGS

Exploration Mode

Participants appreciated direct access to spatial information, and nearly all able to locate images and count the number of columns.

Animals also have emotions

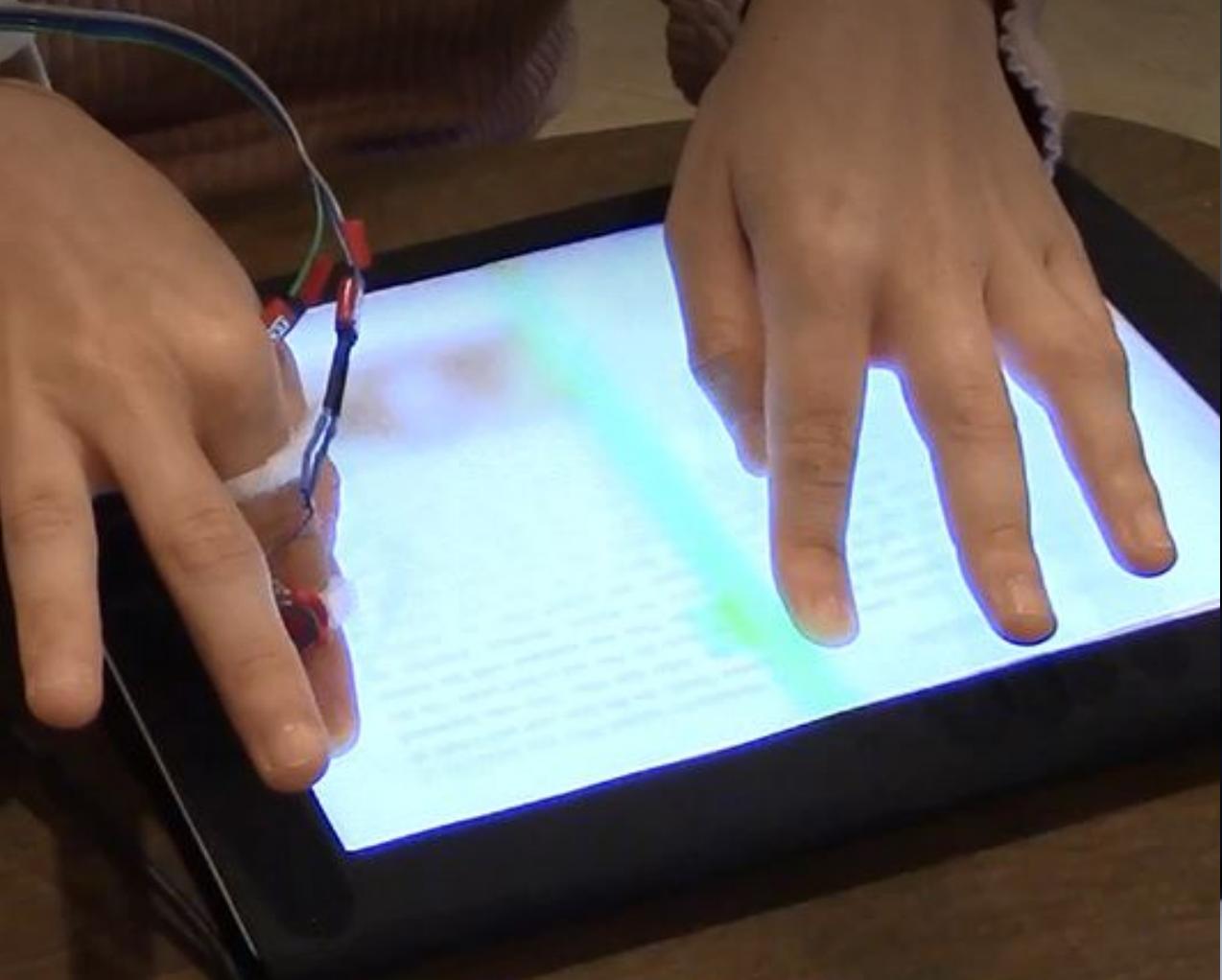
Lorem ipsum dolor sit amet, consectetur adipiscing elit. Nam malesuada augue at venenatis vestibulum. Fusce non dapibus orci, in vestibulum nisi. Sed eu elit nec exposuere dictum. Sed sed libero rutrum, dictum leo at, tempus elit. Integer porta egestas nibh, quis mollis erat dignissim non. Nulla nec luctus nisl. Sed ultrices. Sed ultrices libero a pellentesque sagittis. Sed ultrices libero a pellentesque sagittis.

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READING STUDIES I & II



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Study II: physical prototype study (4 participants)

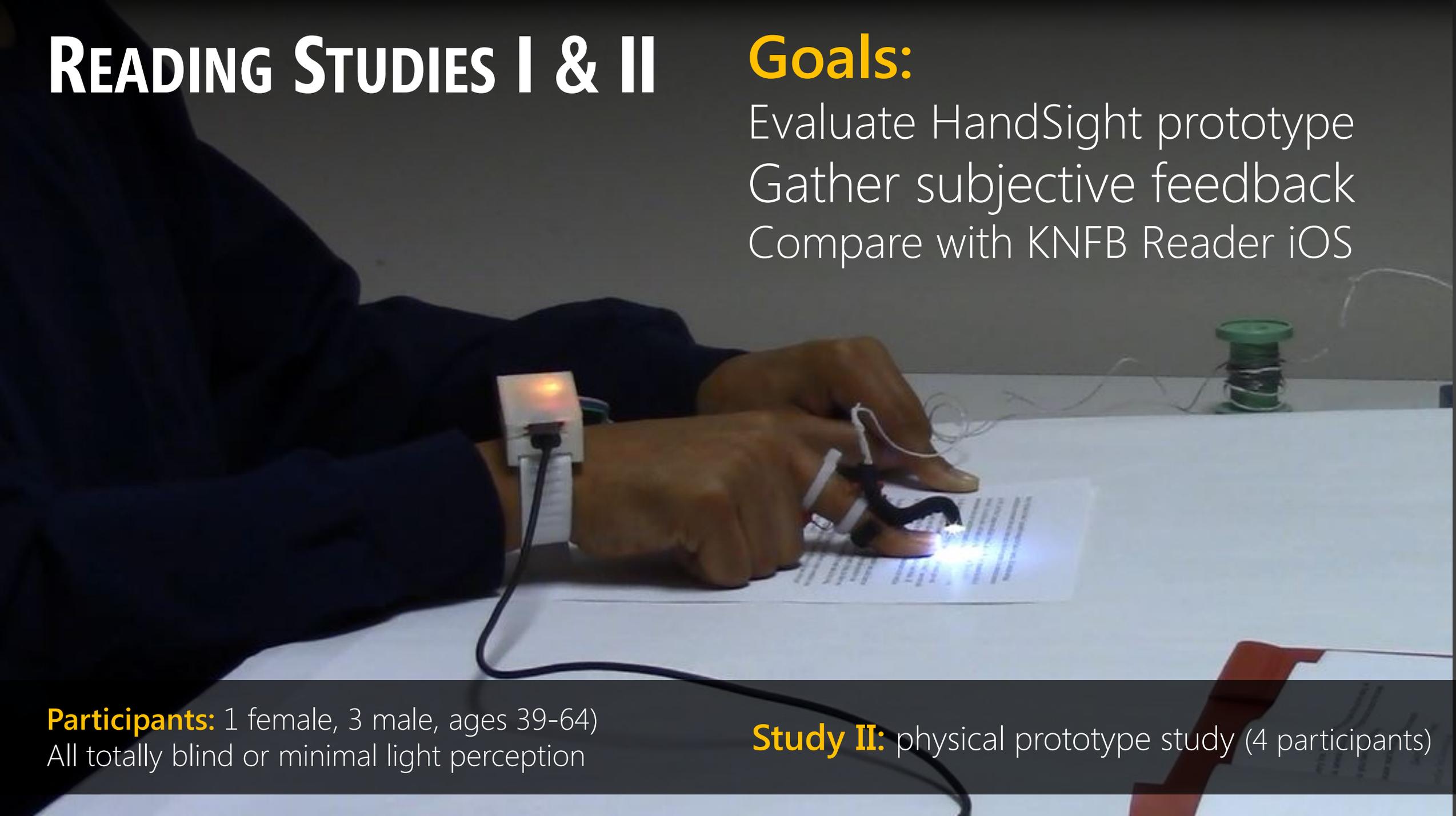
READING STUDIES I & II

Goals:

Evaluate HandSight prototype
Gather subjective feedback
Compare with KNFB Reader iOS

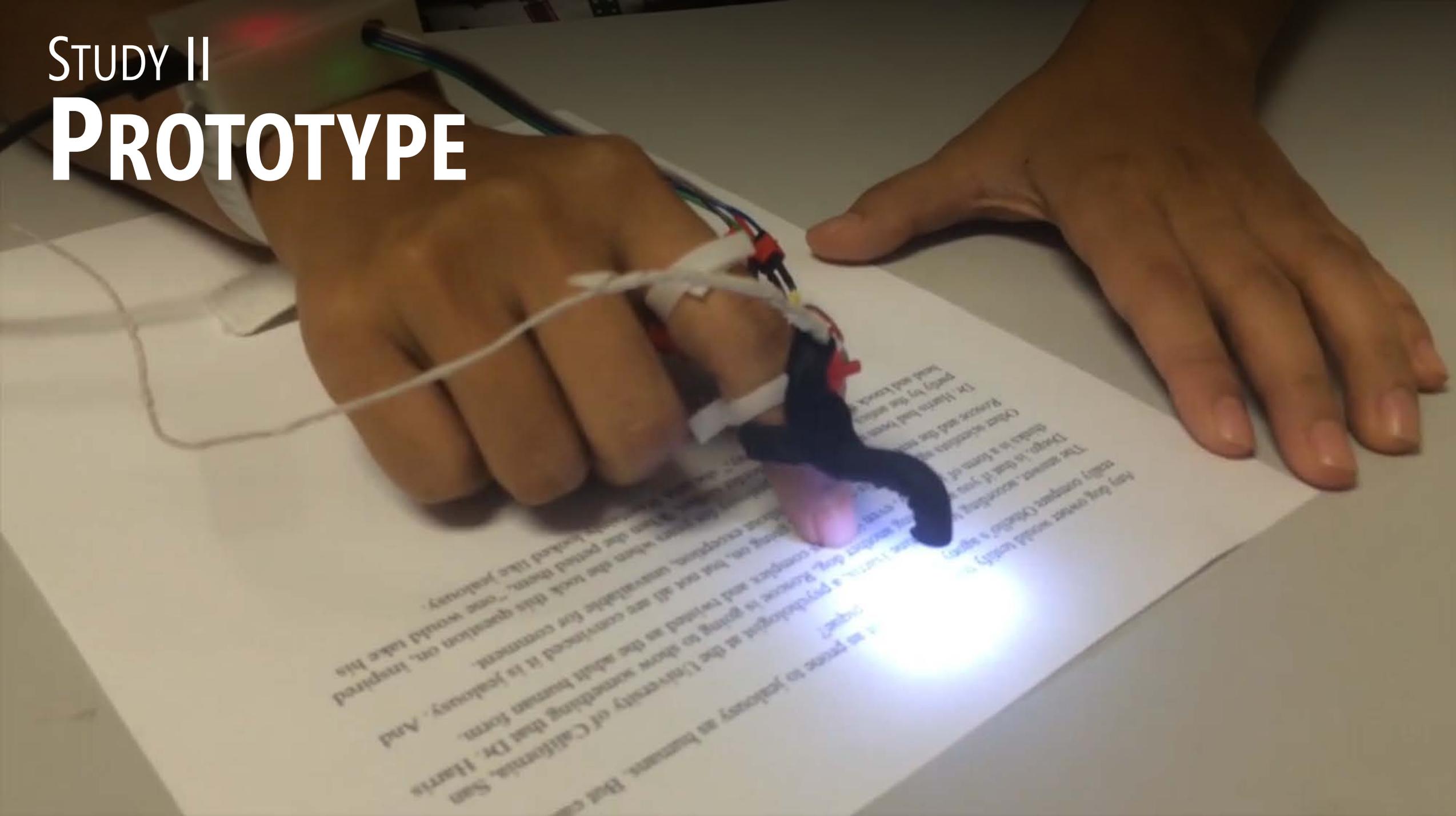
Participants: 1 female, 3 male, ages 39-64)
All totally blind or minimal light perception

Study II: physical prototype study (4 participants)



STUDY II

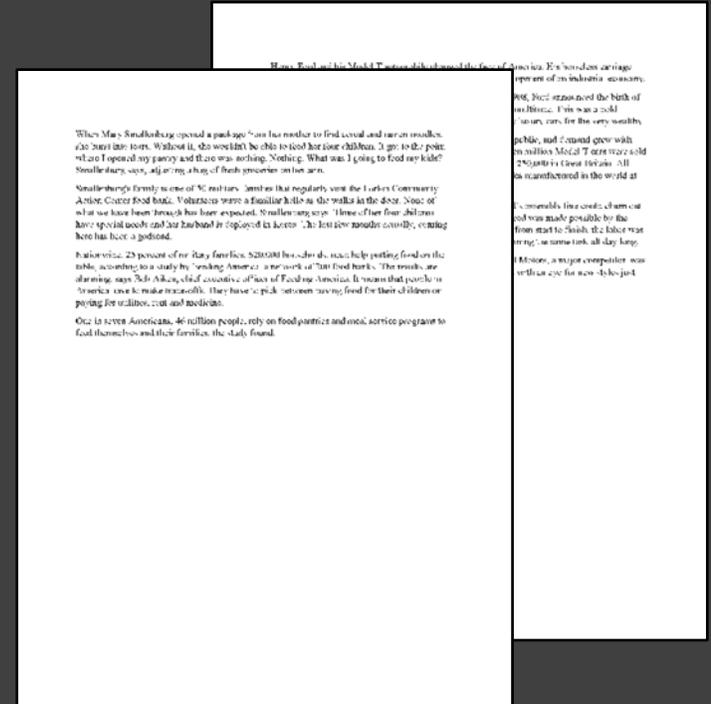
PROTOTYPE



STUDY II

METHOD: HANDSIGHT

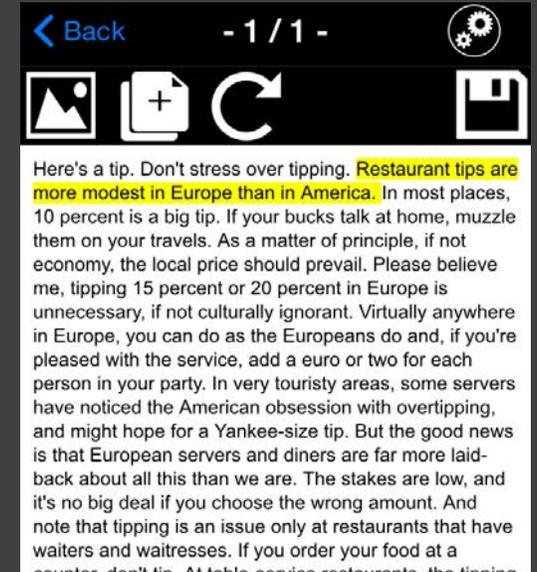
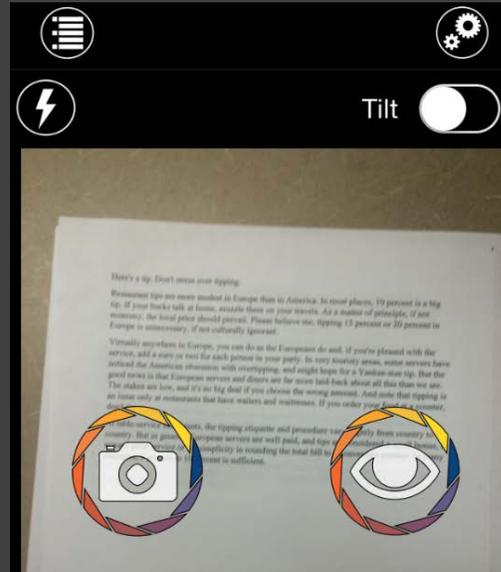
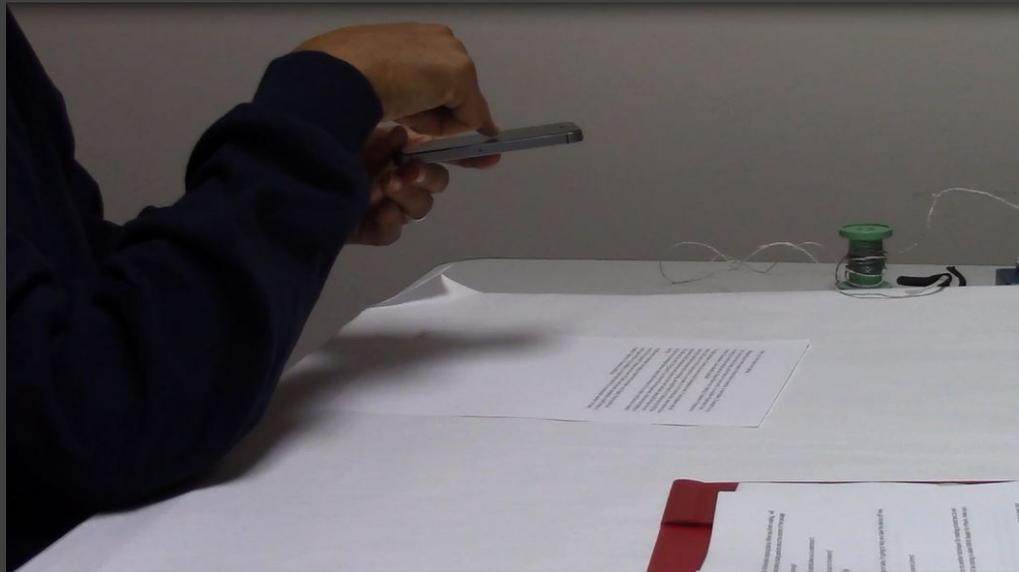
Participants used **preferred guidance** from Study I to explore and read physical documents



STUDY II

METHOD: KNFB READER IOS

Photographed and read physical documents



IMPLICATIONS

ADVANTAGES AND DISADVANTAGES OF A FINGER-BASED READING APPROACH

Pros

IMPLICATIONS

ADVANTAGES AND DISADVANTAGES OF A FINGER-BASED READING APPROACH

Pros

Spatial layout information

IMPLICATIONS

ADVANTAGES AND DISADVANTAGES OF A FINGER-BASED READING APPROACH

Pros

Spatial layout information

Direct control over reading

IMPLICATIONS

ADVANTAGES AND DISADVANTAGES OF A FINGER-BASED READING APPROACH

Pros

- Spatial layout information
- Direct control over reading
- Reduced camera framing issues

IMPLICATIONS

ADVANTAGES AND DISADVANTAGES OF A FINGER-BASED READING APPROACH

Pros

- Spatial layout information
- Direct control over reading
- Reduced camera framing issues
- Efficient text detection and recognition

IMPLICATIONS

ADVANTAGES AND DISADVANTAGES OF A FINGER-BASED READING APPROACH

Pros

- Spatial layout information
- Direct control over reading
- Reduced camera framing issues
- Efficient text detection and recognition

* We observed these in our studies

IMPLICATIONS

ADVANTAGES AND DISADVANTAGES OF A FINGER-BASED READING APPROACH

Pros

- Spatial layout information
- Direct control over reading
- Reduced camera framing issues
- Efficient text detection and recognition

* We observed these in our studies

Cons

- Slower, requires increased concentration and physical dexterity

IMPLICATIONS

ADVANTAGES AND DISADVANTAGES OF A FINGER-BASED READING APPROACH

Pros

- Spatial layout information
- Direct control over reading
- Reduced camera framing issues
- Efficient text detection and recognition

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Cons

- Slower, requires increased concentration and physical dexterity

* Consistent with Shilkrot *et al.* 2014, 2015

IMPLICATIONS

ADVANTAGES AND DISADVANTAGES OF A FINGER-BASED READING APPROACH

Pros

- Spatial layout information
- Direct control over reading
- Reduced camera framing issues
- Efficient text detection and recognition

* We observed these in our studies

Cons

- Slower, requires increased concentration and physical dexterity
 - * Consistent with Shilkrot *et al.* 2014, 2015
- Importance of spatial layout information is unclear

CONTRIBUTIONS

Implementation and systematic evaluation of **haptic and auditory cues** for directional finger guidance

Identification of **tradeoffs** of both the finger guidance methods and touch-based reading in general in terms of speed, accuracy, and user preference

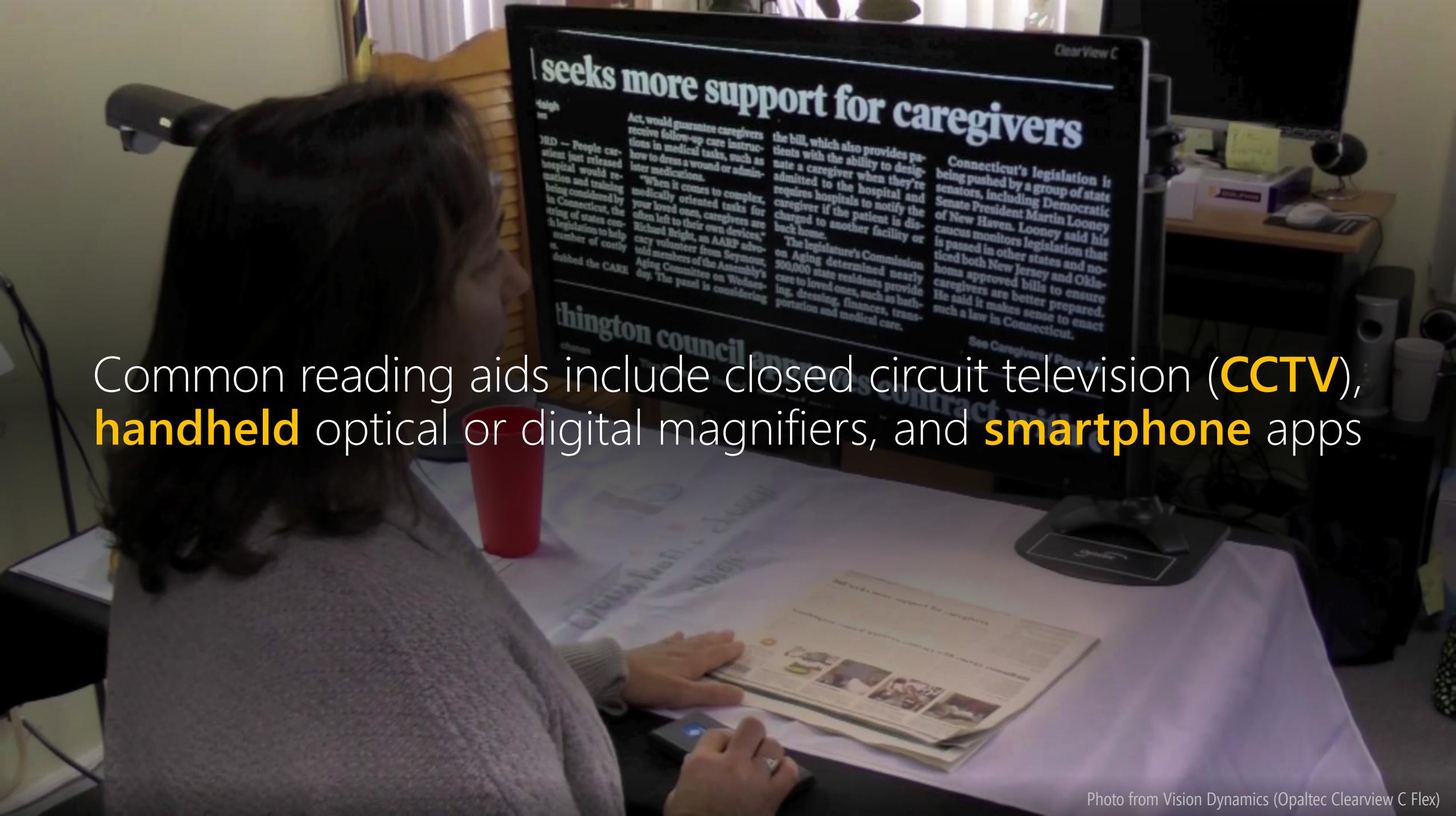
Proof-of-concept **realtime system** for reading and exploring printed documents via touch

EXTENSION FOR LOW VISION USERS



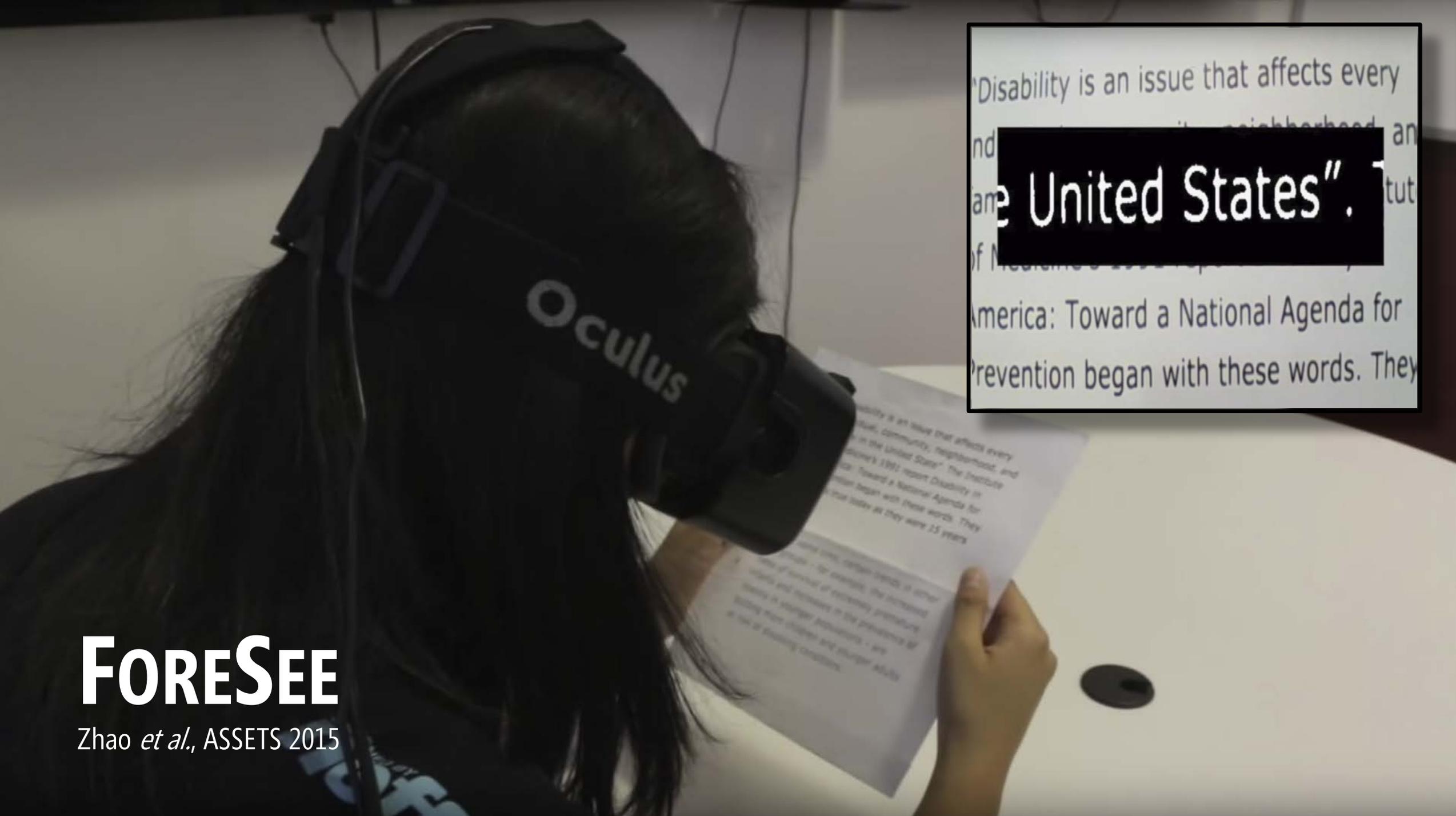
Lee Stearns, Victor De Souza, Jessica Yin, Leah Findlater, and Jon E. Froehlich, **"Augmented Reality Magnification for Low Vision Users with the Microsoft HoloLens and a Finger-Worn Camera,"** in *Proceedings of ASSETS 2017*.

Lee Stearns, Leah Findlater, and Jon E. Froehlich, **"Design of an Augmented Reality Magnification Aid for Low Vision Users,"** in *Proceedings of ASSETS 2018 (To Appear)*.



Common reading aids include closed circuit television (CCTV), **handheld** optical or digital magnifiers, and **smartphone** apps

AR has the potential to be **low vision users, head portable, multi-tasking, and better integrated** into a person's everyday life.



"Disability is an issue that affects every individual in their neighborhood, and in the United States".

America: Toward a National Agenda for Prevention began with these words. They

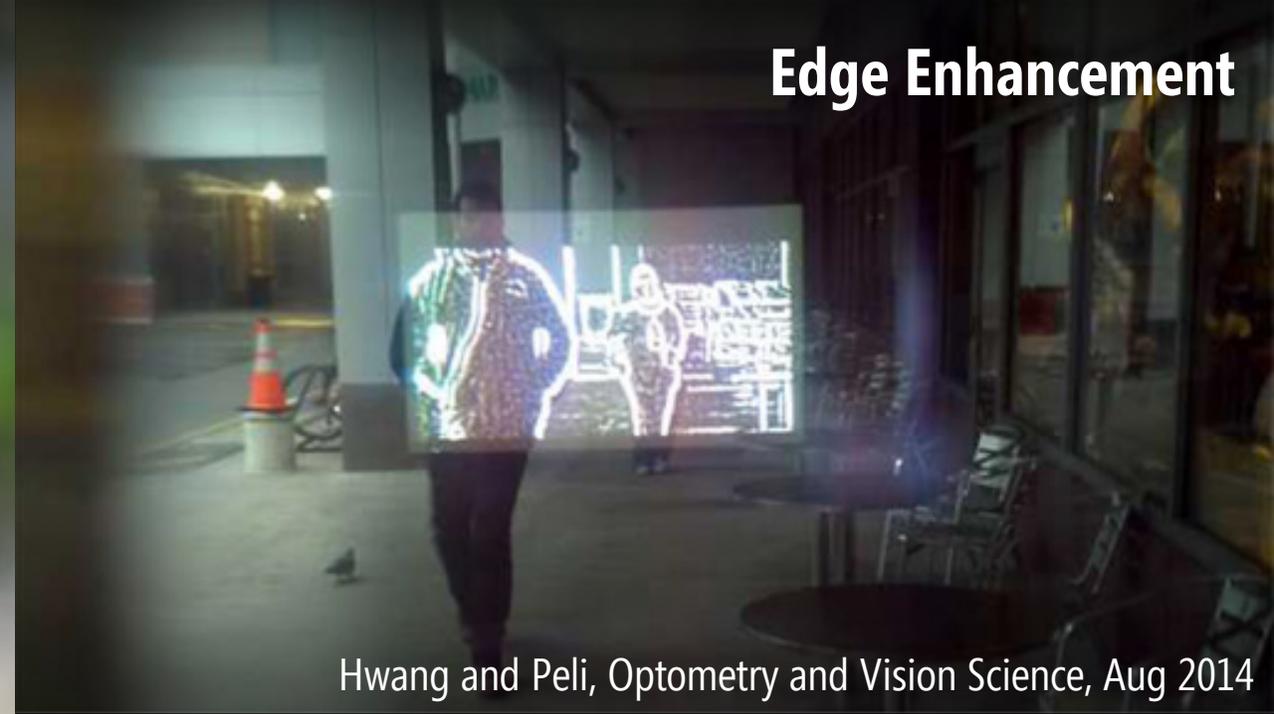
FORESEE

Zhao *et al.*, ASSETS 2015

GOOGLE GLASS

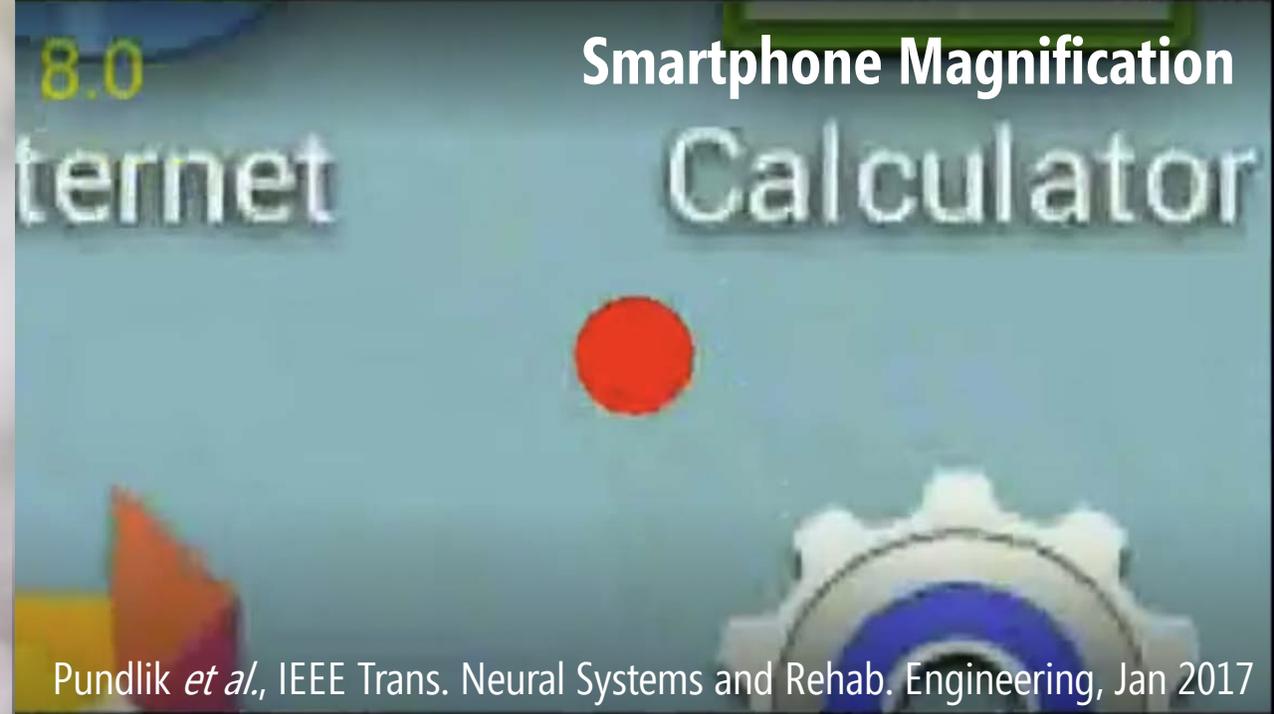


Edge Enhancement



Hwang and Peli, Optometry and Vision Science, Aug 2014

Smartphone Magnification



Pundlik *et al.*, IEEE Trans. Neural Systems and Rehab. Engineering, Jan 2017

COMMERCIAL HEAD-WORN VISION ENHANCEMENT SYSTEMS



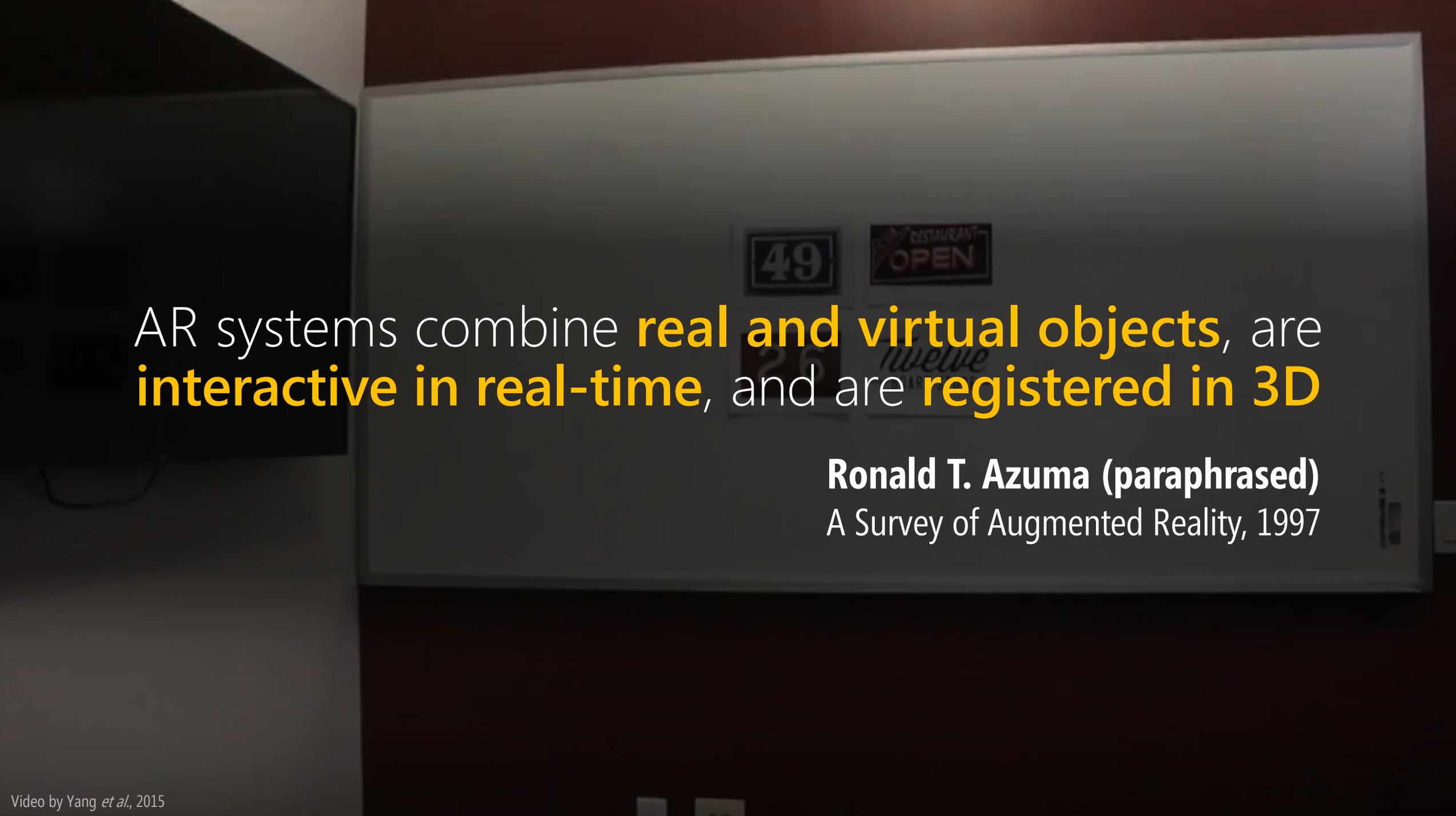
eSight



NuEyes



IrisVision



AR systems combine **real and virtual objects**, are **interactive in real-time**, and are **registered in 3D**

Ronald T. Azuma (paraphrased)
A Survey of Augmented Reality, 1997



MICROSOFT HOLOLENS

...Chesapeake Bay, predicti
...factors are contributing: geolog
...ice caps are melting; warming seaw
...weakening and carrying less water a
...The average elevation of the Deal Is
...Famine, drought, sickness and extir
...thly life if carbon emissions aren't
...ntually halted. But for Katherine



OUR APPROACH

DESIGN SPACE **GOALS**

Augment rather than **replace** existing vision capabilities

DESIGN SPACE **GOALS**

Augment rather than **replace** existing vision capabilities

Leverage **augmented reality** and persistent 3D content

DESIGN SPACE

GOALS

Augment rather than **replace** existing vision capabilities

Leverage **augmented reality** and persistent 3D content

Prioritize **customization** and **flexibility**

INITIAL INVESTIGATION: HOLOLENS DESIGN



Built-in camera to capture images



Two display modes:

Fixed 2D & Fixed 3D



Voice Commands to select mode



Image Enhancements:

Binary threshold & Invert colors



INITIAL INVESTIGATION: HOLOLENS **OBSERVATIONS**

Camera resolution too low

Turning head to look at desired content was uncomfortable

Voice commands cumbersome, imprecise, limited customization



AR PROTOTYPE 1

HoloLens and Finger-Camera



HoloLens

Camera

PHYSICAL DESIGN

AR PROTOTYPE 1: HOLOLENS AND FINGER-CAMERA

**Camera
LED**

Custom Mount

PHYSICAL DESIGN

AR PROTOTYPE 1: HOLOLENS AND FINGER-CAMERA



Virtual Display Design 1: Fixed 2D

Acts as a heads-up display, stays in the user's view at all times



VIRTUAL DISPLAYS

AR PROTOTYPE 1: HOLOLENS AND FINGER-CAMERA

Aa Bb



Users customize the position and size of the display for each design using midair tap and drag gestures



USER INTERACTIONS

AR PROTOTYPE 1: HOLOLENS AND FINGER-CAMERA



AR PROTOTYPE 1: HOLOLENS AND FINGER-CAMERA

METHOD



3 **Low Vision Participants** (1 Female, 2 Male, Ages 28-54)
Each participant used **three virtual display designs** to read **documents and other text** (e.g., mail, pill bottle, cereal box)

AR PROTOTYPE 1: HOLOLENS AND FINGER-CAMERA

METHOD



They provided **feedback and suggestions** on their likes, dislikes, design preferences, ideas for improvements or new features

AR PROTOTYPE 1: HOLOLENS AND FINGER-CAMERA

FINDINGS

Virtual Display Designs



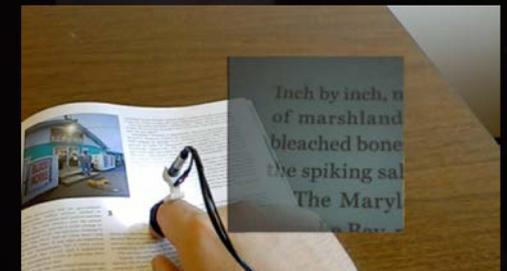
Fixed 3D (Vertical or Horizontal)

Reading experience similar to using a CCTV or handheld magnifier.



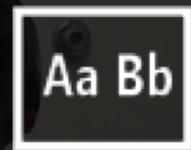
Finger Tracking

Can help to quickly search a document.



Fixed 2D

Always visible, required least concentration.

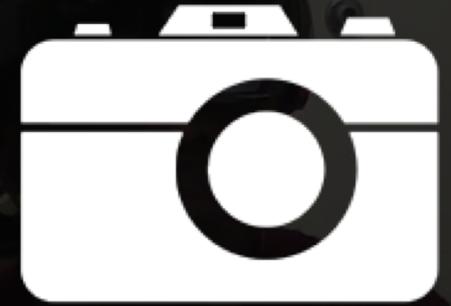


AR PROTOTYPE 1: HOLOLENS AND FINGER-CAMERA

FINDINGS

Finger-Worn Camera

- [+] Flexible, allows hands-free use
- [-] Requires moving finger to read
- [-] Small field of view (~3-4 lines)



AR PROTOTYPE 1: HOLOLENS AND FINGER-CAMERA

FINDINGS

HoloLens Display

- [-] Low contrast due to transparency
- [-] Narrow view, center of vision



AR PROTOTYPE 1: HOLOLENS AND FINGER-CAMERA

FINDINGS

User Input

- [-] Midair gestures difficult to use
- [-] Unable to make quick adjustments



AR PROTOTYPE 2

HoloLens and Smartphone



HoloLens

iPhone

PHYSICAL DESIGN

AR PROTOTYPE 2: HOLOLENS AND SMARTPHONE

AR PROTOTYPE 2: HOLOLENS AND SMARTPHONE

PHYSICAL DESIGN



Virtual Display Design 1: Attached to Headset

Maintains fixed position relative to the user at all times

VIRTUAL DISPLAYS

AR PROTOTYPE 2: HOLOLENS AND SMARTPHONE

Aa Bb



Each design included several options for customization, including the position, size, and contrast/colors

USER INTERACTIONS

AR PROTOTYPE 2: HOLOLENS AND SMARTPHONE





AR PROTOTYPE 2: HOLOLENS AND SMARTPHONE METHOD

6 **Low Vision Participants** (3 Female, 3 Male, Ages 28-68)
Each participant used **three virtual display designs** to read
documents and other text (e.g., mail, pill bottle, cereal box)

AR PROTOTYPE 2: HOLOLENS AND SMARTPHONE

FINDINGS

Participants were **more successful and positive** about their experience using this version of our system.

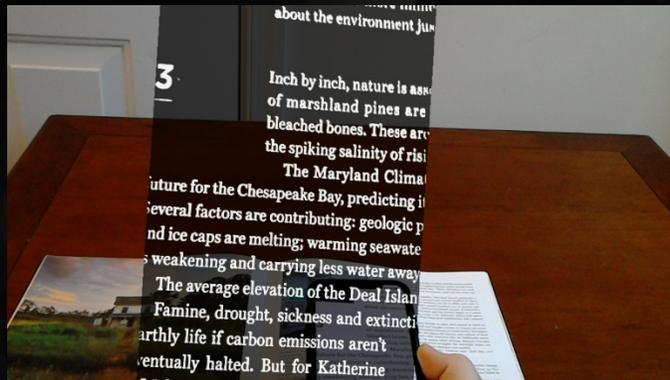
They were better able to experience the **AR aspects of our approach**, which most participants found promising.

AR PROTOTYPE 2: HOLOLENS AND SMARTPHONE

FINDINGS

Virtual Display Designs

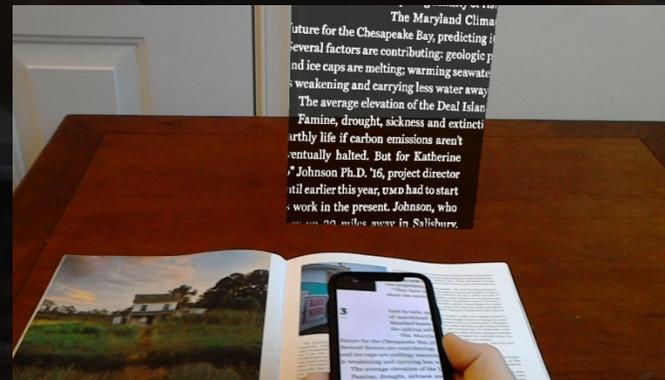
Aa Bb



Attached to Headset

Easier to focus on the text

Potentially distracting



Attached to World

Natural reading experience

Easier to multitask



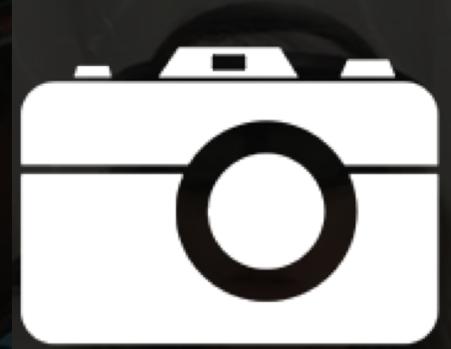
Attached to Phone

Versatile

Intuitive interactions

AR PROTOTYPE 2: HOLOLENS AND SMARTPHONE

FINDINGS



Smartphone

- [+] Better camera
- [+] More usable interactions
- [-] No longer hands-free
- [-] Too heavy for extended use



AR PROTOTYPE 2: HOLOLENS AND SMARTPHONE FINDINGS



HoloLens

Issues with contrast, field of view, and physical size and weight still present.

Participants with central vision loss struggled to use the system.

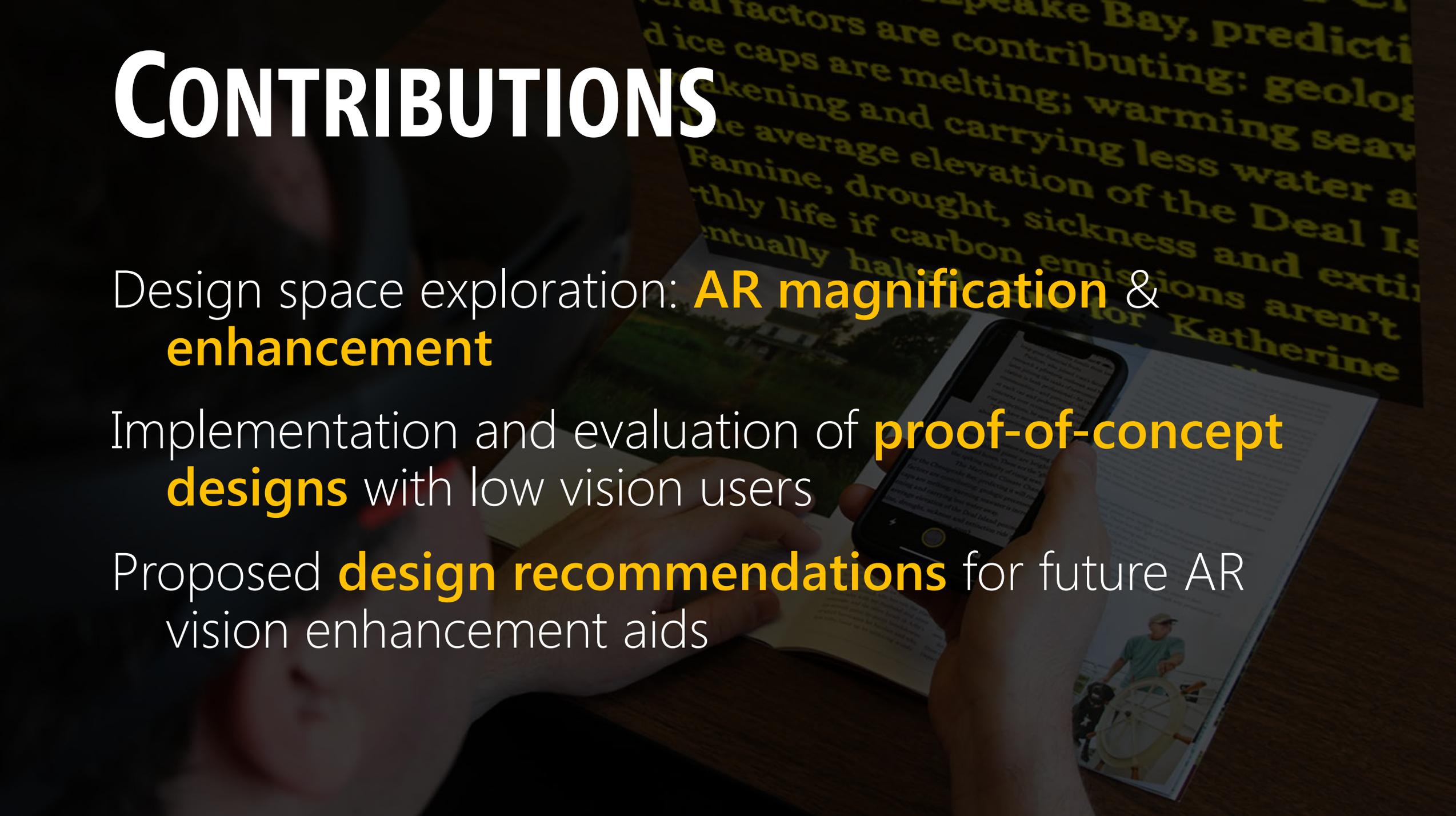


CONCLUSIONS

Strengths and Weaknesses of 3D AR for Magnification

- [+] Enables new interactions not possible with other approaches
- [+] Good for multitasking
- [-] May require more effort to use than fixed 2D display

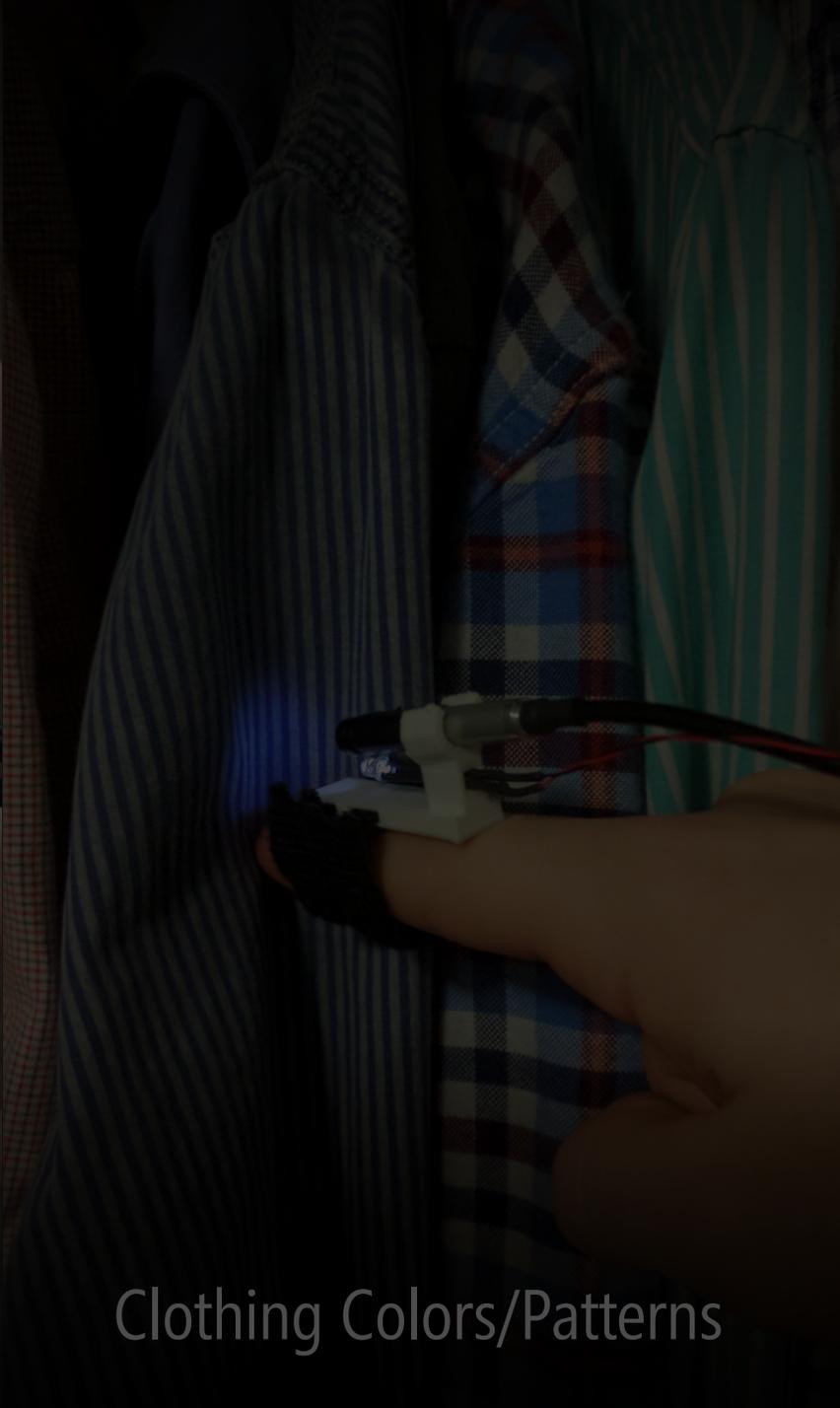
CONTRIBUTIONS



Design space exploration: **AR magnification & enhancement**

Implementation and evaluation of **proof-of-concept designs** with low vision users

Proposed **design recommendations** for future AR vision enhancement aids



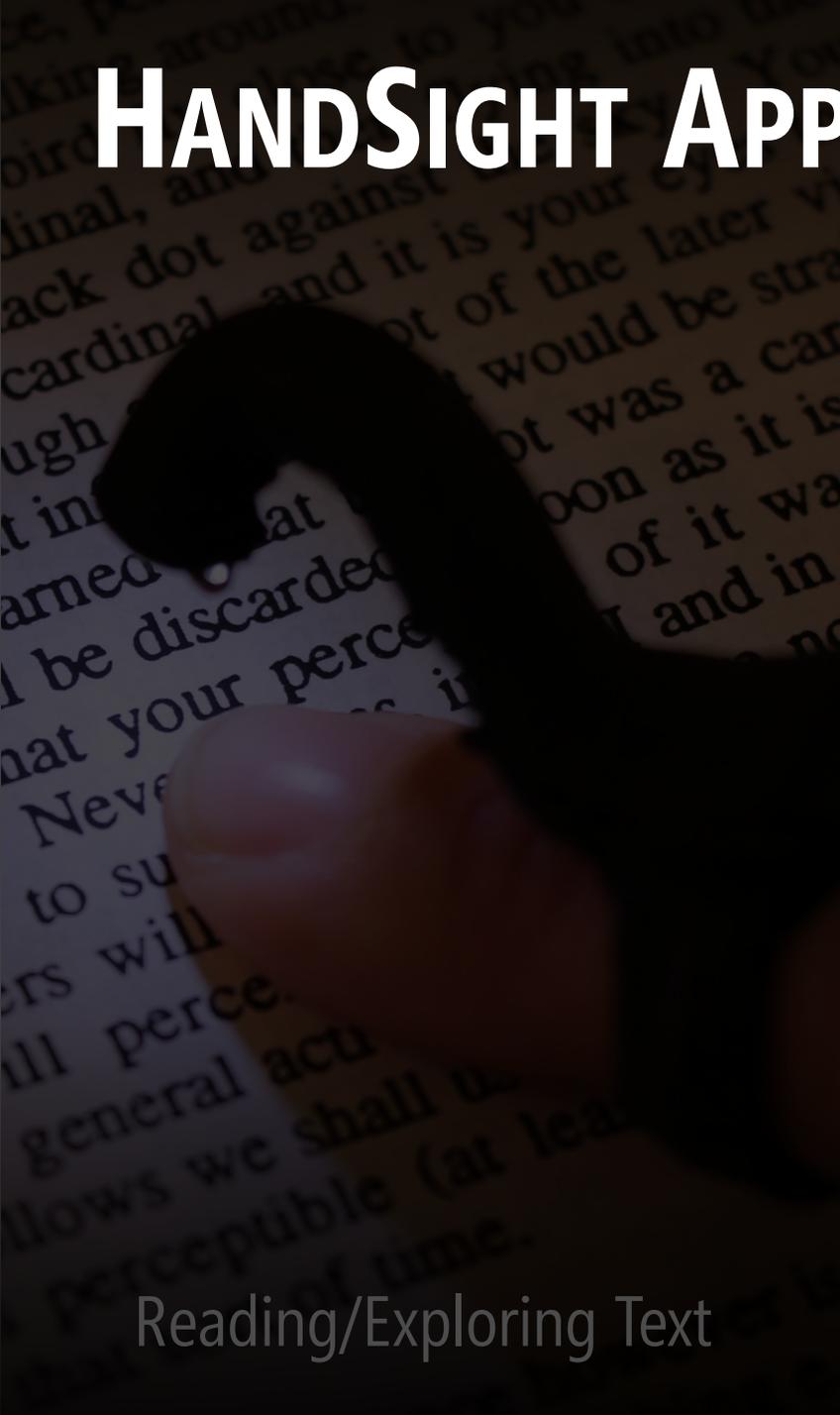
HANDSIGHT APPLICATION AREAS

Reading/Exploring Text

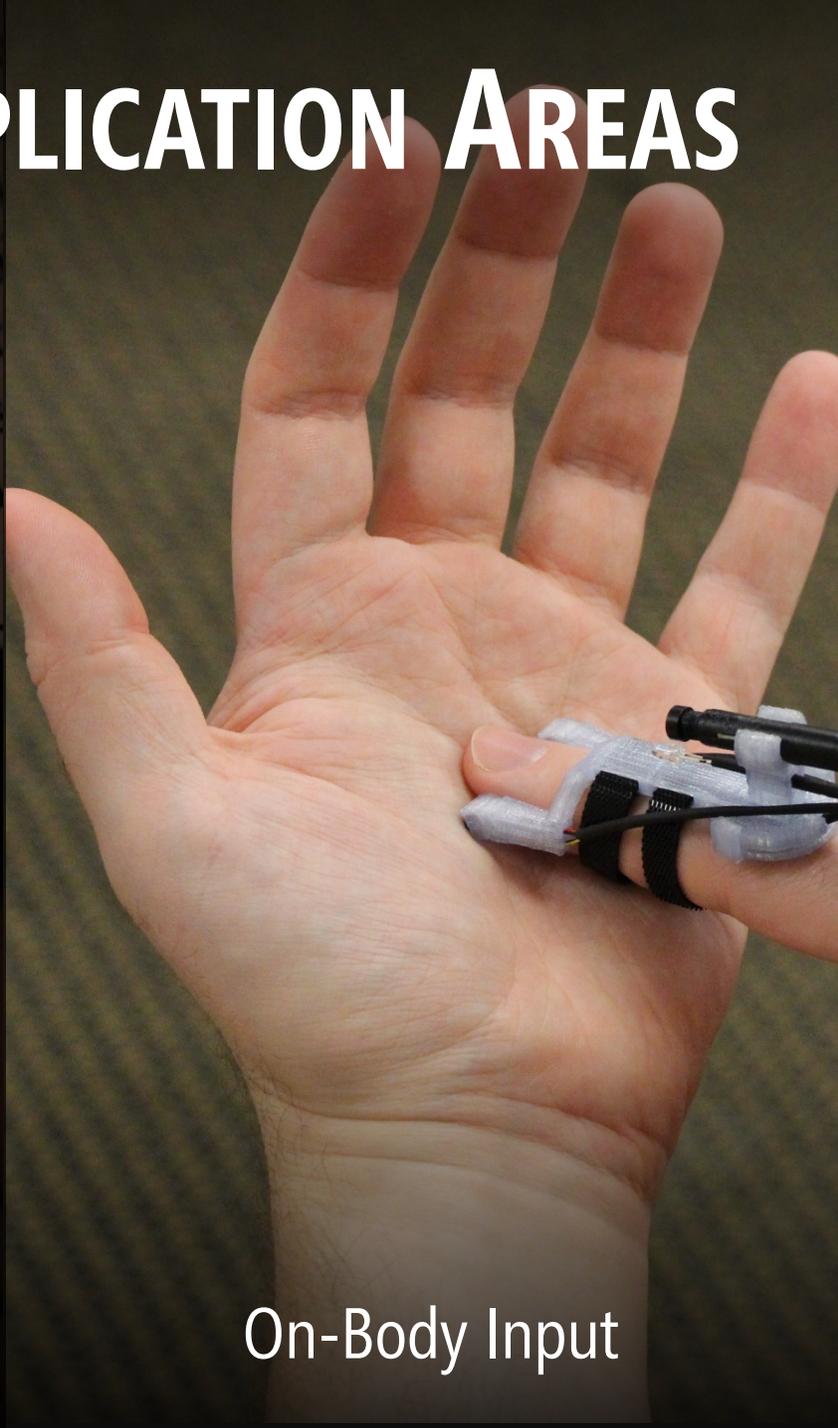
On-Body Input

Clothing Colors/Patterns

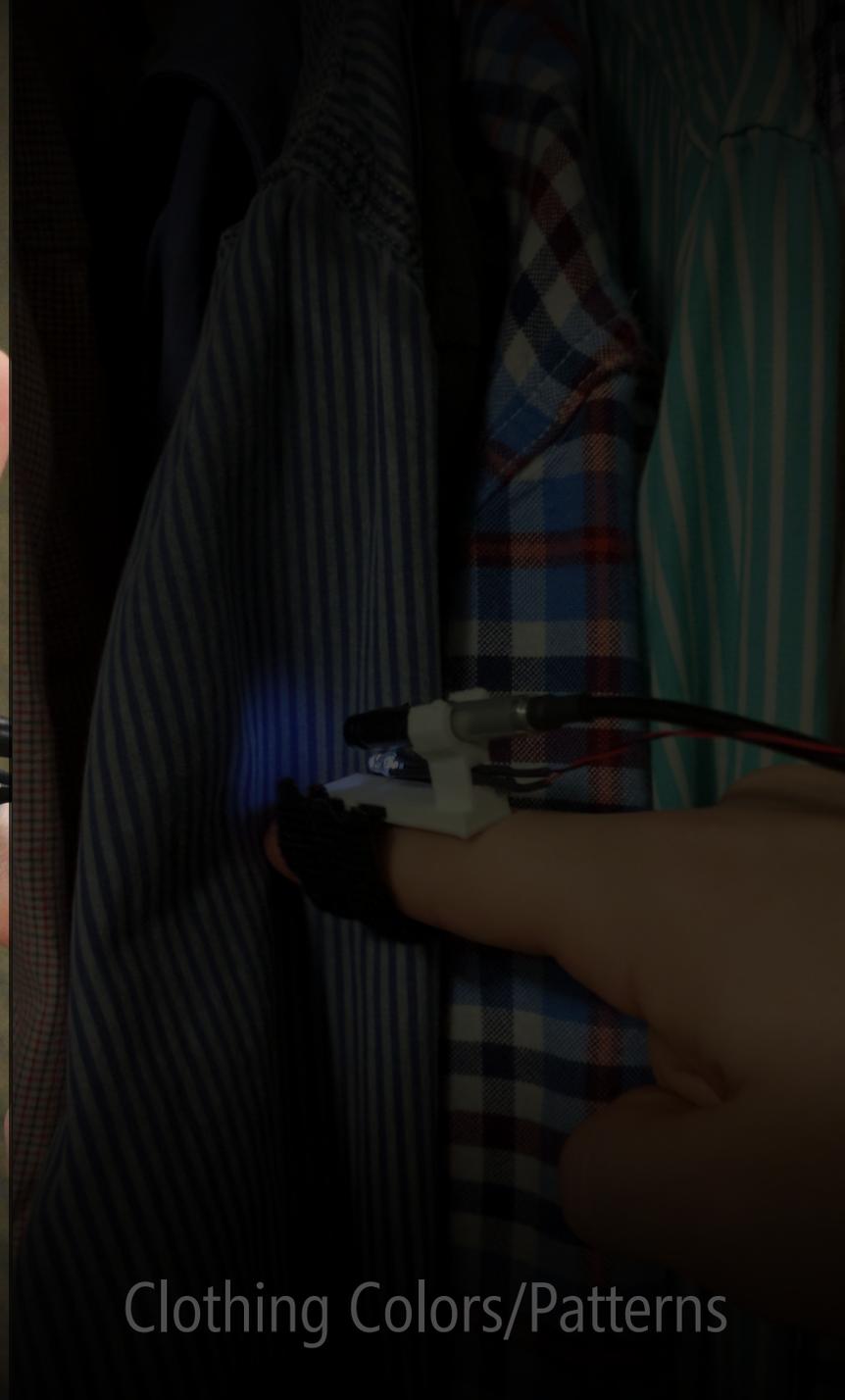
HANDSIGHT APPLICATION AREAS



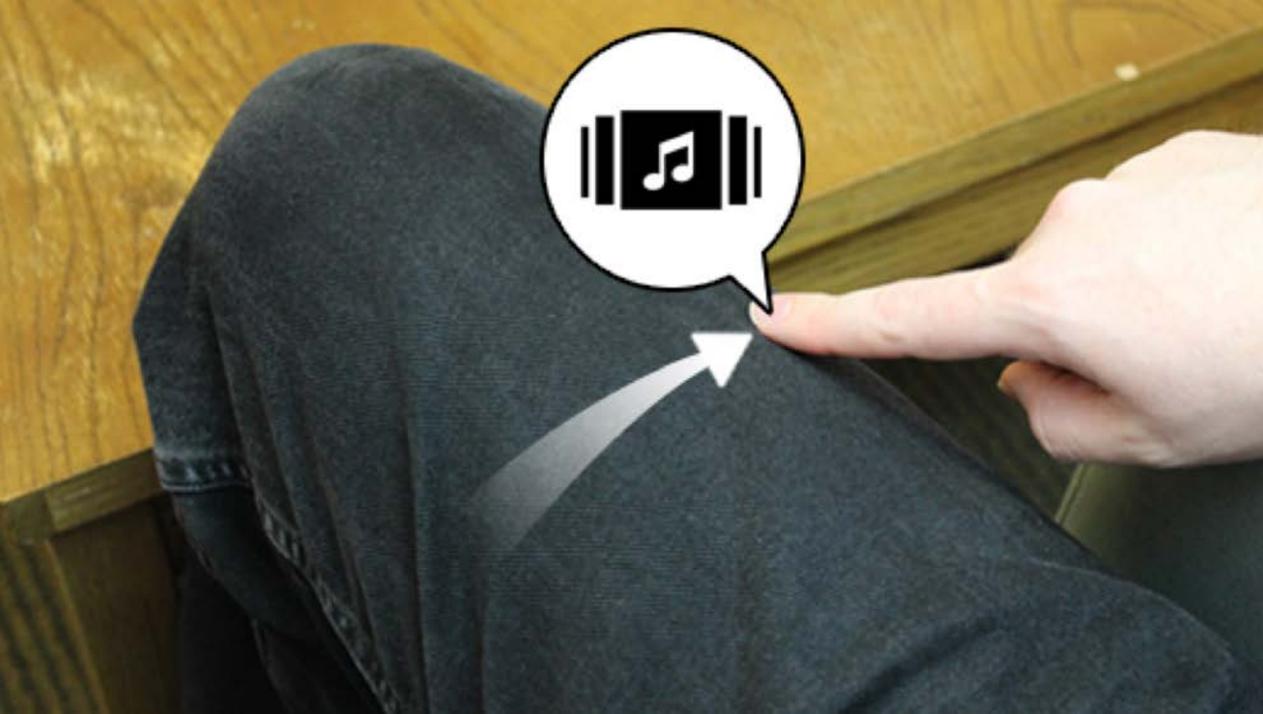
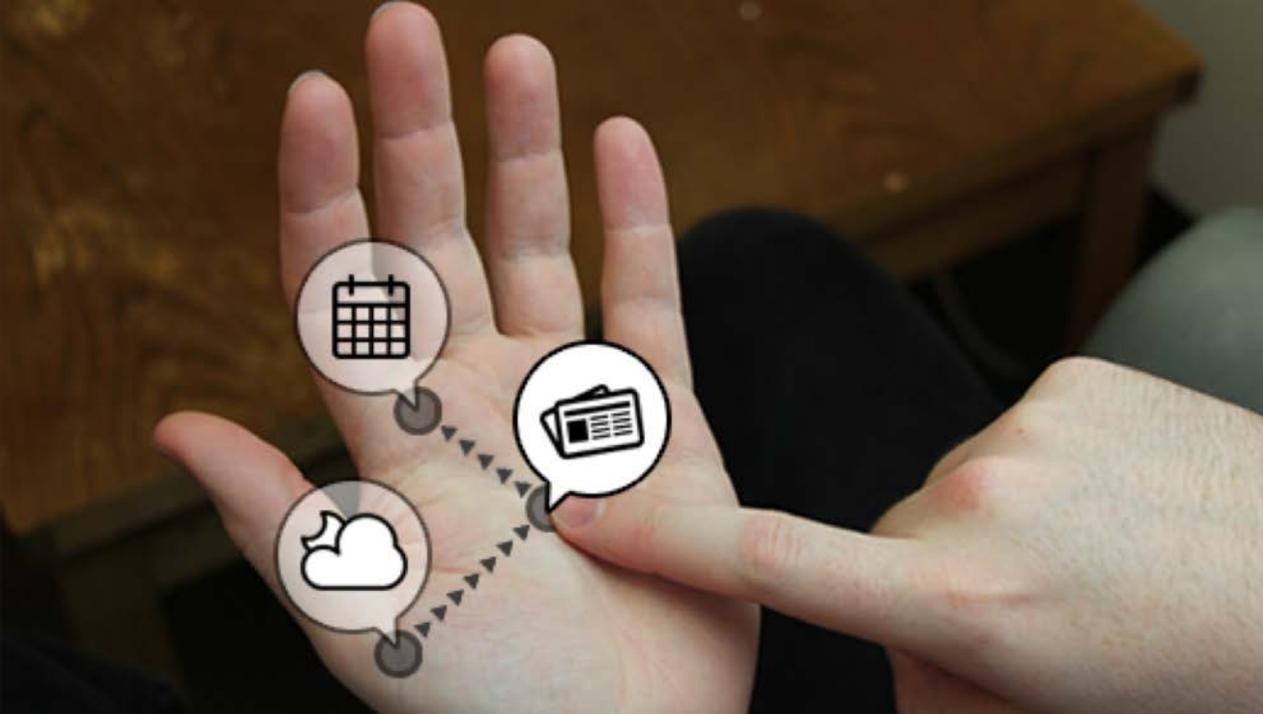
Reading/Exploring Text



On-Body Input



Clothing Colors/Patterns



ON-BODY INPUT

USING FINGER-WORN SENSORS

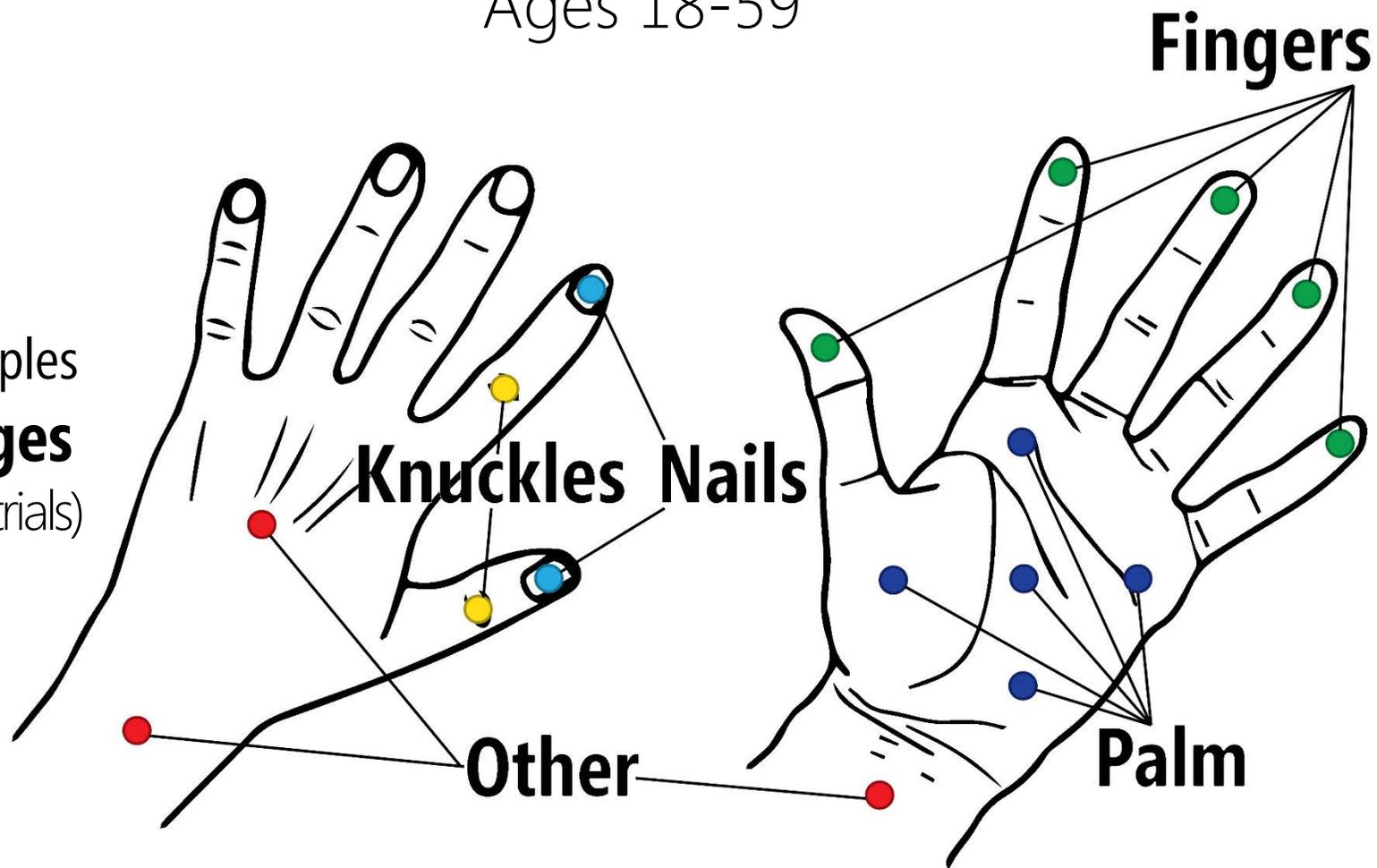
Advantages:

1. More easily **scalable** to other body locations and surfaces
2. Larger **input vocabulary**: touch position × relative gestures
3. Simplified **sensing and processing** due to sensor positioning

ON-BODY STUDY I DATASET

30 Sighted Participants
23 Female, 7 Male
Ages 18-59

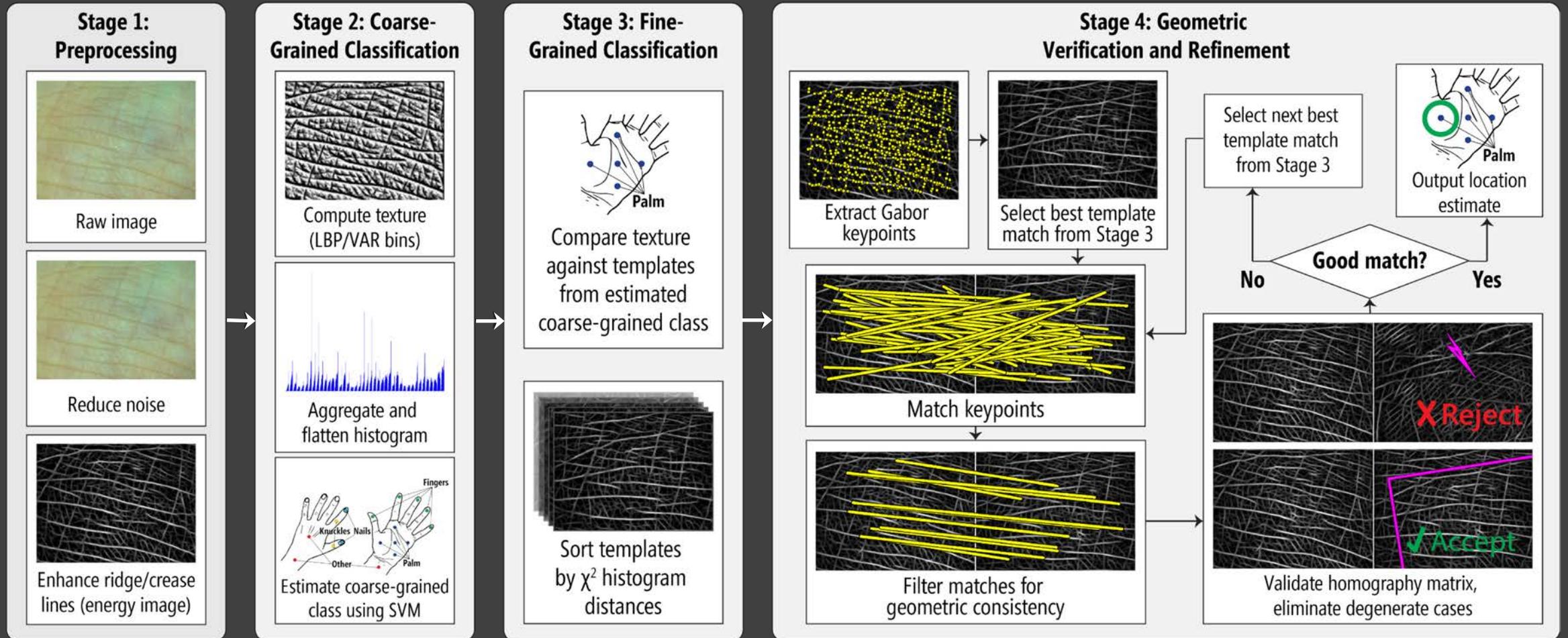
30 participants \times 17 locations \times 20 samples
Total dataset size: 10,198 images
(one participant accidentally skipped two trials)



Lee Stearns, Uran Oh, Bridget J. Cheng, Leah Findlater, David Ross, Rama Chellappa, and Jon E. Froehlich, "Localization of Skin Features on the Hand and Wrist from Small Image Patches," in *Proceedings of ICPR 2016*.

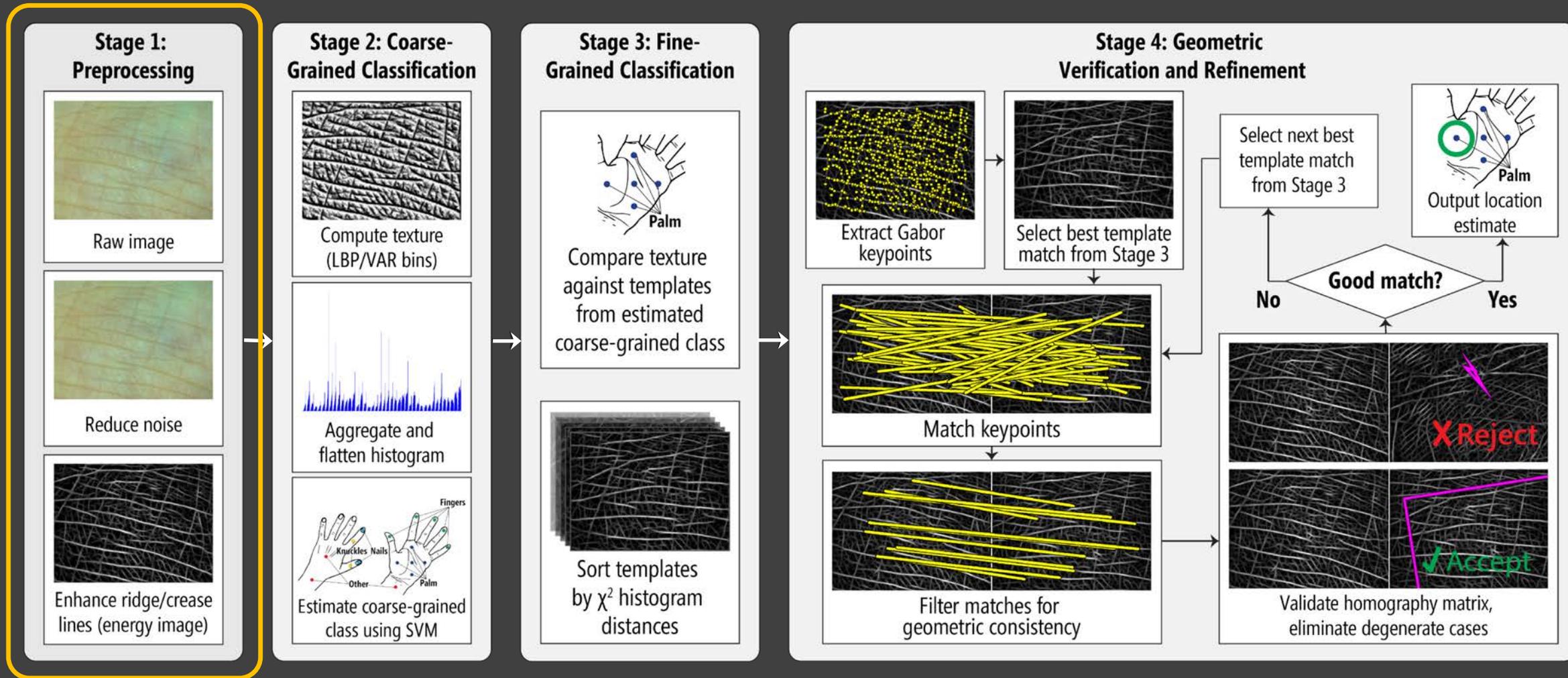
ON-BODY STUDY I

ALGORITHMS



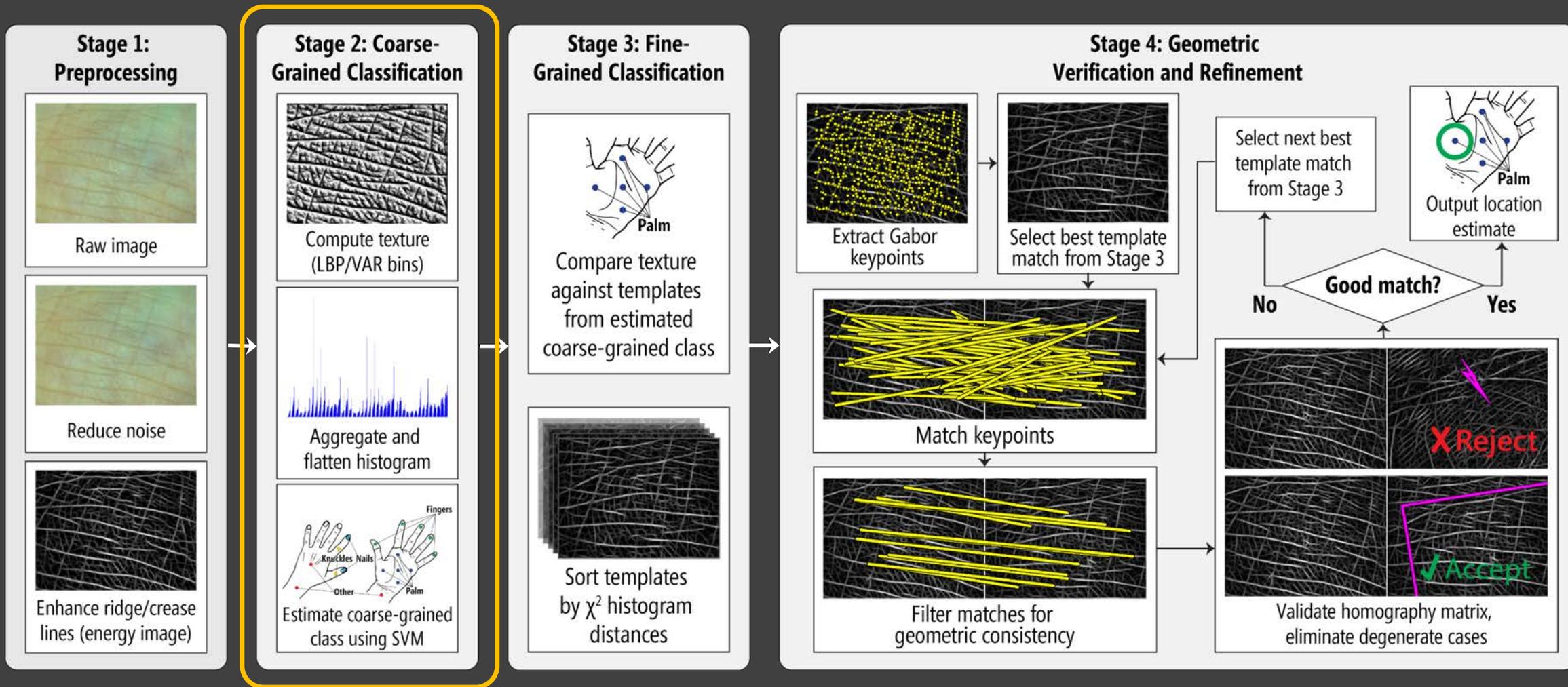
ON-BODY STUDY I

ALGORITHMS



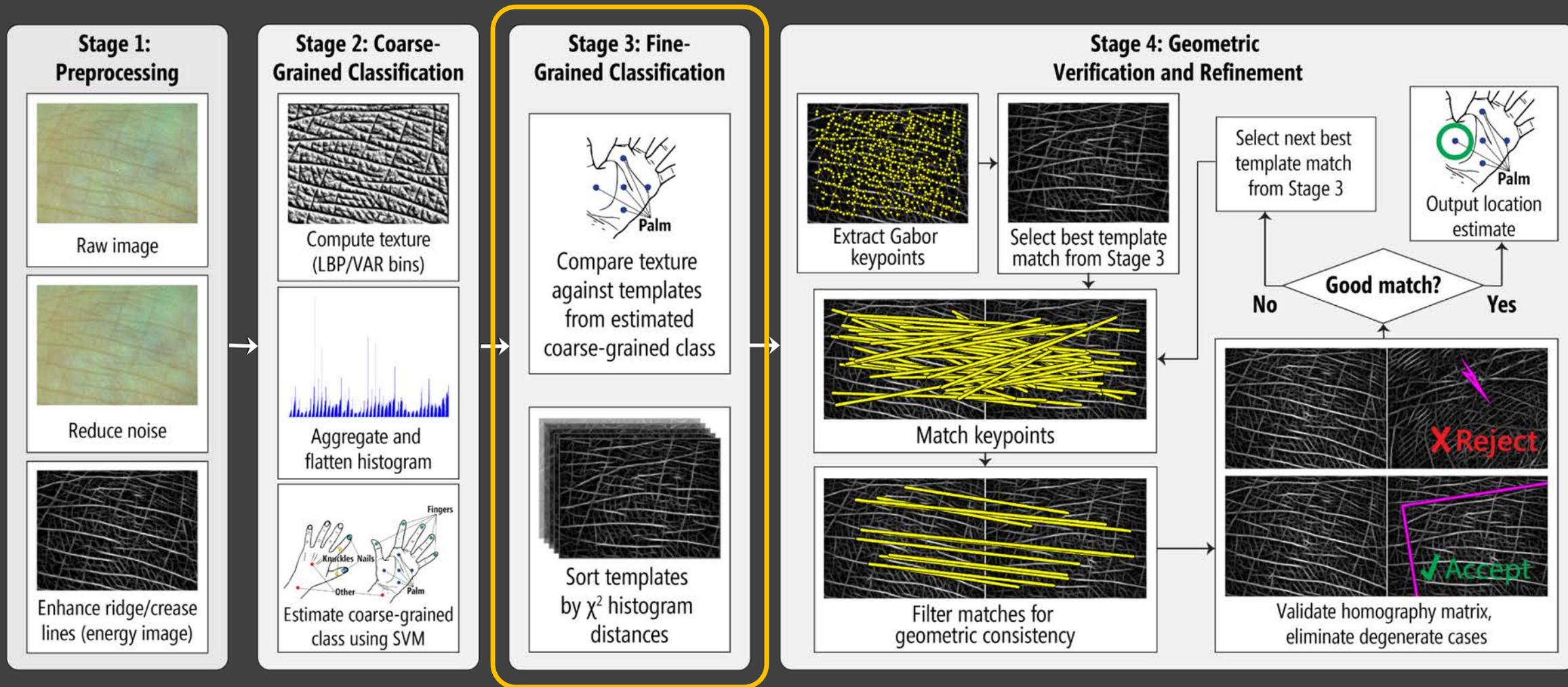
ON-BODY STUDY I

ALGORITHMS



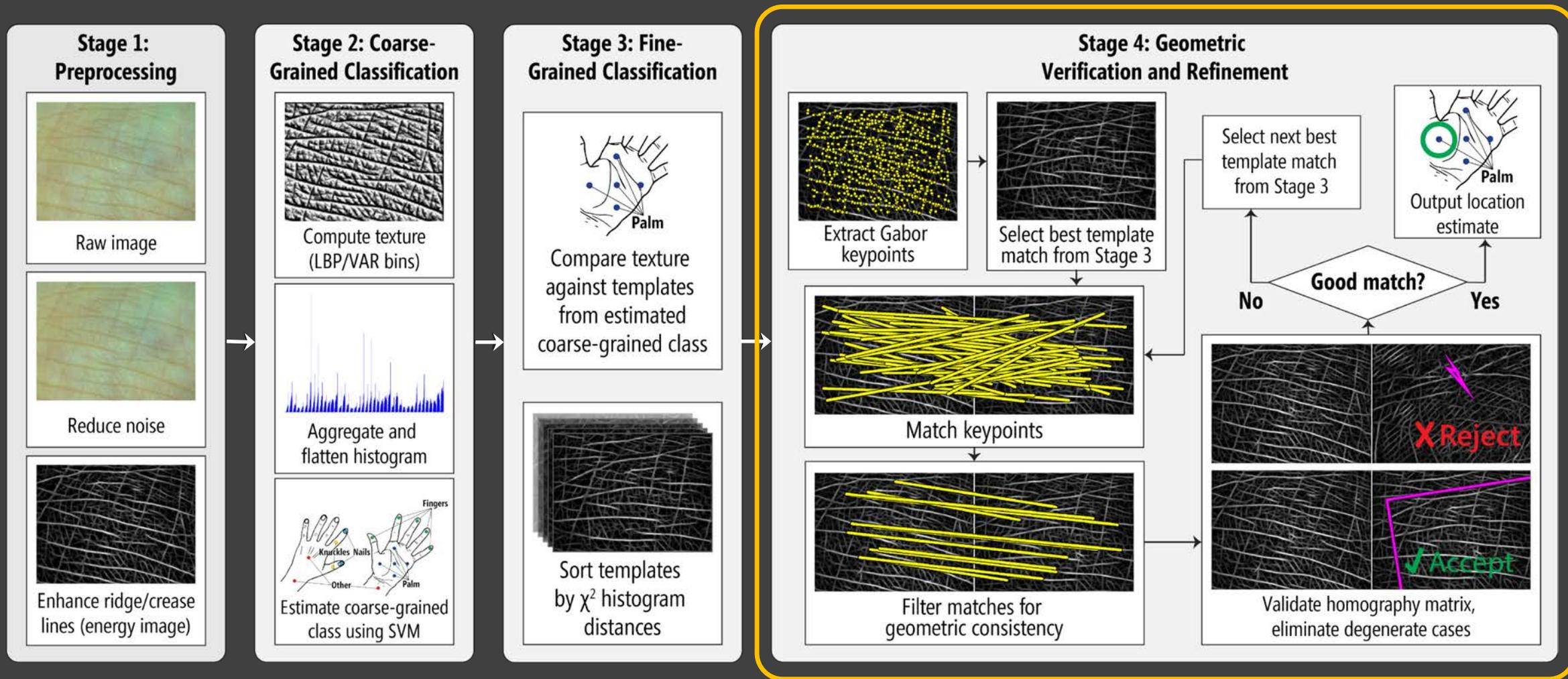
ON-BODY STUDY I

ALGORITHMS



ON-BODY STUDY I

ALGORITHMS



ON-BODY STUDY I

EXPERIMENTS AND RESULTS

Within-Person Classification Experiment ($n=30$)

Coarse-Grained Localization (Stage 2)

(5 classes: ● finger, ● palm, ● knuckle, ...)

accuracy: **99.1%** ($SD=0.9\%$)

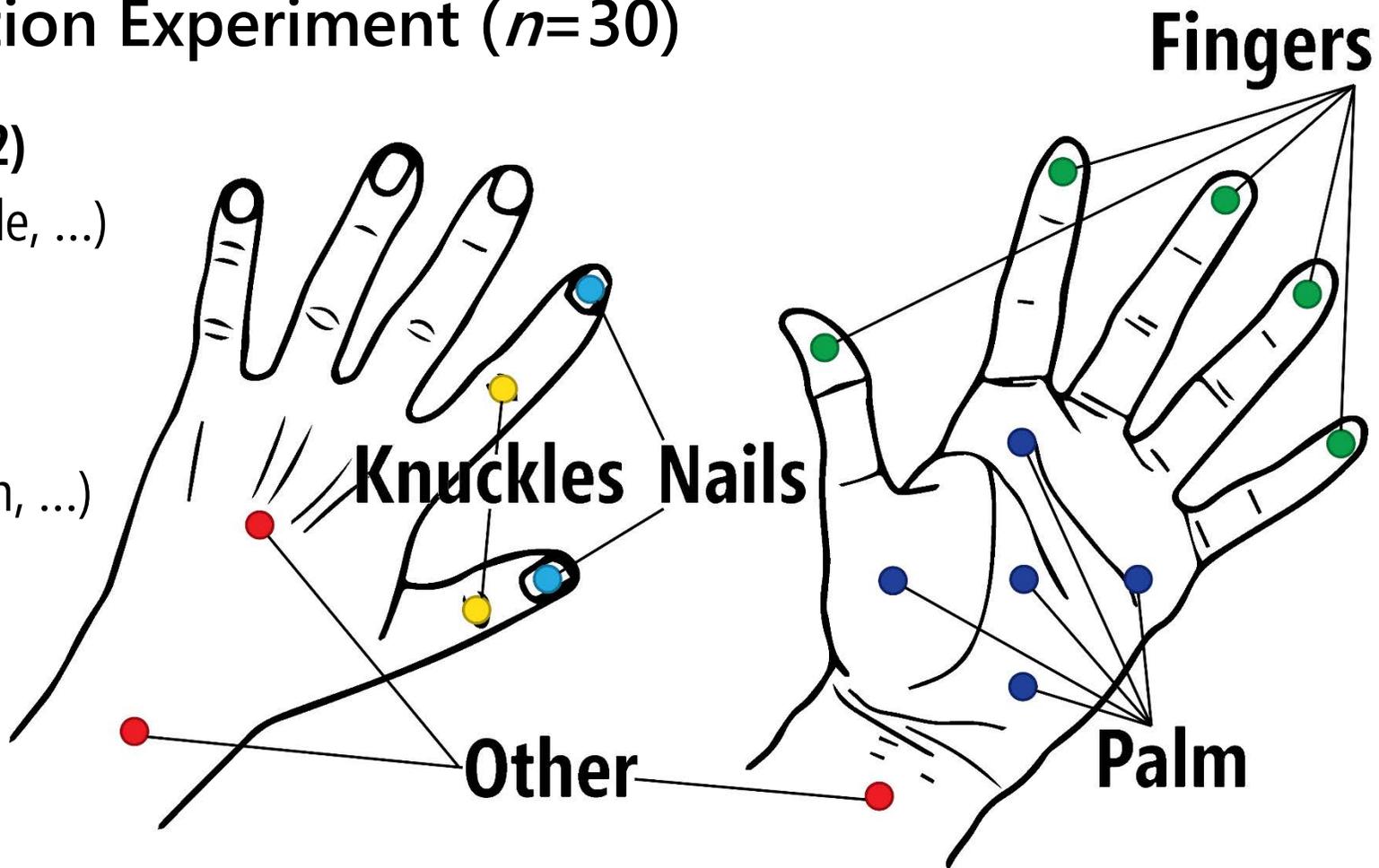
Fine-Grained Localization (Stage 3)

(17 classes: ● palm up, ● palm down, ...)

accuracy: **88.0%** ($SD=4.5\%$)

Fine-Grained Localization (Stage 4)

accuracy: **96.4%** ($SD=2.3\%$)



ON-BODY STUDY I

EXPERIMENTS AND RESULTS

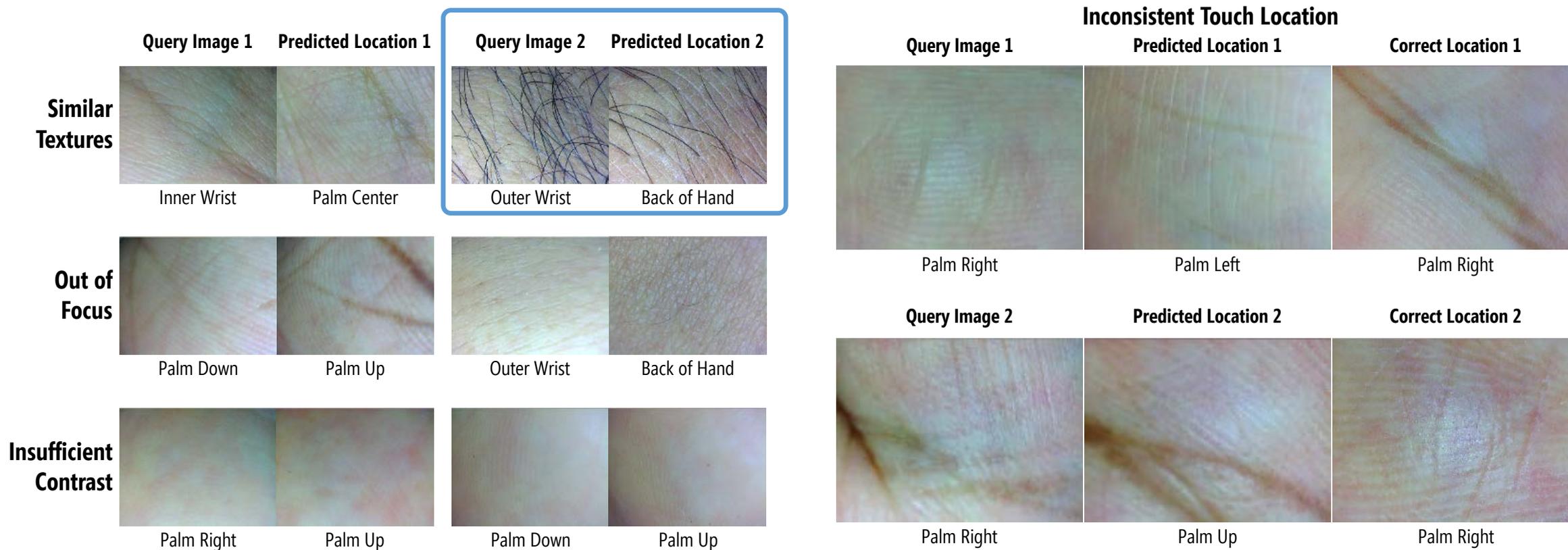
Within-Person Classification Experiment ($n=30$)



ON-BODY STUDY I

EXPERIMENTS AND RESULTS

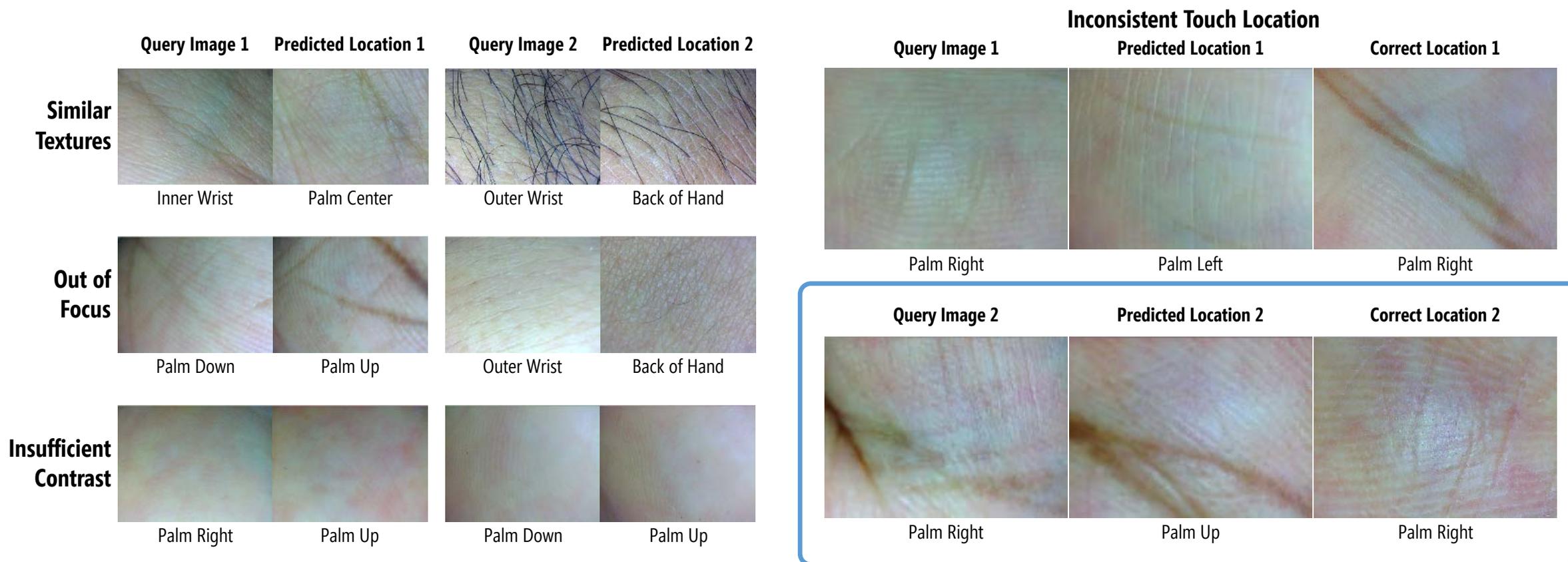
Within-Person Classification Experiment ($n=30$)



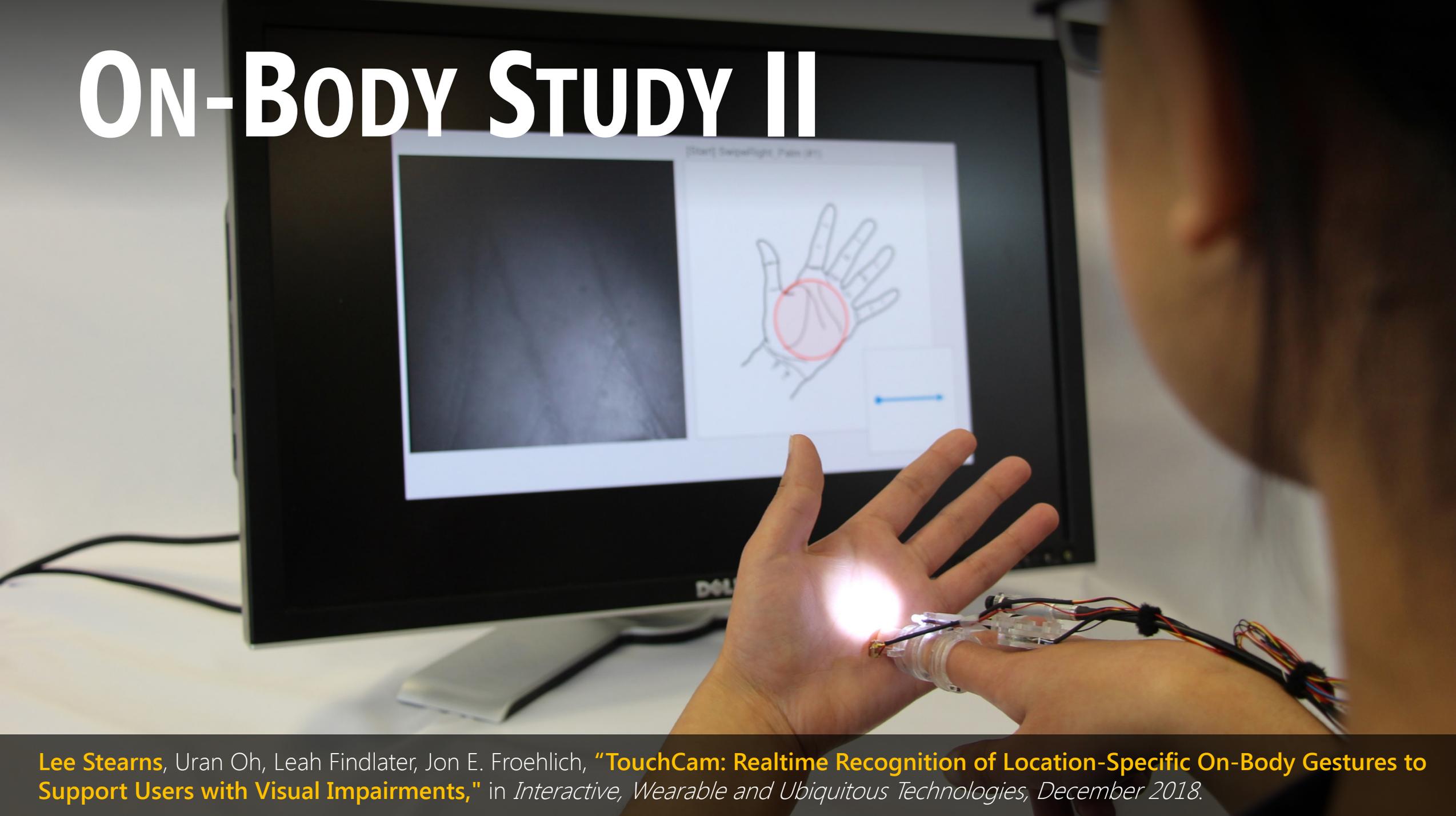
ON-BODY STUDY I

EXPERIMENTS AND RESULTS

Within-Person Classification Experiment ($n=30$)

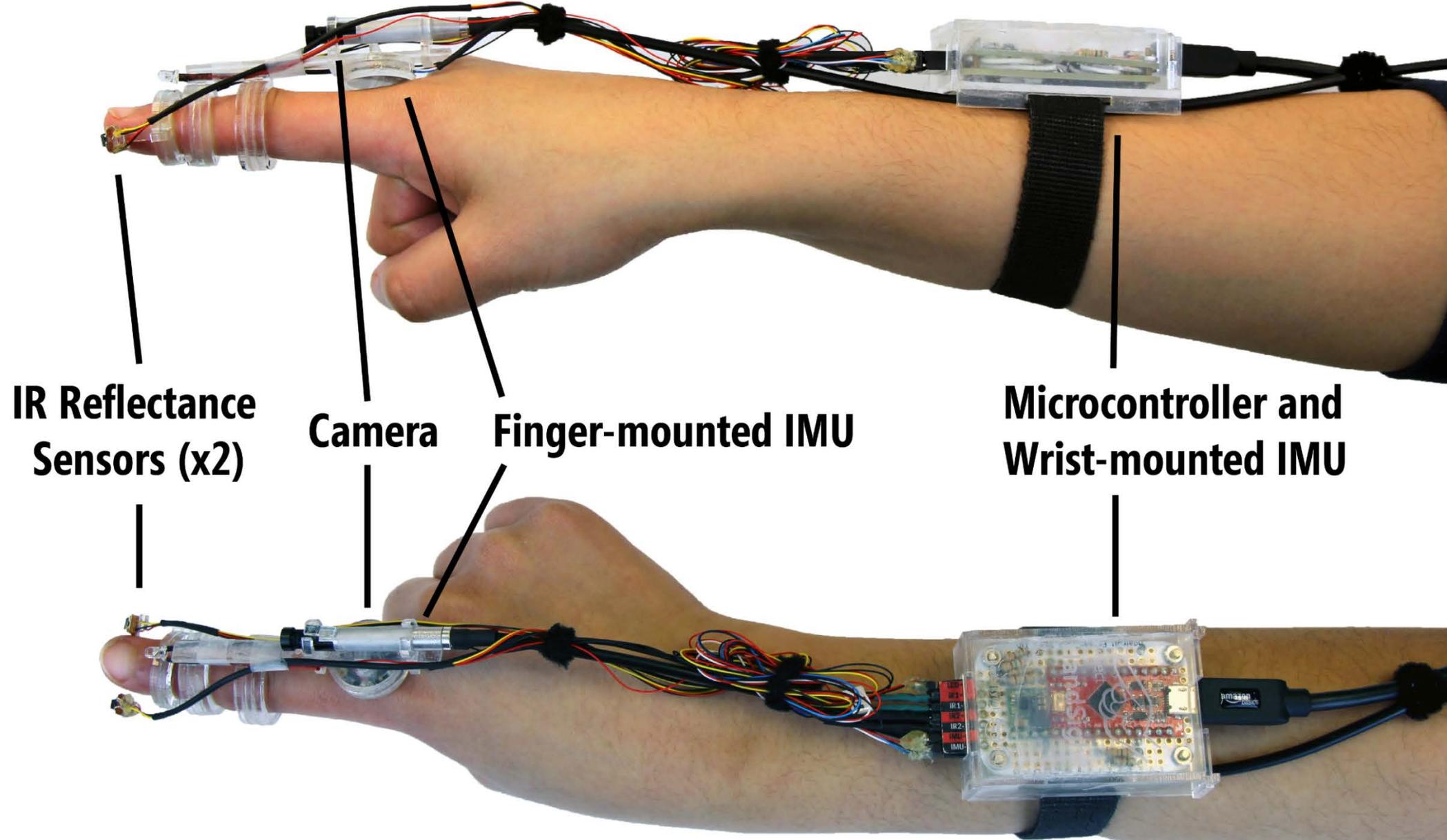


ON-BODY STUDY II



Lee Stearns, Uran Oh, Leah Findlater, Jon E. Froehlich, **"TouchCam: Realtime Recognition of Location-Specific On-Body Gestures to Support Users with Visual Impairments,"** in *Interactive, Wearable and Ubiquitous Technologies*, December 2018.

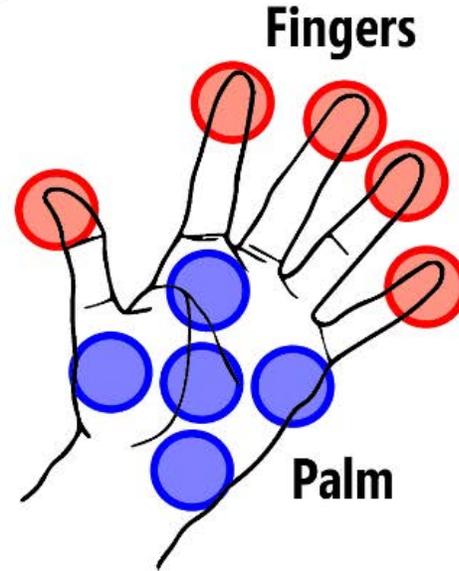
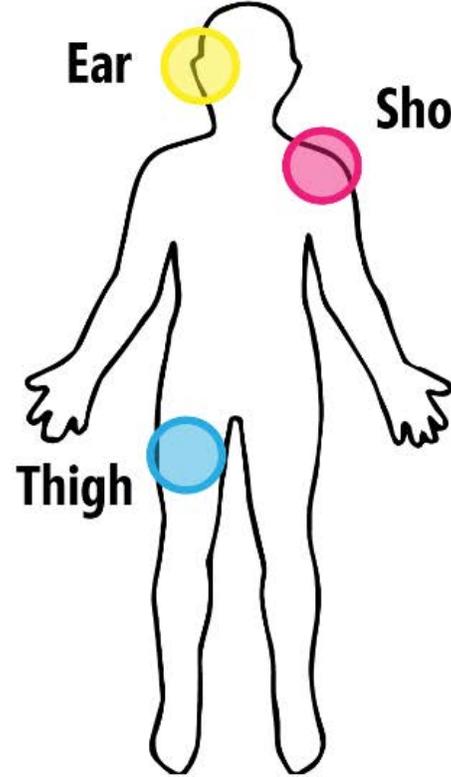
OFFLINE PROTOTYPE



DATA COLLECTION

15 Body Locations

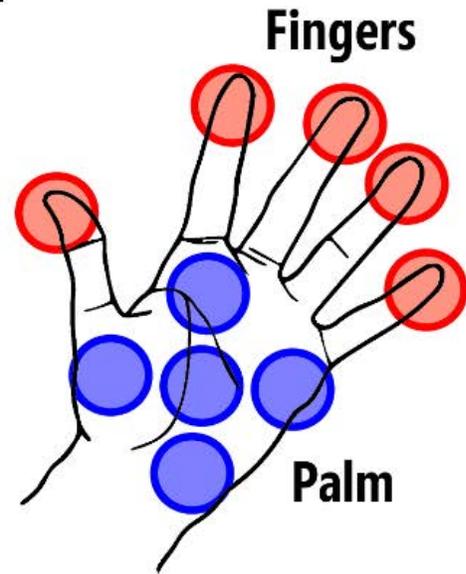
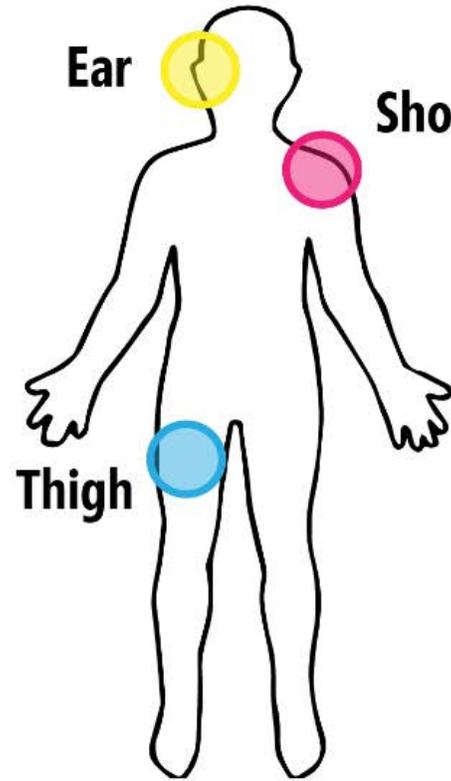
24 Sighted Participants
16 Female, 8 Male
Ages 19-51



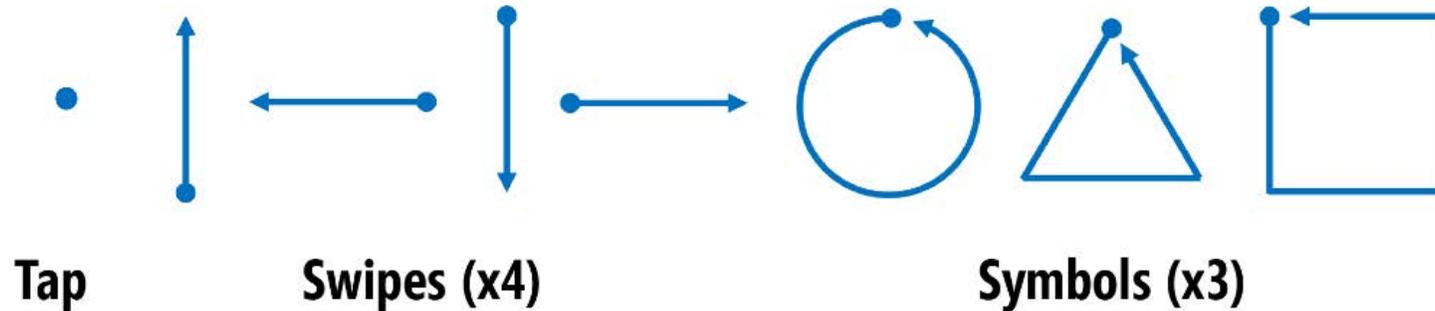
DATA COLLECTION

24 Sighted Participants
16 Female, 8 Male
Ages 19-51

15 Body Locations



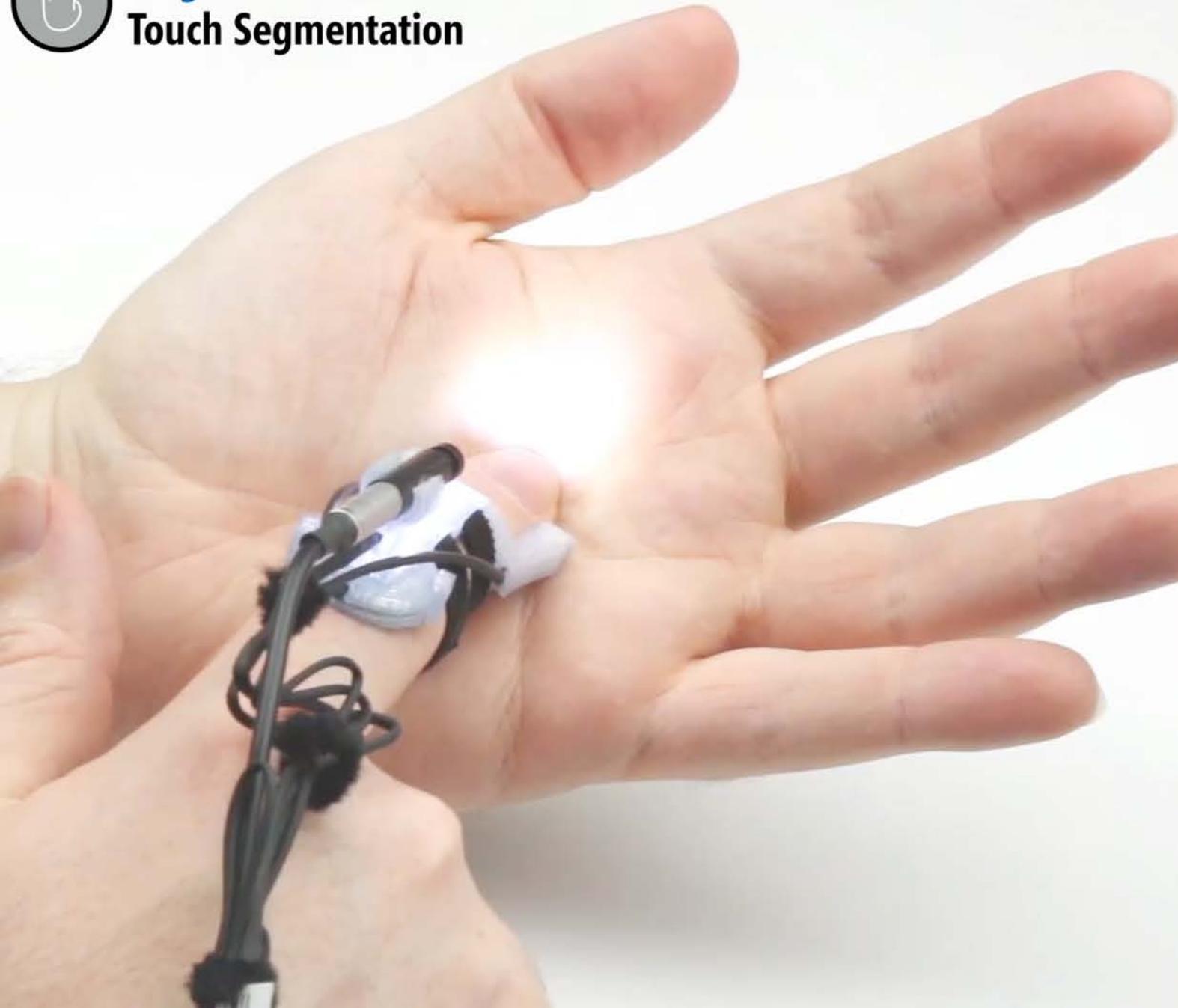
8 Basic Gestures



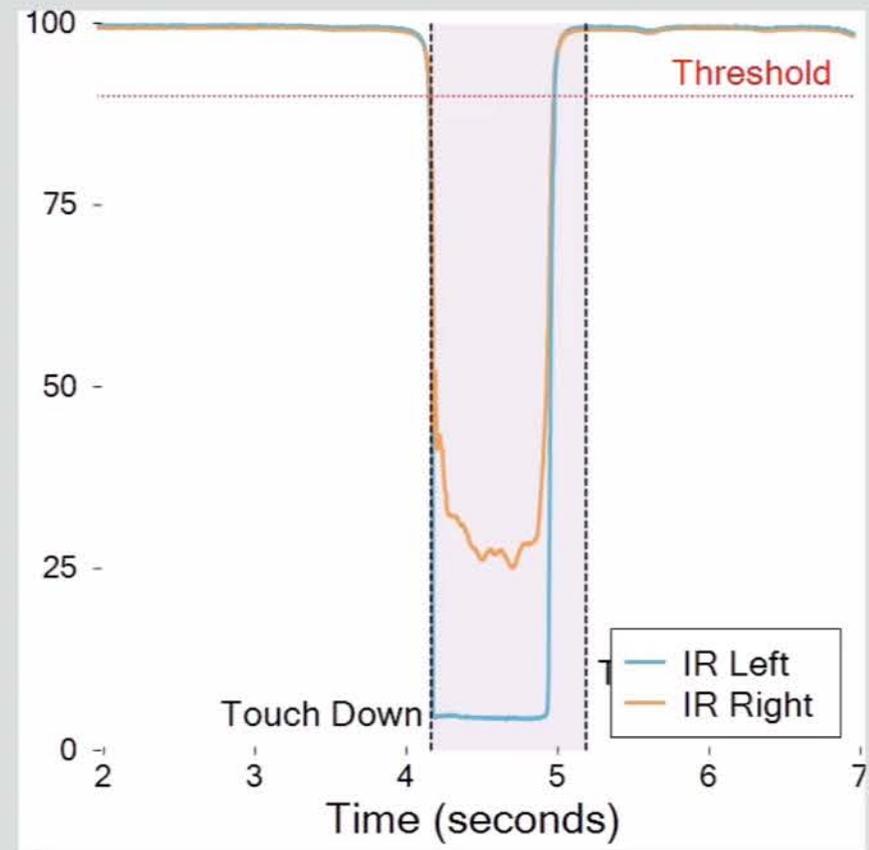


Stage I

Touch Segmentation



Signals



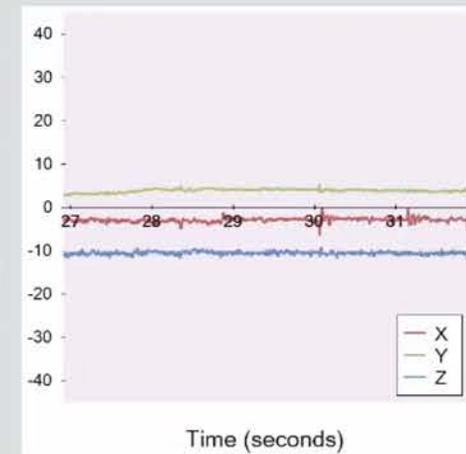
IR(% Max)



Stage II Feature Extraction

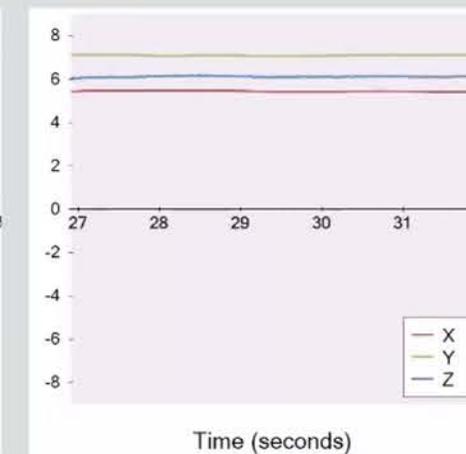
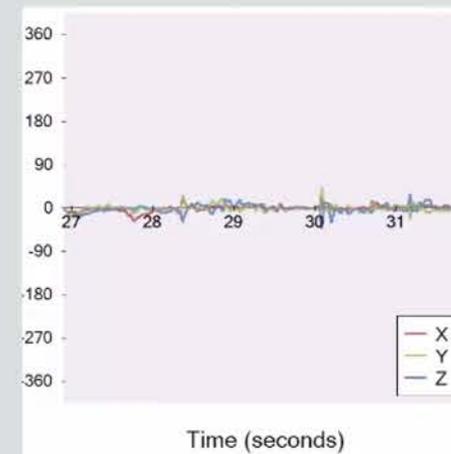


Signals



Camera

Accelerometer (m/s²)



Gyroscope (°/s)

Magnetometer (gauss)



Stage III
Localization



Signals



Palm Center

Camera

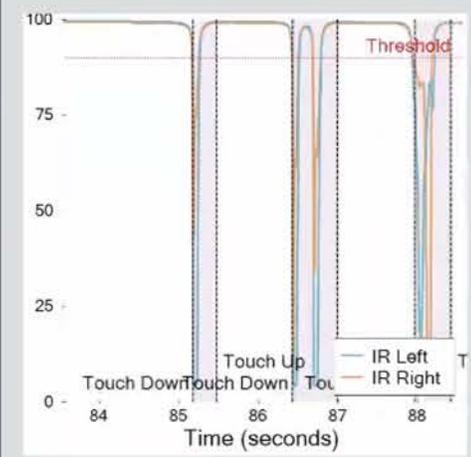


Stage IV Gesture Classification

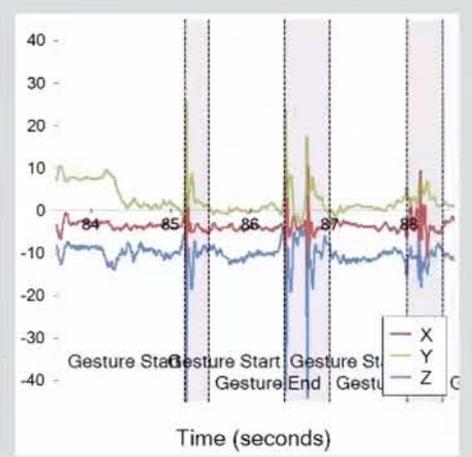
Swipe Right



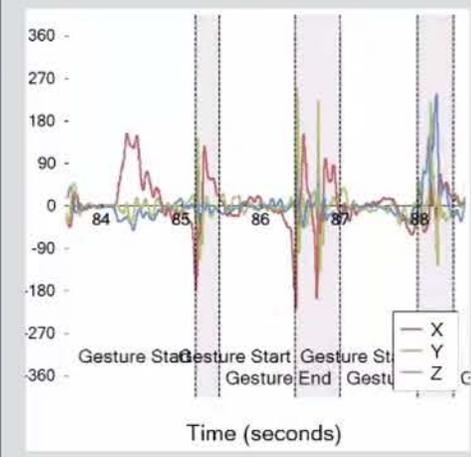
Signals



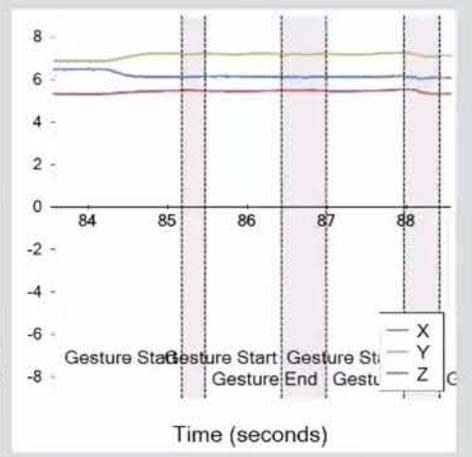
IR (% Max)



Accelerometer (m/s²)



Gyroscope (°/s)



Magnetometer (gauss)

ON-BODY STUDY I

EXPERIMENTS AND RESULTS

Within-Person Classification Experiment ($n=24$)

Coarse-Grained Localization

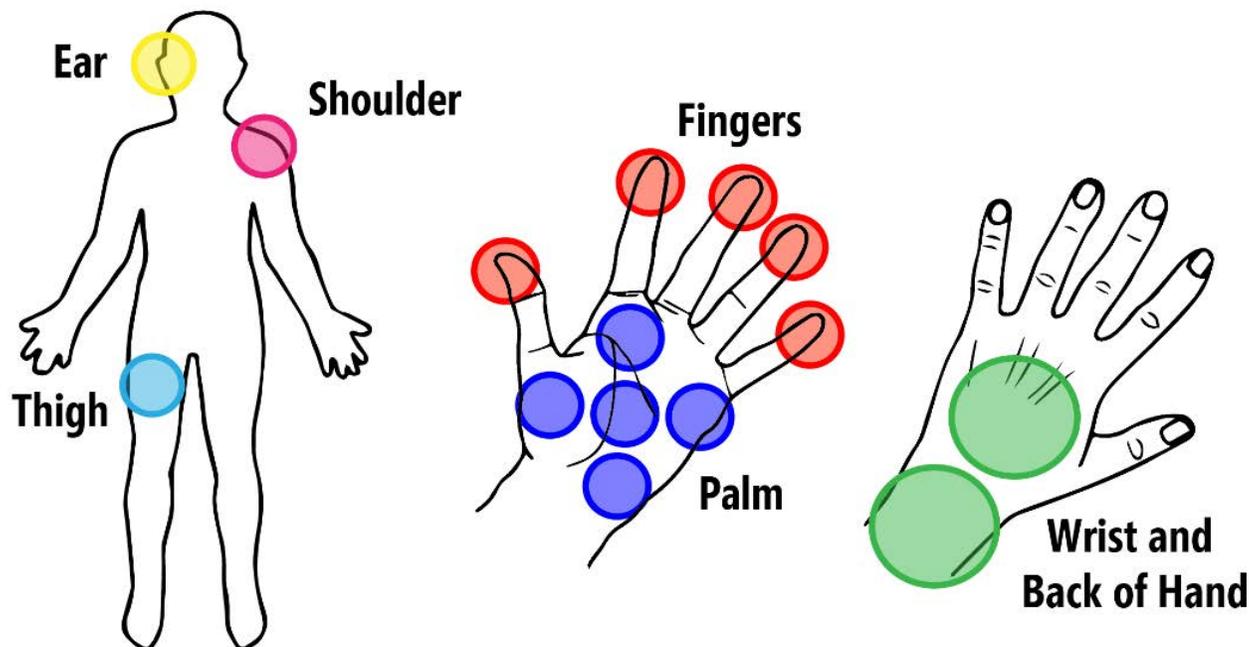
(6 classes: ● finger, ● palm, ● thigh, ...)

accuracy: **98.0%** ($SD=2.3\%$)

Fine-Grained Localization

(15 classes: ● palm up, ● palm down, ...)

accuracy: **88.7%** ($SD=7.0\%$)



ON-BODY STUDY I

EXPERIMENTS AND RESULTS

Within-Person Classification Experiment ($n=24$)

Coarse-Grained Localization

(6 classes: ● finger, ● palm, ● thigh, ...)

accuracy: **98.0%** ($SD=2.3\%$)

Fine-Grained Localization

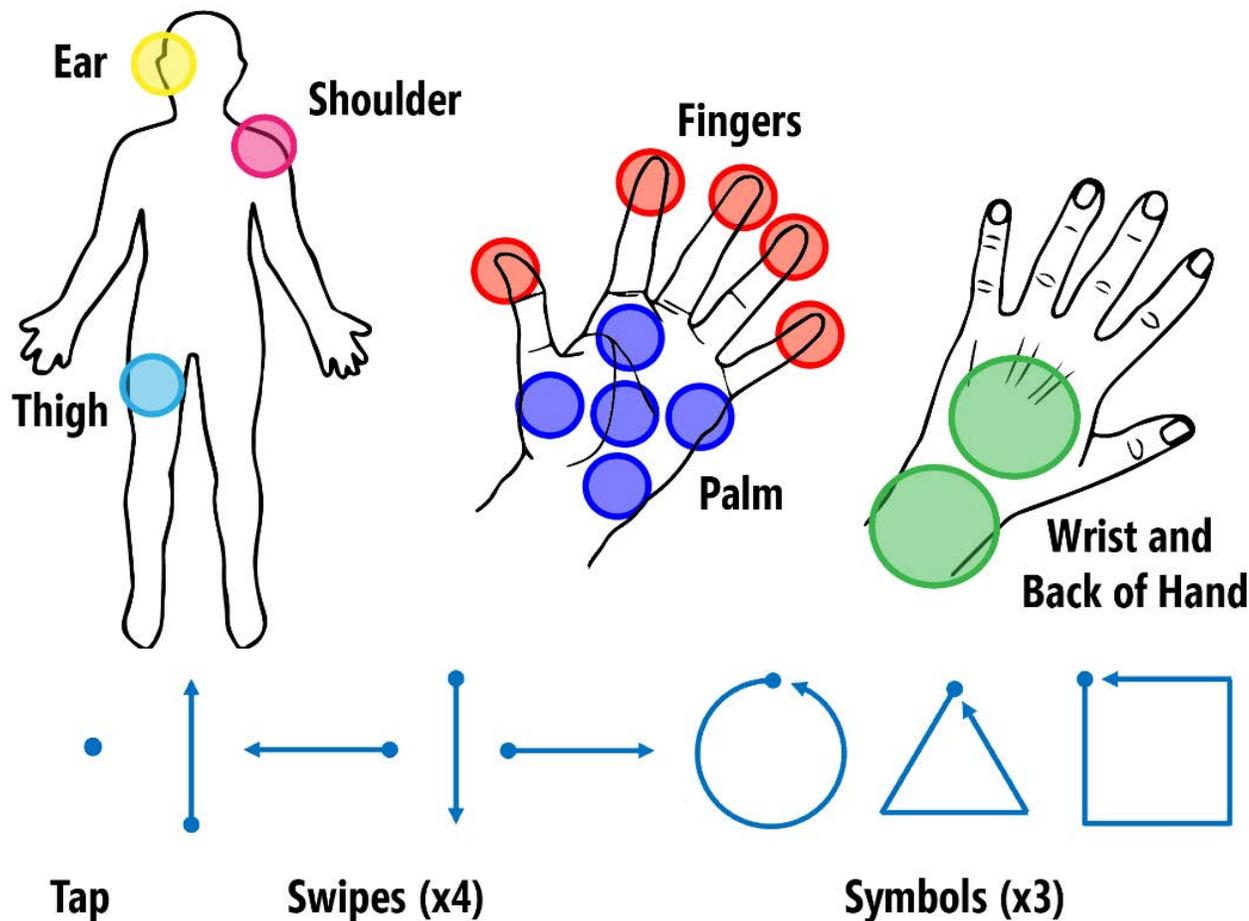
(15 classes: ● palm up, ● palm down, ...)

accuracy: **88.7%** ($SD=7.0\%$)

Location-Specific Gesture Recognition

(24 classes: 3 locations \times 8 gestures)

accuracy: **95.7%** ($SD=3.2\%$)



ON-BODY STUDY III

12 Participants:

7 female, 5 male

Ages 29-65

All blind or low vision

Uran Oh, **Lee Stearns**, Alisha Pradhan, Jon E. Froehlich, Leah Findlater, "**Investigating Microinteractions for People with Visual Impairments and the Potential Role of On-Body Interaction**," in *Proceedings of ASSETS 2017*.

Lee Stearns, Uran Oh, Leah Findlater, Jon E. Froehlich, "**TouchCam: Realtime Recognition of Location-Specific On-Body Gestures to Support Users with Visual Impairments**," in *Interactive, Wearable and Ubiquitous Technologies*, December 2018.

ON-BODY STUDY III

Algorithms

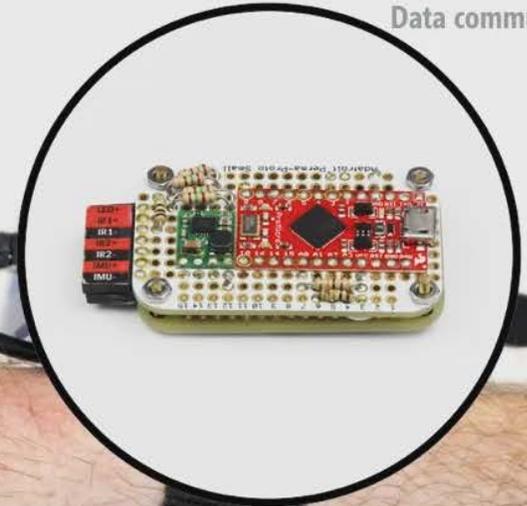
Real-time processing (~60fps)

- Removed geometric verification stage (required 1-2s *per image*)
- Combine predictions across 20 video frames (~300ms)
- Increase number of texture features per image from **1792** to **15,552**
- Reduced number of fine-grained locations (removed 5 fingertip classes)

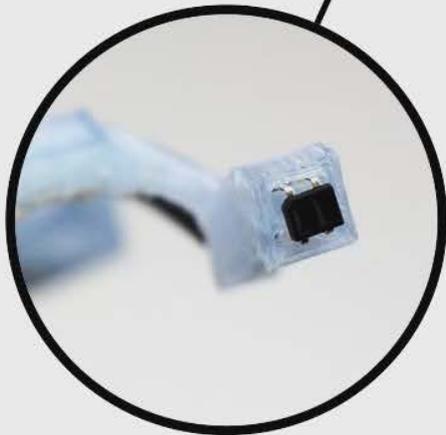
REALTIME PROTOTYPE



Camera and LED
Location detection



Microcontroller
Data communication and processing



IR Sensor (x2)
Touch event detection
and gesture segmentation



IMU
Gesture recognition

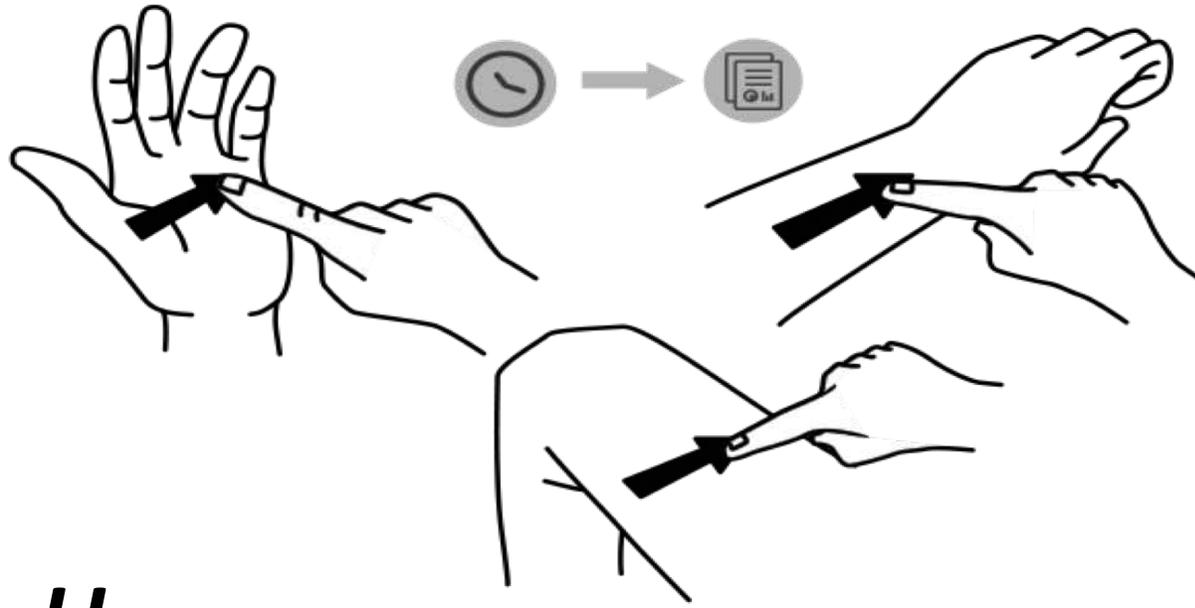


External Computer
Data processing, machine
learning, and power

INTERFACE DESIGNS

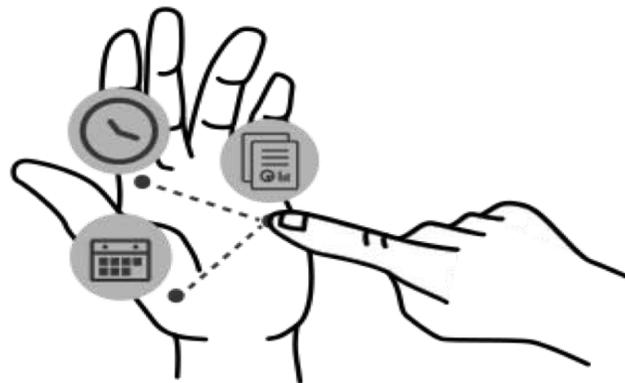
Five applications:

Clock, Daily Summary, Notifications, Health and Fitness, Voice Input



LI

Location-independent gestures



LS_{palm}

Location-specific gestures on the palm



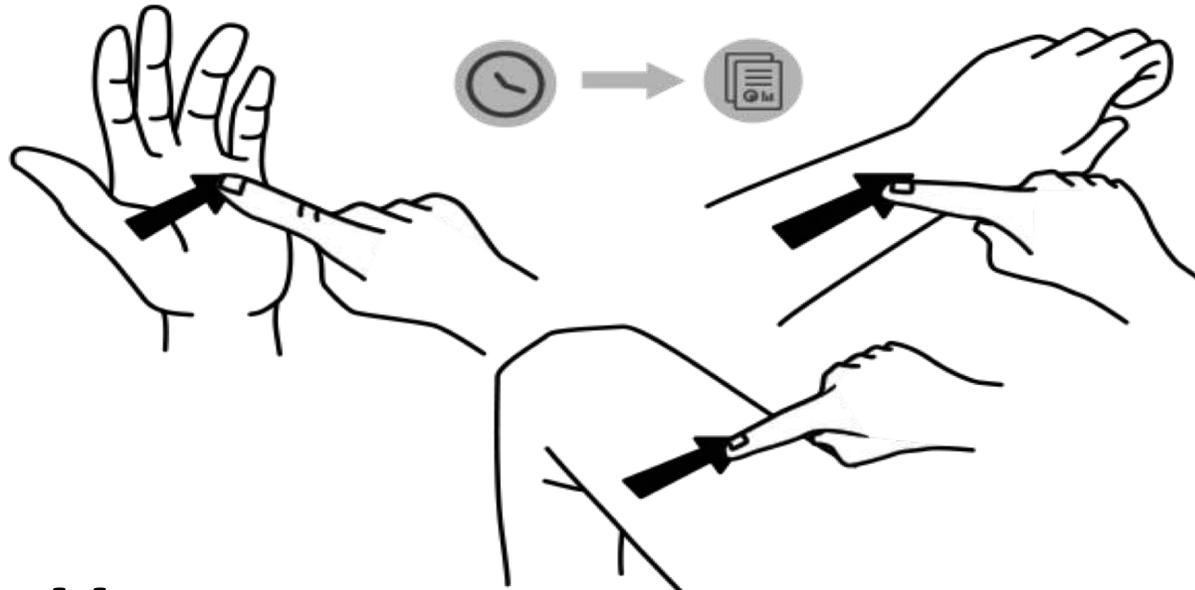
LS_{body}

Location-specific gestures on the body

INTERFACE DESIGNS

Five applications:

Clock, Daily Summary, Notifications, Health and Fitness, Voice Input



LI

Location-independent gestures



LS_{palm}

Location-specific gestures on the palm



LS_{body}

Location-specific gestures on the body



Health & Activities



Notifications



Daily Summary

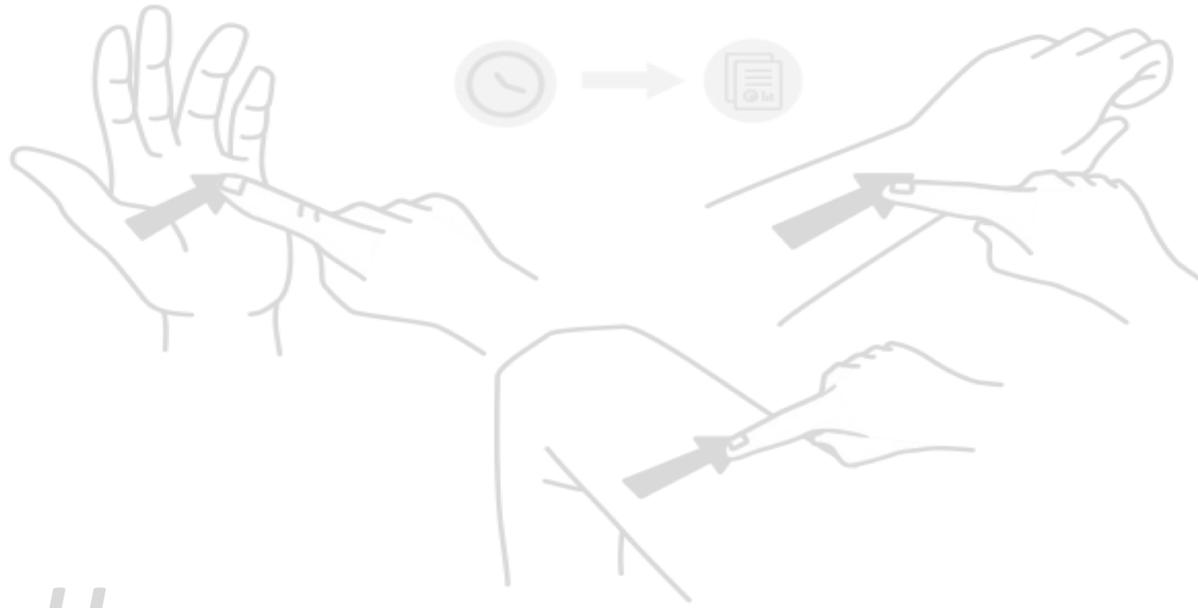
Interaction Design 1: Location-Independent Gestures

Swipe left and right anywhere on the body to sequentially navigate a list of applications.

INTERFACE DESIGNS

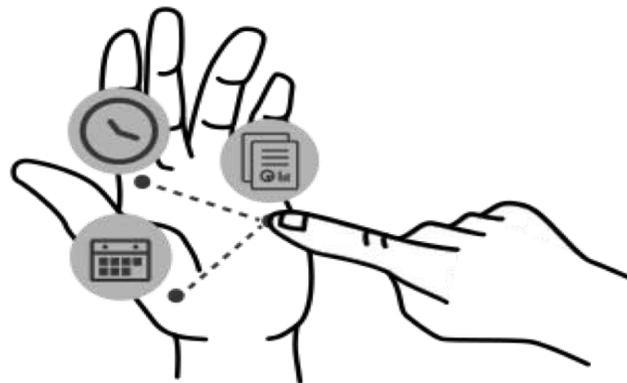
Five applications:

Clock, Daily Summary, Notifications, Health and Fitness, Voice Input



LI

Location-independent gestures



LS_{palm}

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LS_{body}

Location-specific gestures on the body



Voice Input



Health & Activities



Notifications

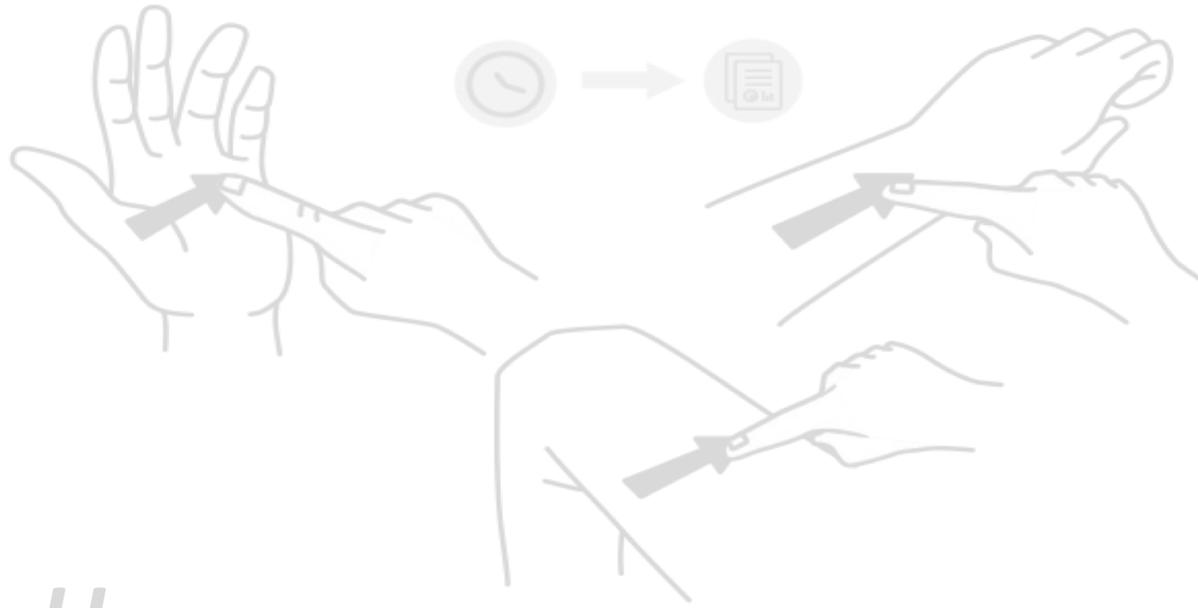
Interaction Design 2: Location-Specific Gestures on the Palm

Applications are mapped to five palm locations, select by directly touching a location. Supports "touch and explore".

INTERFACE DESIGNS

Five applications:

Clock, Daily Summary, Notifications, Health and Fitness, Voice Input



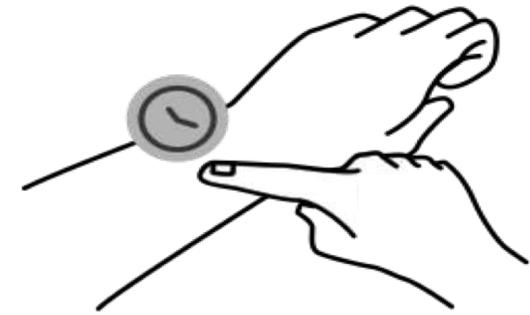
LI

Location-independent gestures



LS_{palm}

Location-specific gestures on the palm



LS_{body}

Location-specific gestures on the body



Notifications



Daily Summary



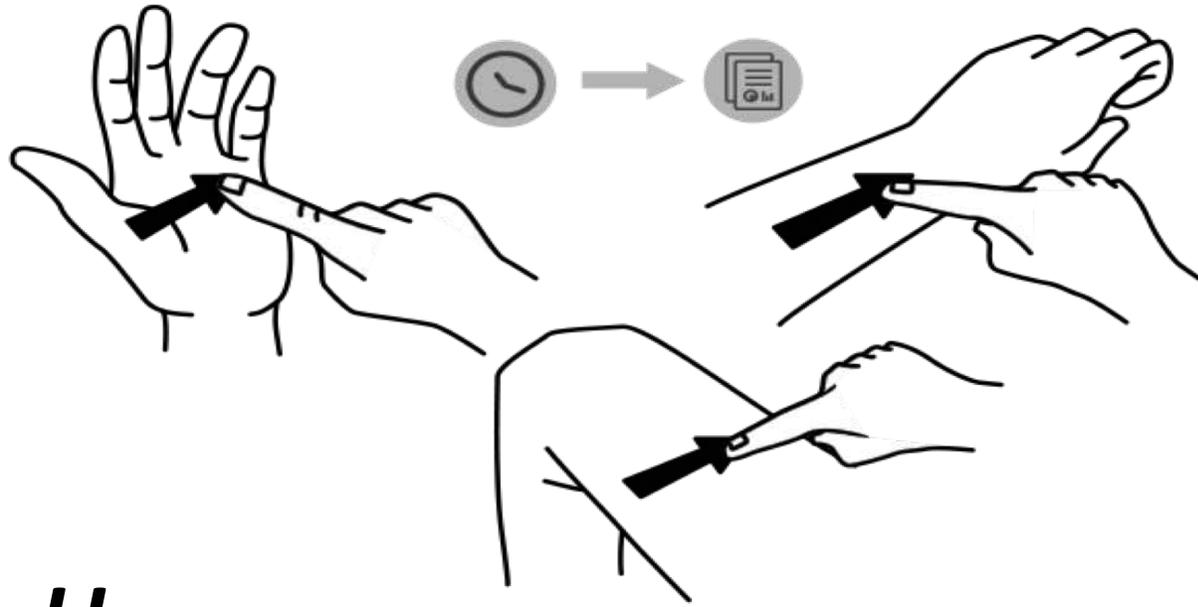
Clock

Interaction Design 3: Location-Specific Gestures on the Body

Applications are mapped to five body locations, semantically when possible. Touch to directly select application.

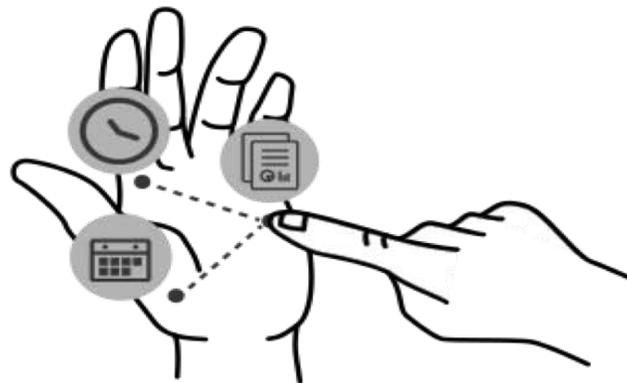
FINDINGS

(12 Visually Impaired Participants)



LI

Location-independent gestures



LS_{palm}

Location-specific gestures on the palm

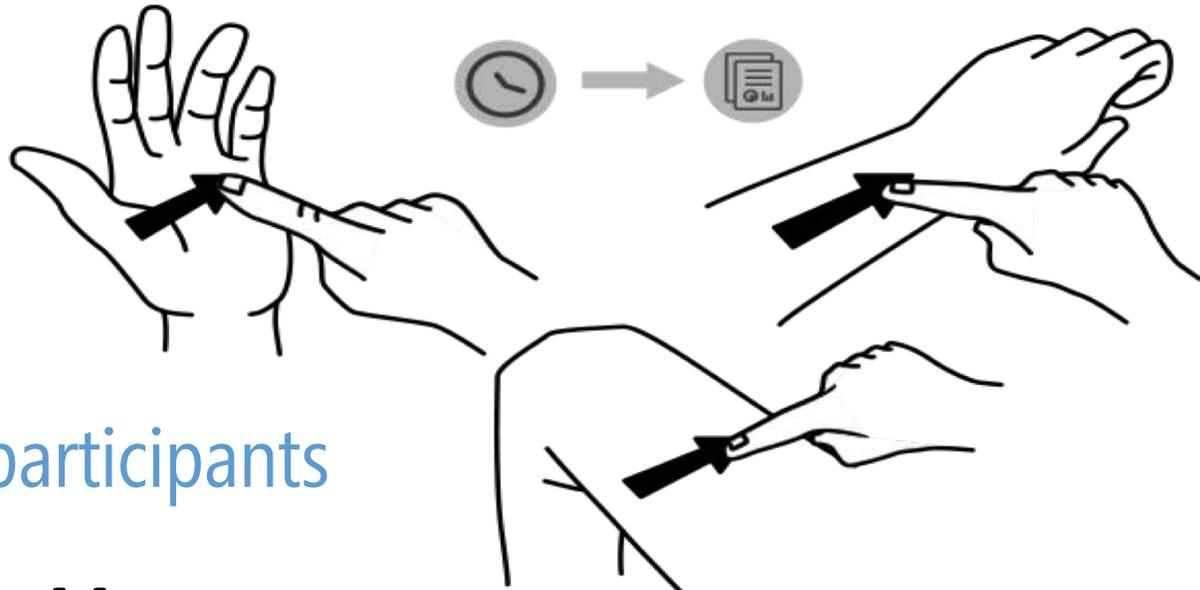


LS_{body}

Location-specific gestures
on the body

FINDINGS

(12 Visually Impaired Participants)



5 participants

LI

Location-independent gestures



LS_{palm}

Location-specific gestures on the palm

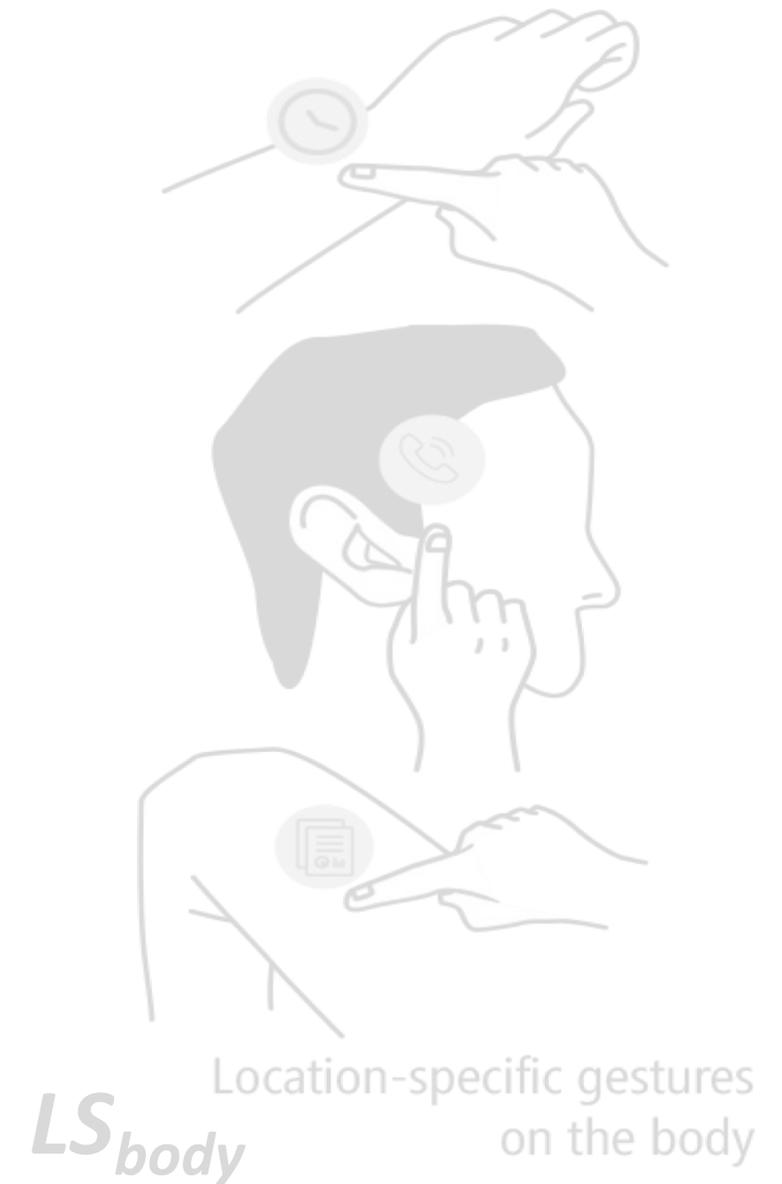
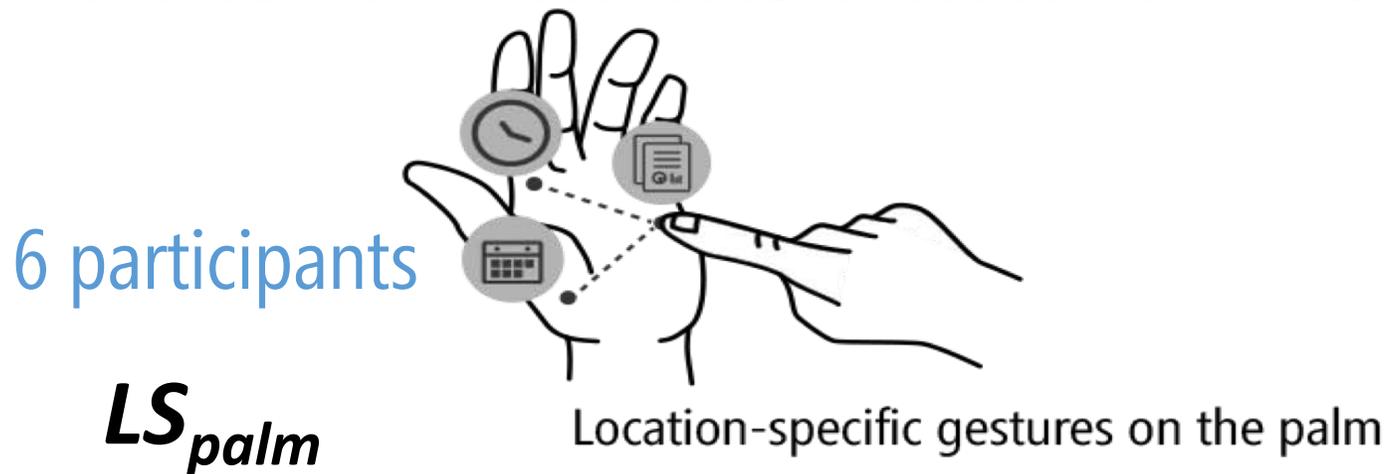
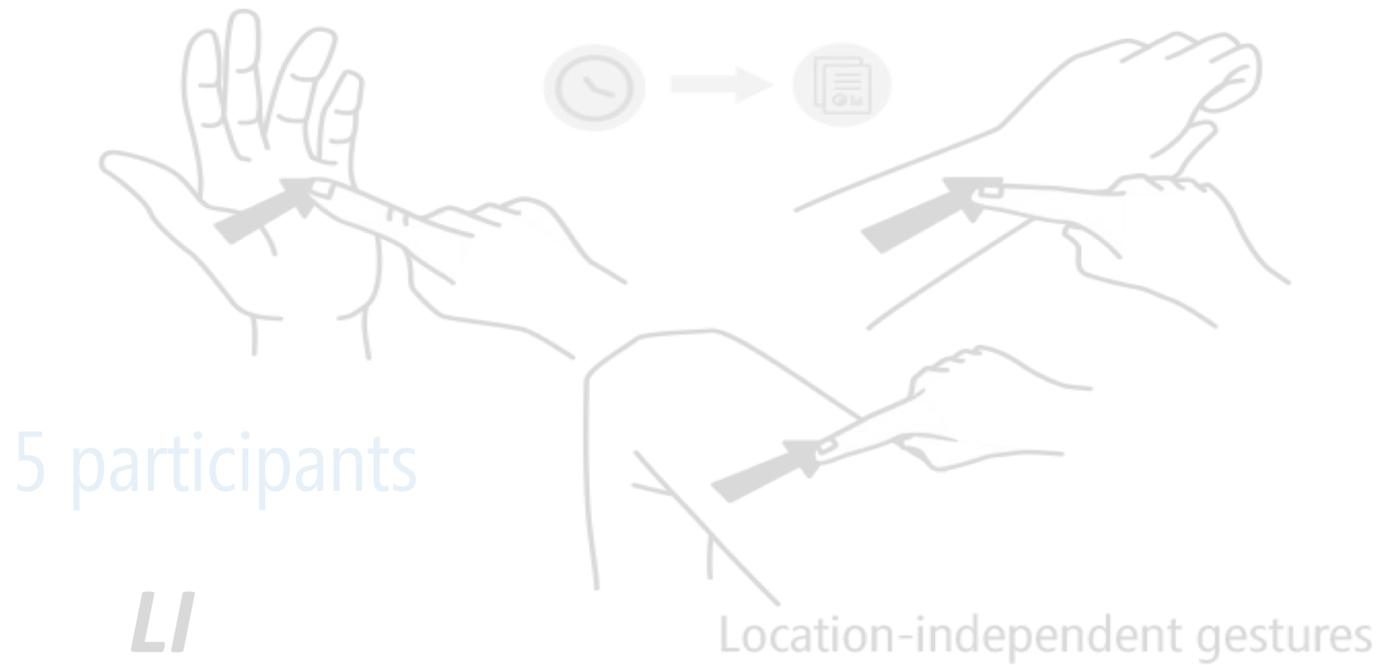


Location-specific gestures
on the body

LS_{body}

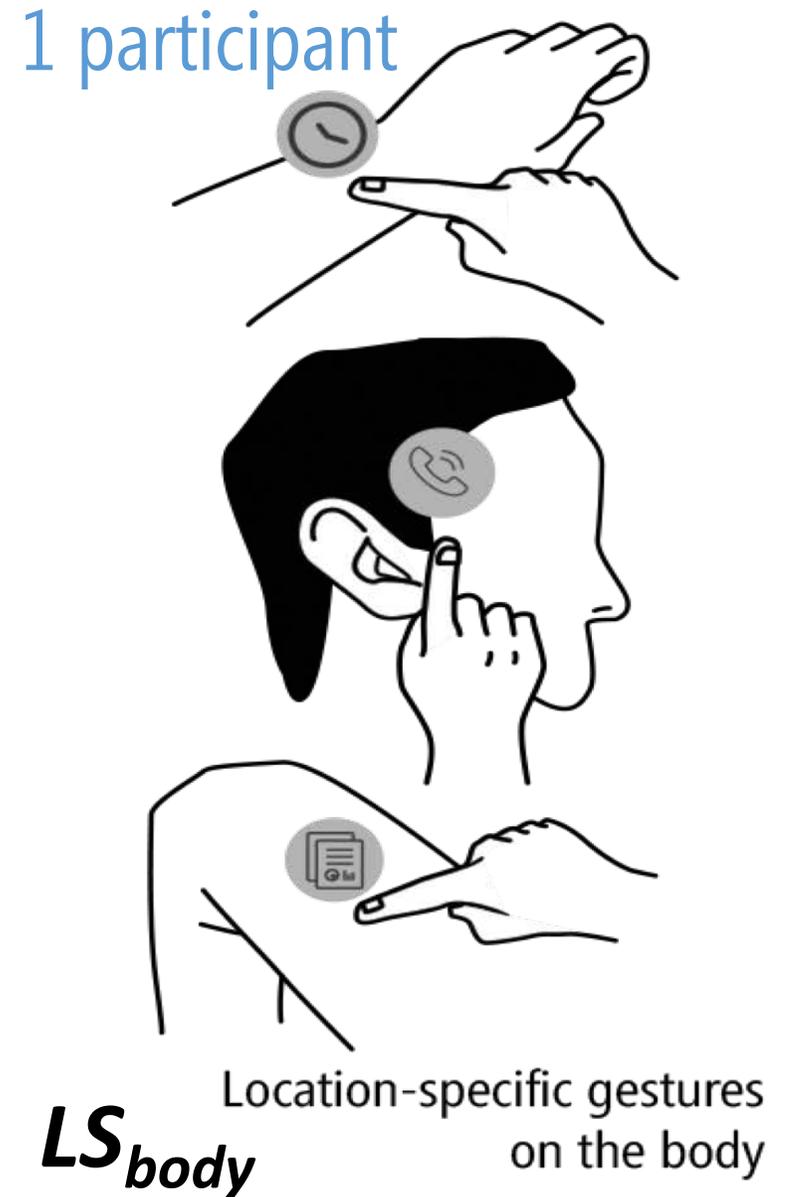
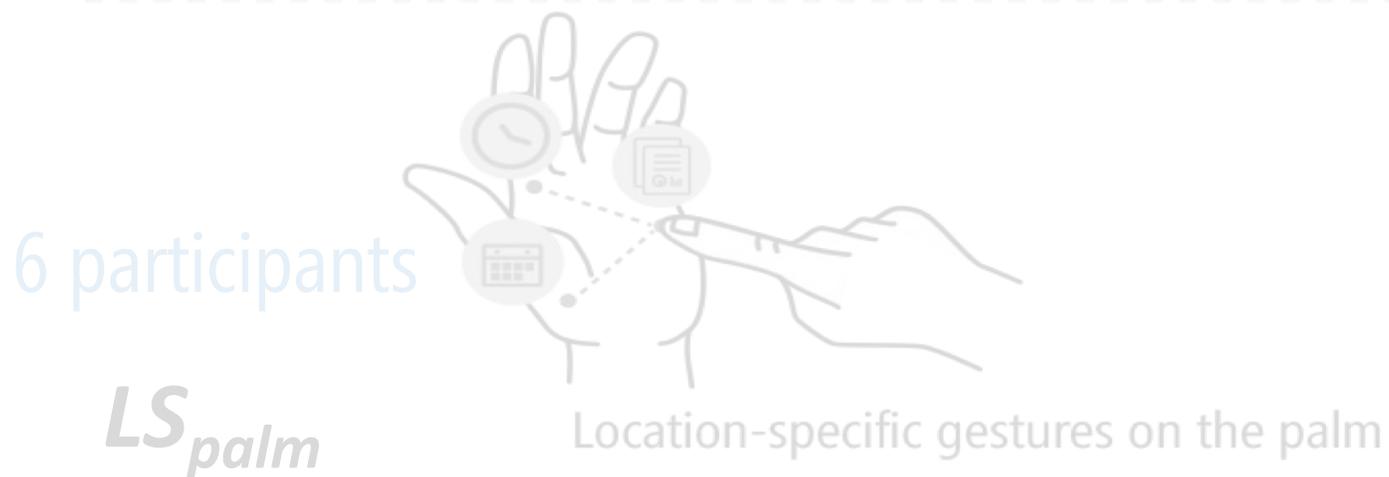
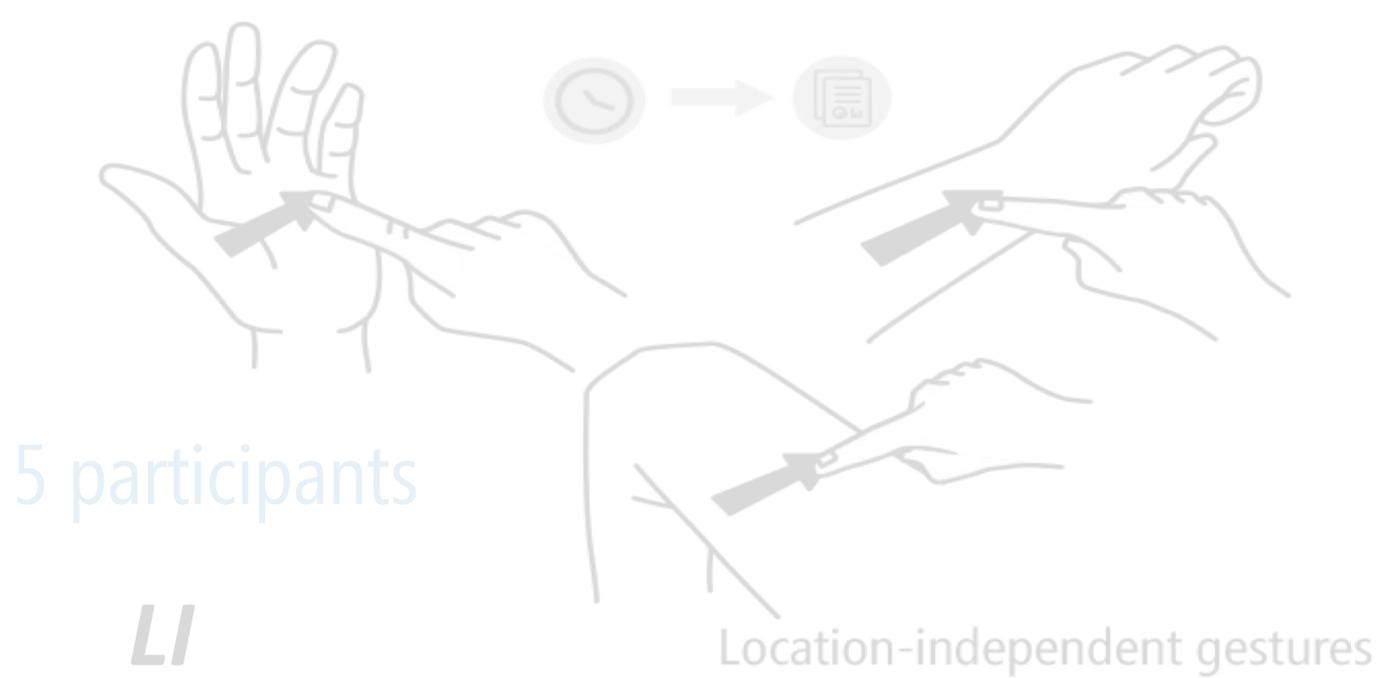
FINDINGS

(12 Visually Impaired Participants)



FINDINGS

(12 Visually Impaired Participants)



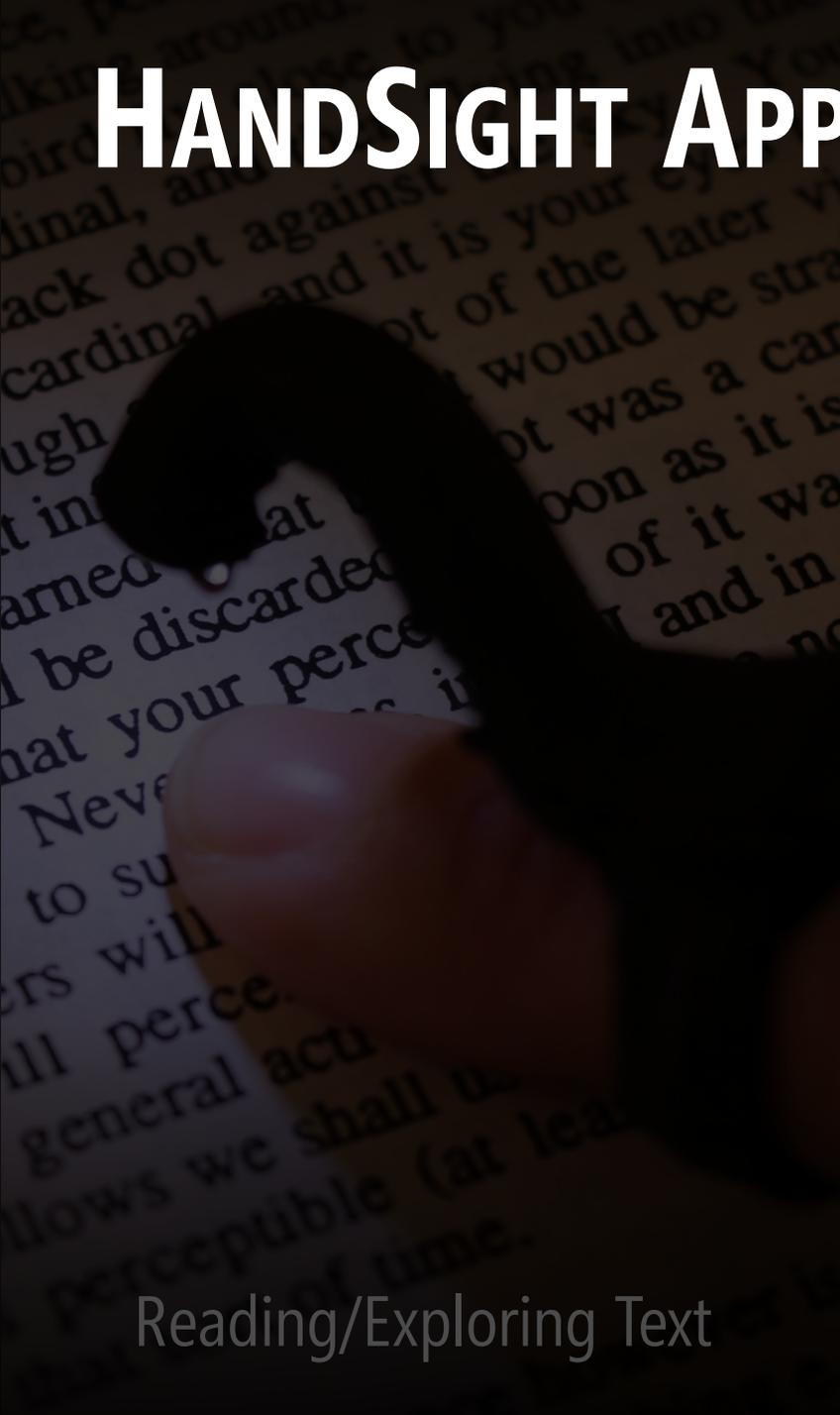
CONTRIBUTIONS

On-body input method using finger-worn sensors
Mitigates camera framing issues
New types of contextual, **location-specific gestures**

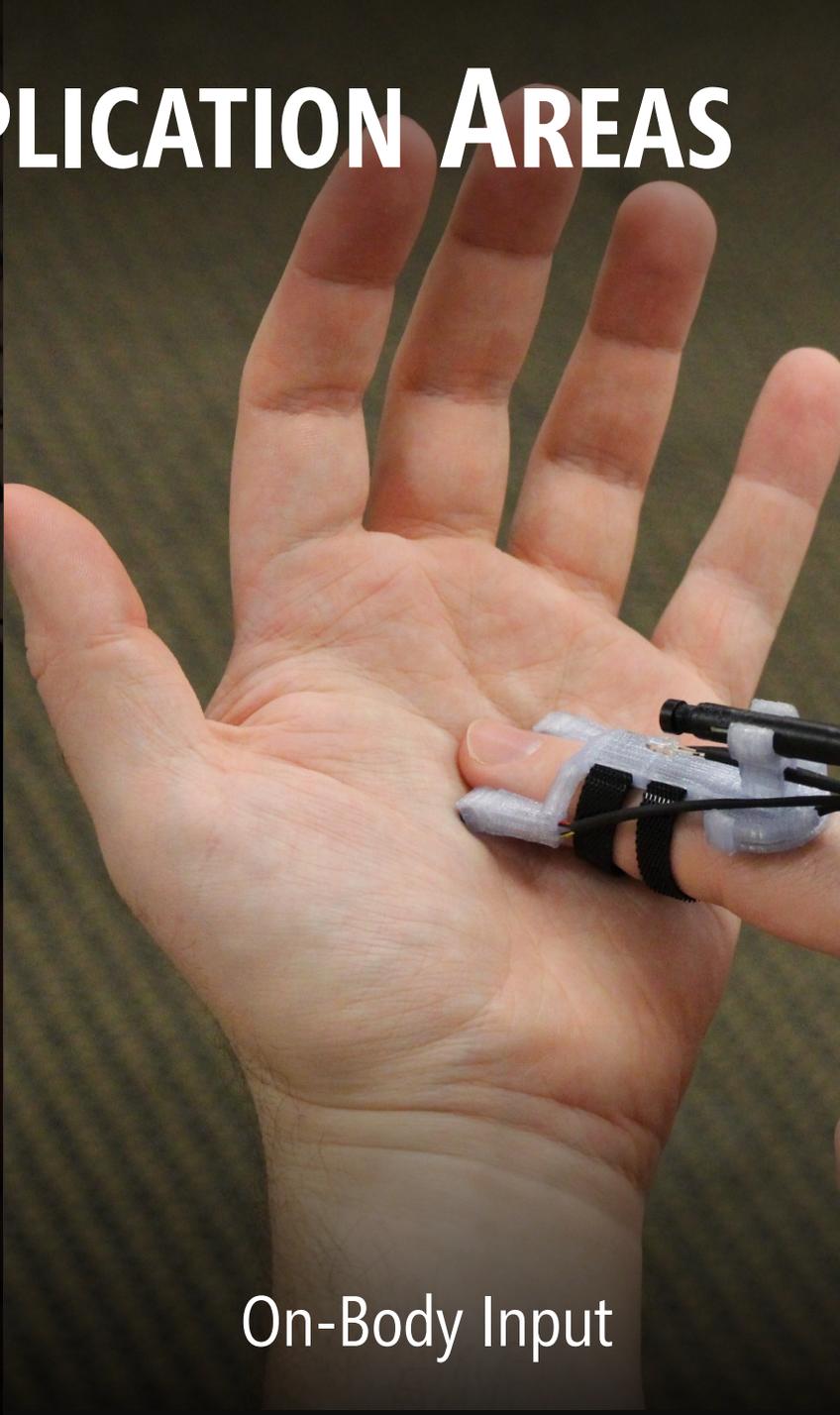
Our findings demonstrate feasibility, with **high accuracy** and **realtime performance**

We identified **tradeoffs** that will impact the design of future **on-body interfaces** (*e.g.*, accuracy, usability)

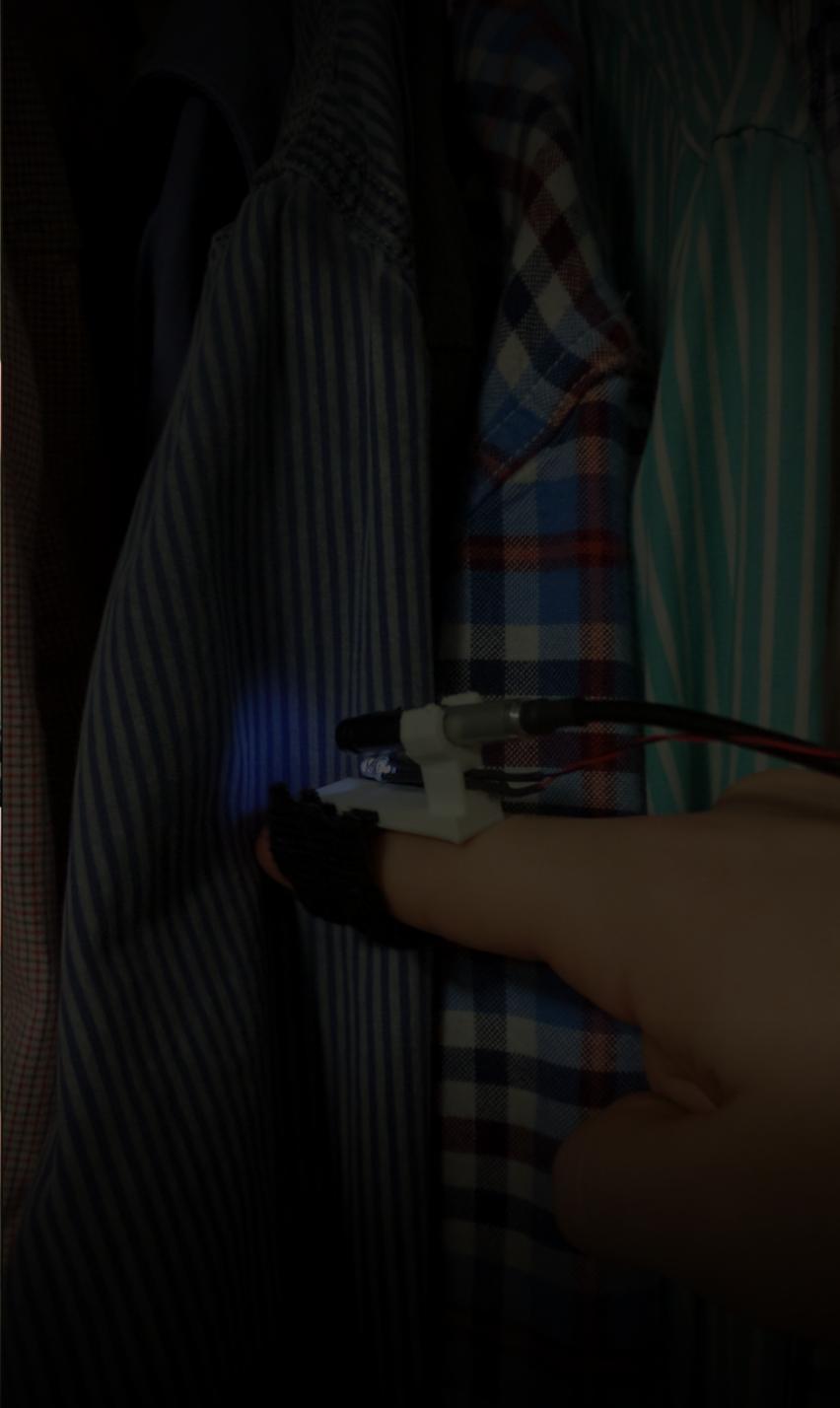
HANDSIGHT APPLICATION AREAS



Reading/Exploring Text



On-Body Input



On-Body Input

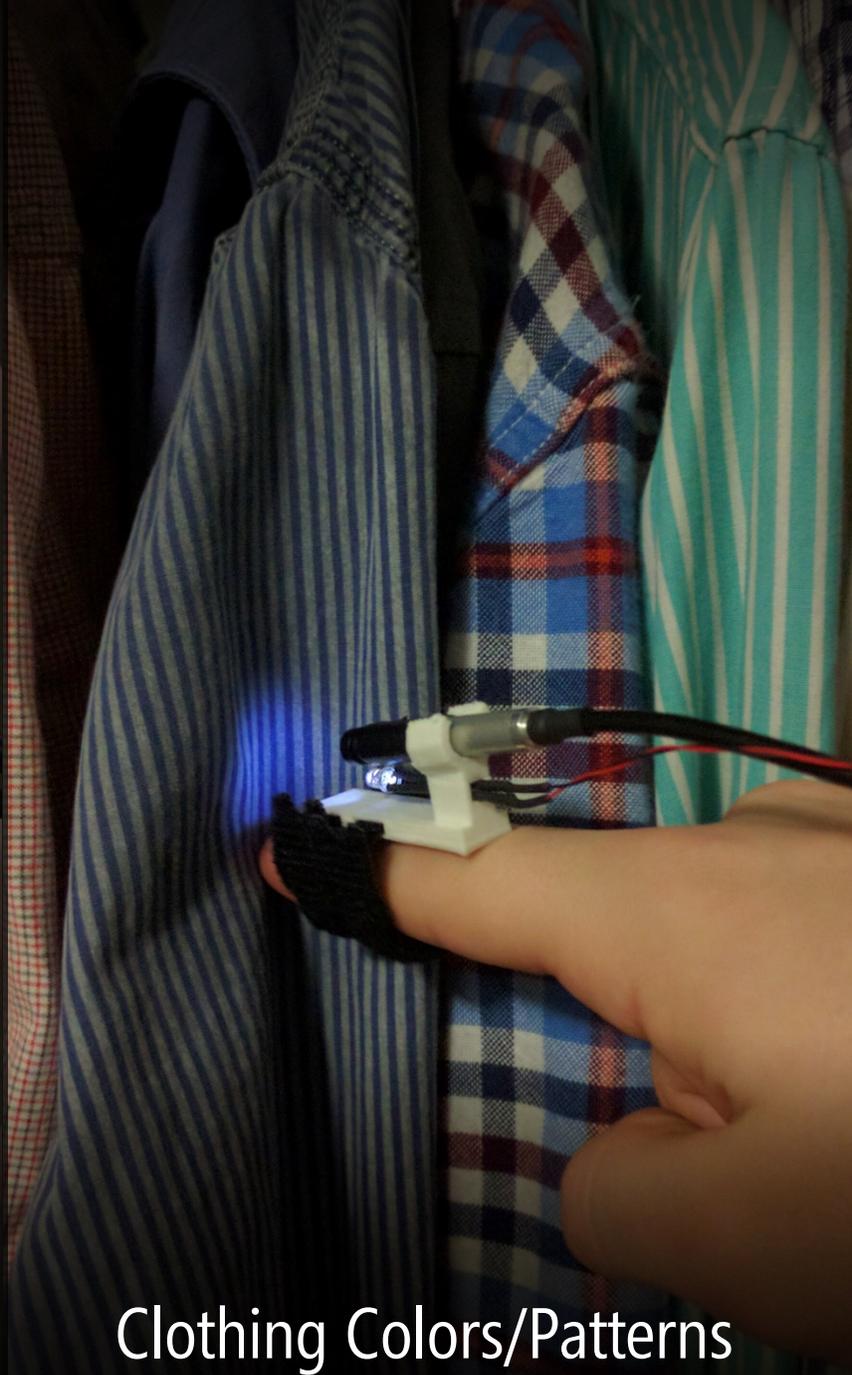
HANDSIGHT APPLICATION AREAS



Reading/Exploring Text



On-Body Input



Clothing Colors/Patterns

A close-up photograph showing two hands holding small, white, finger-mounted cameras. The cameras are positioned over various patterned fabrics, including a blue and white plaid shirt, a blue and white striped shirt, a red and white plaid shirt, and a red and white checkered shirt. The lighting is focused on the fabrics, highlighting their textures and colors. The background is dark, making the fabrics and the white cameras stand out.

IDENTIFYING CLOTHING COLORS AND PATTERNS

Alexander Medeiros, **Lee Stearns**, Leah Findlater, Chuan Chen, Jon E. Froehlich, "**Recognizing Clothing Colors and Textures using a Finger-Mounted Camera: An Initial Investigation**," in *ASSETS 2017 (Poster Track)*.

Lee Stearns, Leah Findlater, Jon E. Froehlich, "**Applying Transfer Learning to Recognize Clothing Patterns Using a Finger-Mounted Camera**," in *ASSETS 2018 (Poster Track, To Appear)*.

COMMERCIAL COLOR RECOGNIZERS



Brytec Color Teller



LedScope Android App



Colorino Color Identifier



Microsoft SeeingAI App

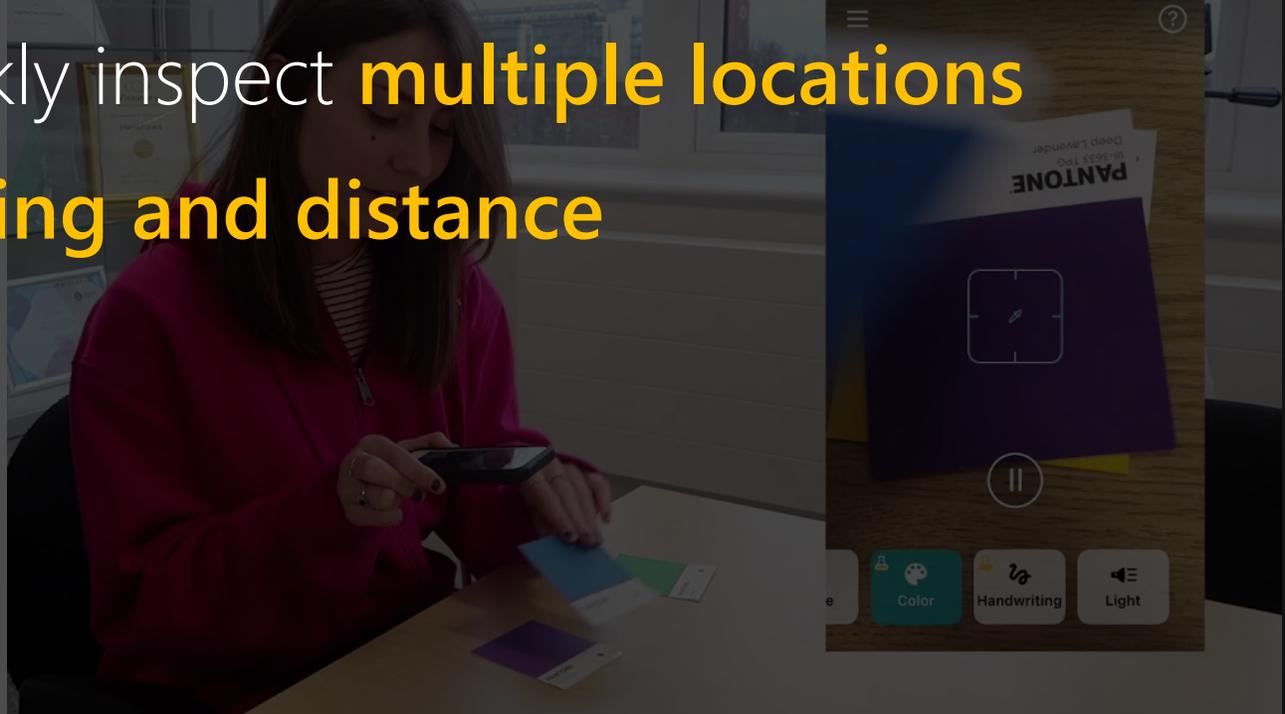
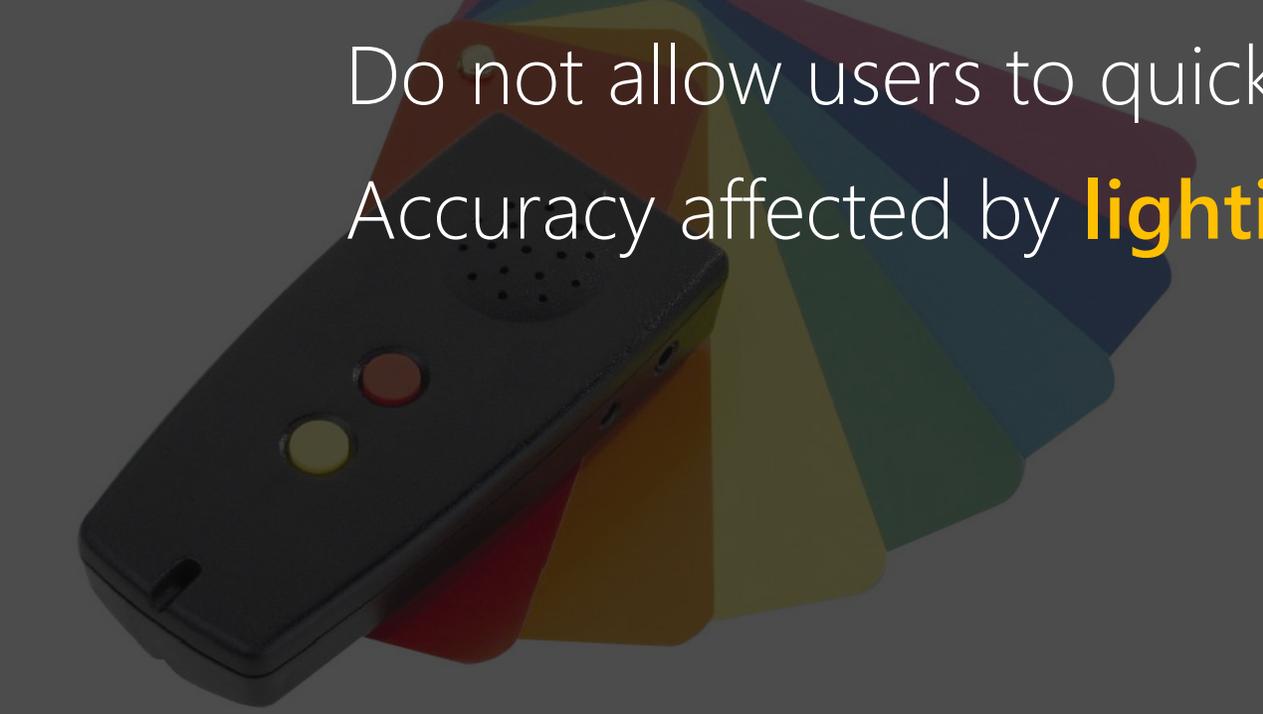
COMMERCIAL COLOR RECOGNIZERS

Limitations:

Cannot recognize **patterns**, only **color**

Do not allow users to quickly inspect **multiple locations**

Accuracy affected by **lighting and distance**

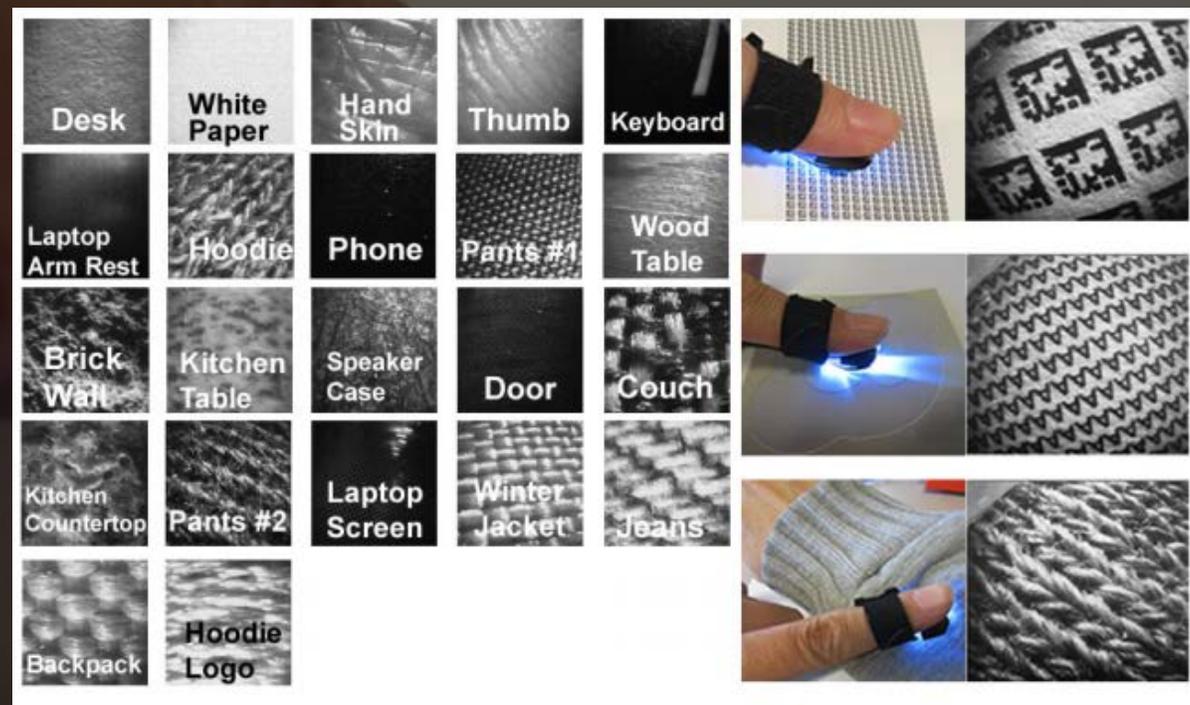
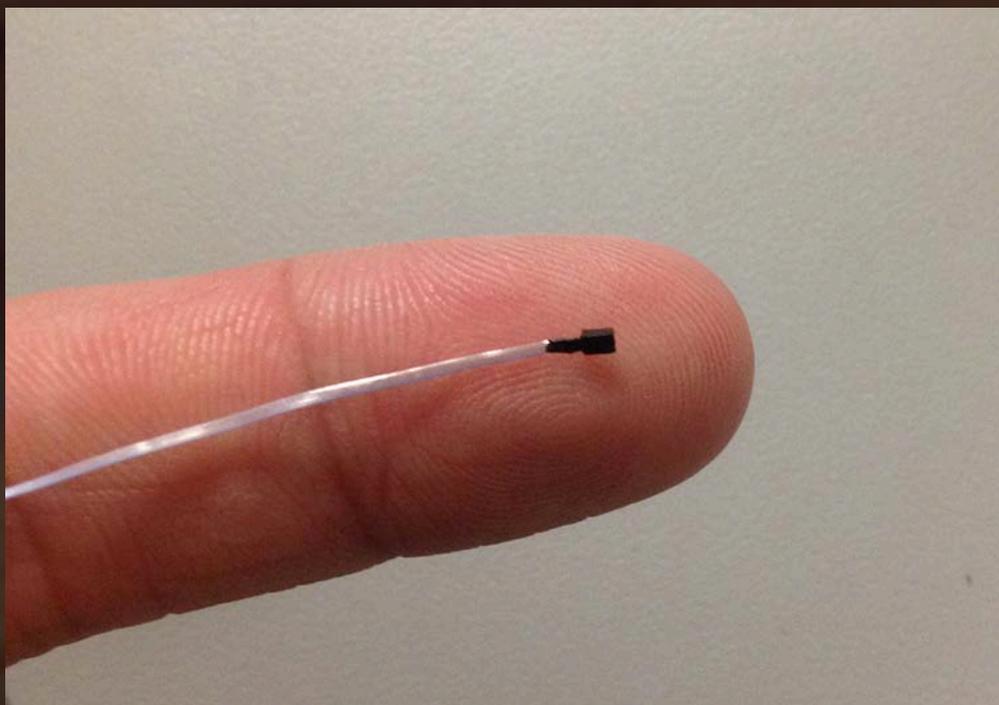


OTHER RELATED WORK



Access Lens: S. Kane, *et al.*, "Access lens: a gesture-based screen reader for real-world documents," in Proceedings of CHI 2013.

OTHER RELATED WORK



OTHER RELATED WORK



IDENTIFYING CLOTHING COLORS AND PATTERNS

Advantages of HandSight:

Can recognize visual patterns as well as color

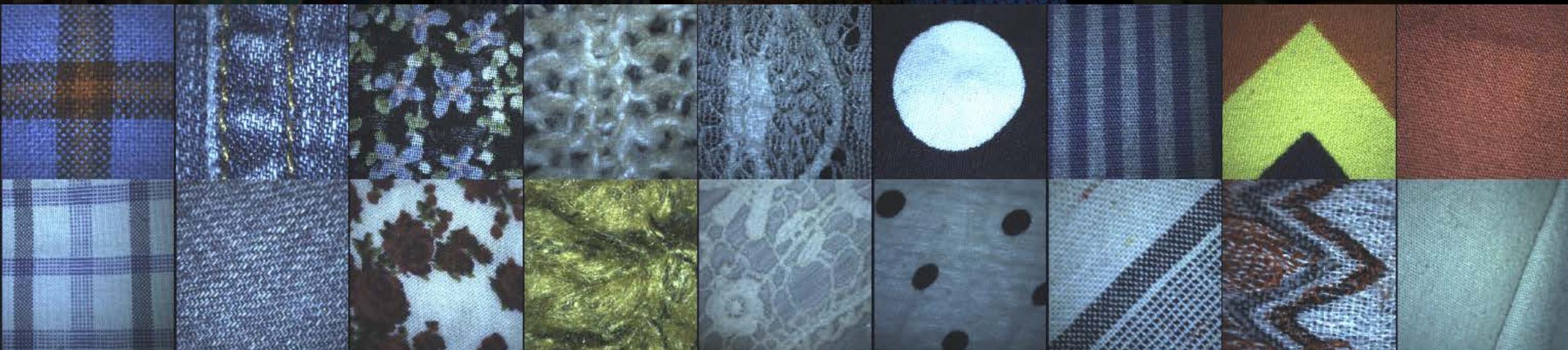
Constrains distance and lighting for consistent results

Allows for interactive exploration of colors and textures

HANDSIGHT CLOTHING PATTERN DATASET

Collected **520 images** across **29 articles of clothing** and **9 categories of pattern**

Controlled and varied the **distance** (5cm vs. 12cm), **rotation** (0° vs. 45°), **perspective** of the camera (90° vs. 45°), and the **tension** of the fabric (taut vs. hanging naturally)



Checked

Denim

Floral

Knitted

Lacelike

Polka-dotted

Striped

Zigzagged

None

PATTERN CLASSIFICATION

INITIAL EXPLORATION

Visual Texture Recognition Algorithms

* Adapted from Cimpoi, *et al.*, 2012

1. Deep convolutional activation features (DeCAF)

Adapt a pretrained object classifier from the **ImageNet Large Scale Visual Recognition Challenge**, removing last two layers used for classification and using the outputs as a raw feature vector (**4096 DeCAF features**).

PATTERN CLASSIFICATION

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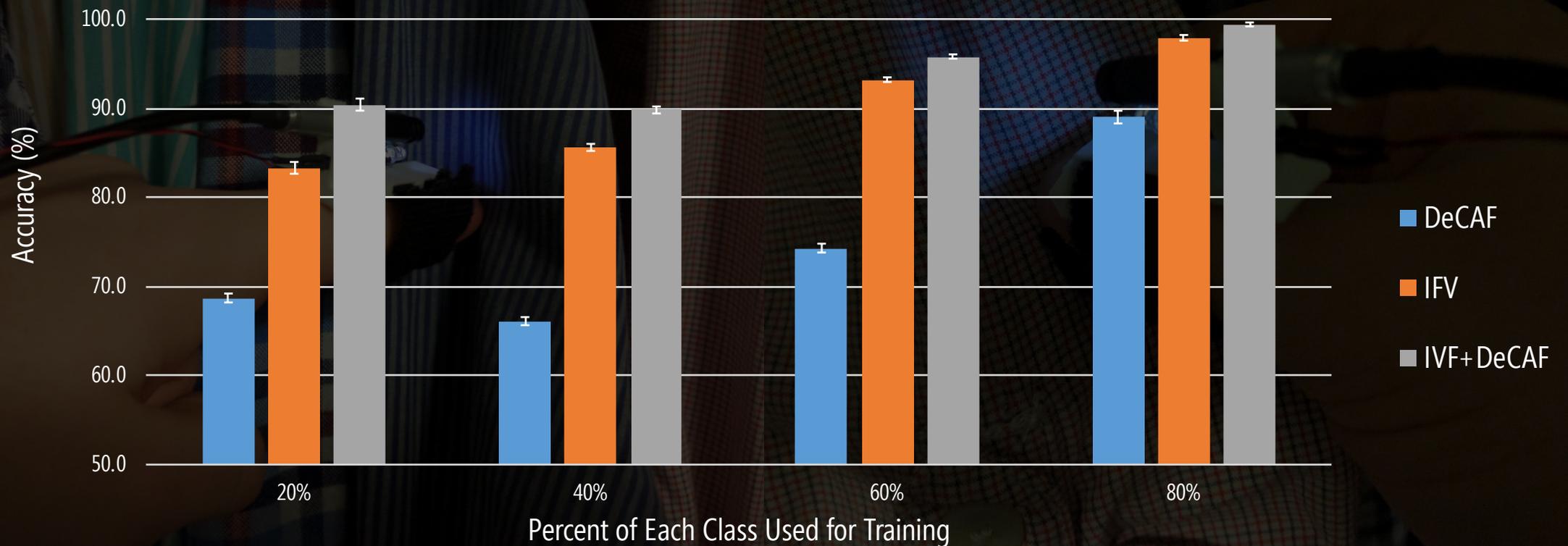
2. Dense SIFT features combined in an Improved Fisher Vector (IFV)

Extract scale invariant features densely at multiple scales, then combine using the **Improved Fisher Vector** formulation. Results in a complementary set of features that captures important texture information (**40,960 IFV features**)

PATTERN CLASSIFICATION

INITIAL EXPLORATION

Average Classification Accuracies



PATTERN CLASSIFICATION

INITIAL EXPLORATION

Highly controlled dataset—**risks overfitting, limits robustness**

Training process **not easily scalable**

ONLINE CLOTHING PATTERN DATASET

Built a larger and more varied dataset of images downloaded from **Google Images**
Focused only on **fabric patterns** that cannot easily be **distinguished by touch**



Solid

Striped

Checkered

Dotted

Zigzag

Floral

ONLINE CLOTHING PATTERN DATASET

Built a larger and more varied dataset of images downloaded from **Google Images**

Focused only on **fabric patterns** that cannot easily be **distinguished by touch**

Downloaded **top 1000 images** for each category (e.g., **"striped fabric"**)

After removing erroneous results, duplicates, and cropping logos/backgrounds,
contained **317–584 images per class (2764 total)**



Solid

Striped

Checkered

Dotted

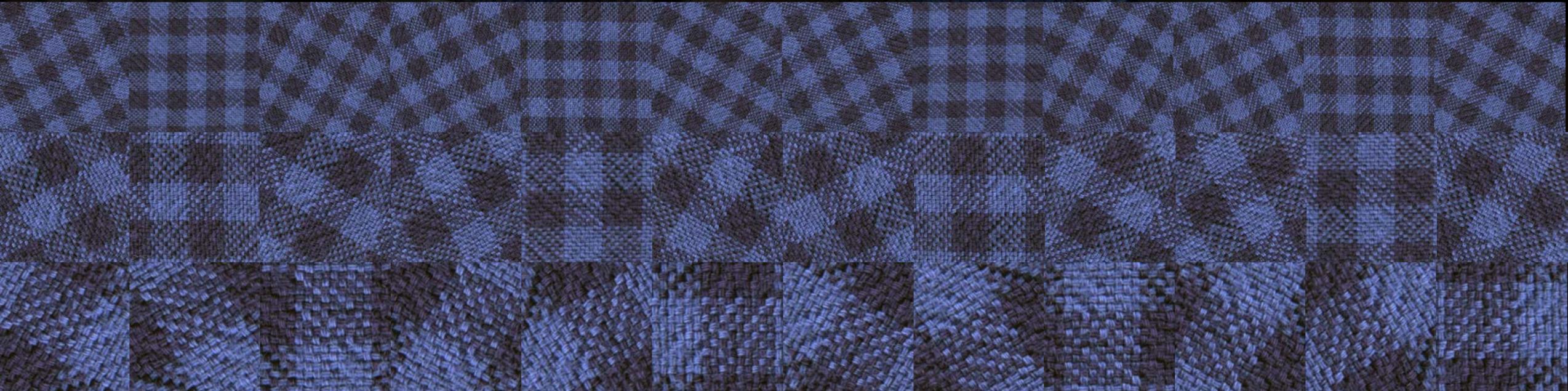
Zigzag

Floral

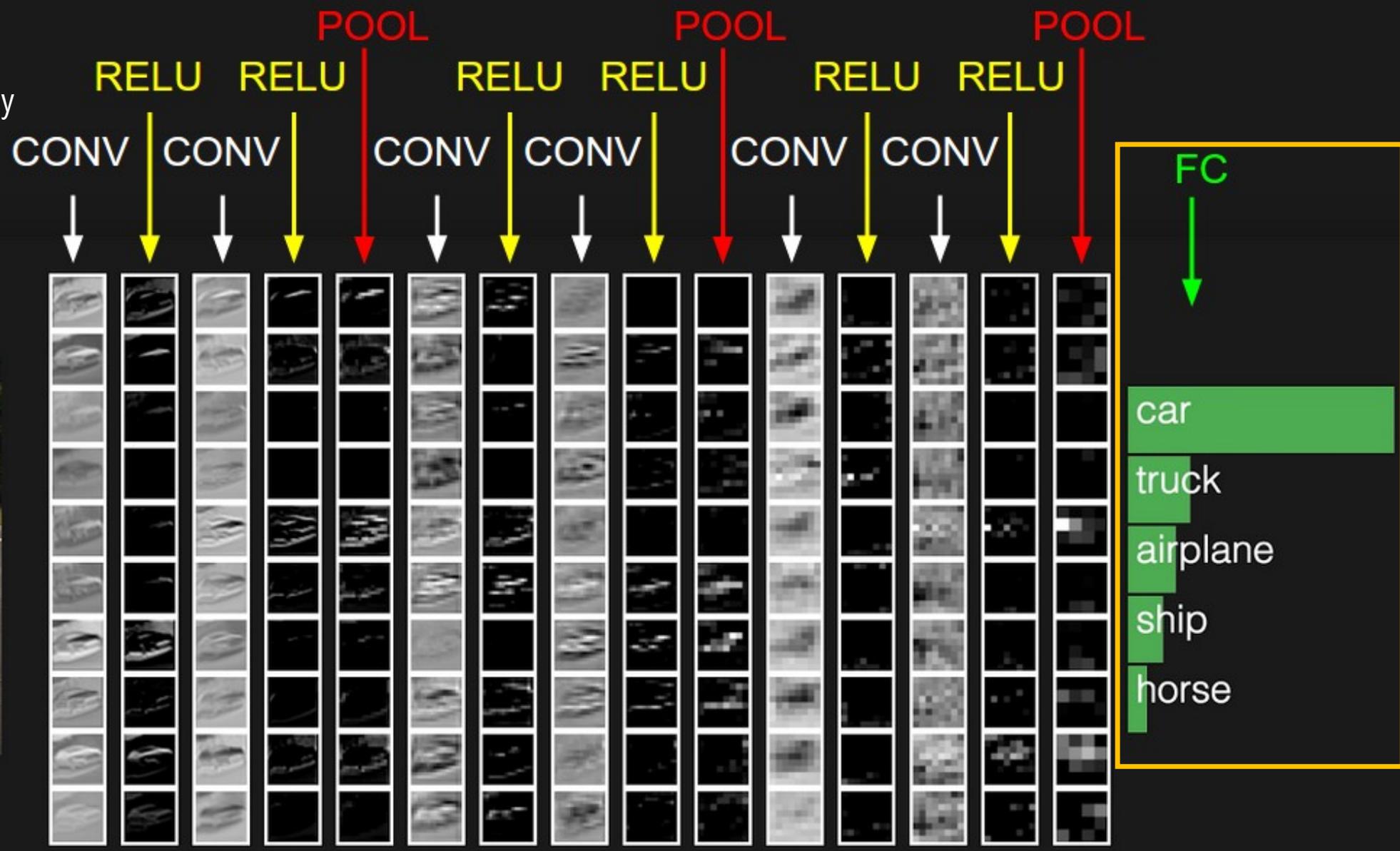
ONLINE CLOTHING PATTERN DATASET

Synthetic variations: **rotation** (30° increments), **scales** (1–4, depending on resolution)

Final dataset: 8,232–17,304 samples per class, 77,052 total



* Simplified visualization, actually used ResNet-101 architecture



PATTERN CLASSIFICATION

AN END-TO-END DEEP LEARNING APPROACH

Randomly sampled 6400 images per class for **training**, and 1600 for **testing**

Validation: classification accuracy on the test set was **91.7%**

Accuracy on HandSight dataset (400 images) was **72.8%**.

PATTERN CLASSIFICATION

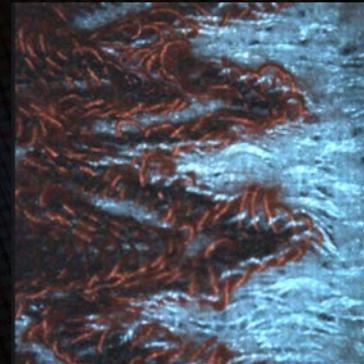
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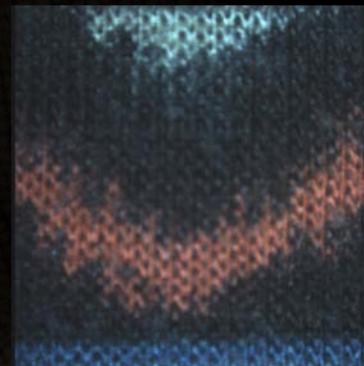
Fine-tuning the classifier with ~half of the HandSight images (N=36 per class) increases accuracy to **96.5%**



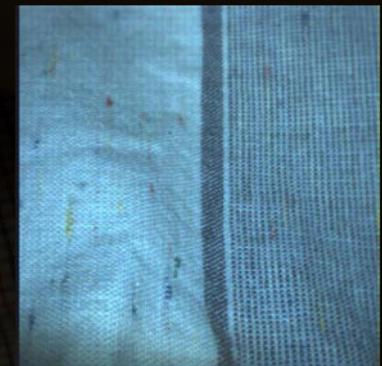
Zigzag → Floral



Striped → Checkered



Zigzag → Checkered



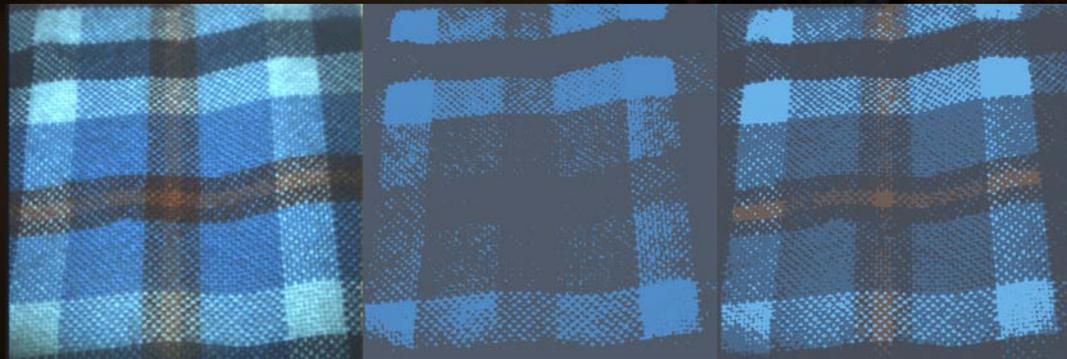
Striped → Solid

ONGOING WORK

IDENTIFYING CLOTHING COLORS

Identify **multiple colors** in a single image

Two methods: **K-means clustering** and **superpixel segmentation**



Original

k=2

k=4



Original

Superpixels

Color clusters

ONGOING WORK

IDENTIFYING CLOTHING COLORS

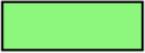
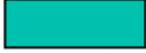
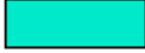
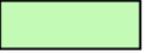
What is the best way to **convey** this information to **users**?

User-configurable level of detail:

Color names

Number of colors

Frequency of feedback

 purple (#7e1e9c)	 green (#15b01a)	 blue (#0343df)	 pink (#ff81c0)	 brown (#653700)	 red (#e50000)
 light blue (#95d0fc)	 teal (#029386)	 orange (#f97306)	 light green (#96f97b)	 magenta (#c20078)	 yellow (#ffff14)
 sky blue (#75bbfd)	 grey (#929591)	 lime green (#89fe05)	 light purple (#bf77f6)	 violet (#9a0eea)	 dark green (#033500)
 turquoise (#06c2ac)	 lavender (#c79fef)	 dark blue (#00035b)	 tan (#d1b26f)	 cyan (#00ffff)	 aqua (#13eac9)
 forest green (#06470c)	 mauve (#ae7181)	 dark purple (#35063e)	 bright green (#01ff07)	 maroon (#650021)	 olive (#6e750e)
 salmon (#ff796c)	 beige (#e6daa6)	 royal blue (#0504aa)	 navy blue (#001146)	 lilac (#cea2fd)	 black (#000000)
 hot pink (#ff028d)	 light brown (#ad8150)	 pale green (#c7fdb5)	 peach (#ffb07c)	 olive green (#677a04)	 dark pink (#cb416b)
 periwinkle (#8e82fe)	 sea green (#53fca1)	 lime (#aaff32)	 indigo (#380282)	 mustard (#ceb301)	 light pink (#ffd1df)

CONTRIBUTIONS

Two datasets of **fabric pattern images**

529 images collected systematically using HandSight.

77,052 images assembled from online sources and augmented synthetically (rotations, scaling, and cropping).

Preliminary algorithmic results demonstrating the feasibility of recognizing clothing patterns with a finger-worn camera.

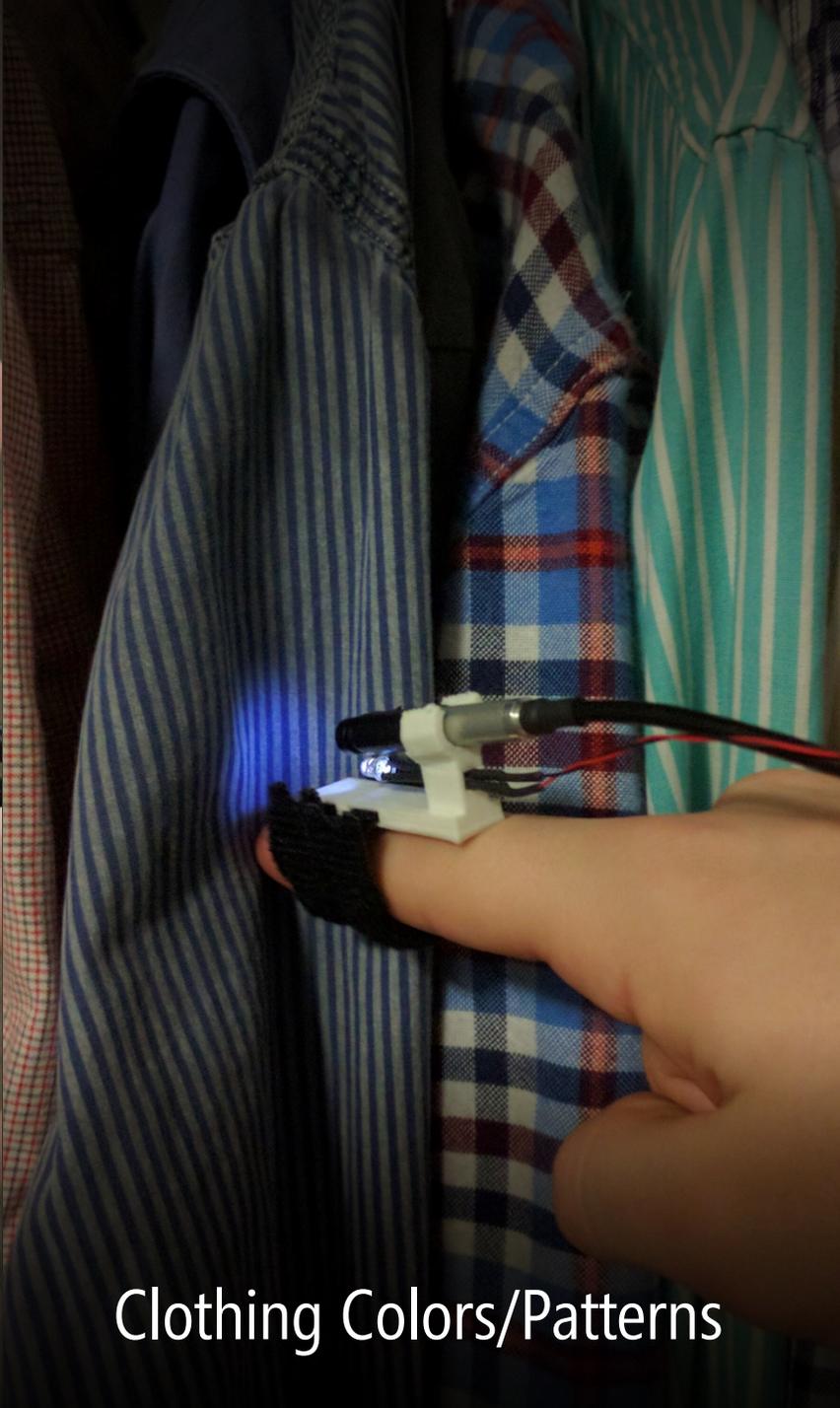
CONCLUSIONS AND FUTURE RESEARCH DIRECTIONS



Reading/Exploring Text



On-Body Input



Clothing Colors/Patterns

CONCLUSIONS AND FUTURE RESEARCH DIRECTIONS



ALTERNATIVE OR SUPPLEMENTARY CAMERA LOCATIONS

CONCLUSIONS AND FUTURE RESEARCH DIRECTIONS

Camera on the User's Finger or Wrist

Enables interactions anywhere the user can touch
Reduced issues with occlusion
Better resolution, more detail at the touch location
Simplified processing of content beneath finger
Easier to recognize relative gestures

Camera on the User's Upper Body

Wider field of view, more contextual information
Easier to localize and track hand/finger position
Can use larger, higher-fidelity hardware
Less likely to interfere with motion or touch sensitivity

ALTERNATIVE OR SUPPLEMENTARY CAMERA LOCATIONS

CONCLUSIONS AND FUTURE RESEARCH DIRECTIONS



SPATIAL EXPLORATION OF DOCUMENTS AND OTHER SURFACES

CONCLUSIONS AND FUTURE RESEARCH DIRECTIONS

1. SATAY (5)	7-95
2. MOO YANG (5)	7-95
3. CRISPY PORK ROLL (5)	4-95
4. CURRY PASTA (5)	5-45
5. GOLDEN TOFU (5)	8-45
6. FRIED CALAMARI (5)	9-45
7. KRA DOOM TONG (5)	7-95
8. CRISPY PORK WONTON (5)	8-45
9. CRISPY SHRIMP ROLL (5)	9-45
10. BKK CHICKEN WINGS (8)	7-95
1. TOD MUN (5)	7-95
2. KANOM JEEB (6)	7-95
3. LARB** (5)	7-95
4. NAM TOK** (5)	10-45
5. YUM PED YANG** (5)	10-45
6. YUM PLA GROB** (5)	10-45
7. YUM TALAY** (5)	7-95
8. YUM WOONSEN** (5)	7-95
9. YUM NUA** (5)	9-45
10. STEAM GREEN MUSSELS** (5)	9-45
11. ALL MARINATED SQUID (5)	7-95
12. A DADD DEOW (5)	7-95

13. BKK STEAK OR PORK (5)	7-95
14. N... (5)	7-95
15. GUI CHAI (2)	4-95
16. ... (5)	7-95
17. ... (5)	7-95
18. ... (5)	7-95
19. TOFU (5)	7-95
20. ... (5)	7-95
21. ... (5)	7-95
22. ... (5)	7-95
23. ... (5)	7-95
24. ... (5)	7-95
25. ... (5)	7-95
26. ... (5)	7-95
27. ... (5)	7-95
28. PC (5)	7-95
29. TOFU (5)	7-95
30. ... (5)	7-95
31. ... (5)	7-95
32. ... (5)	7-95
33. ... (5)	7-95

34. KRA POW*** (5)	11-95
35. PAD PED** (5)	11-95
36. GINGER & GINGER (5)	11-95
37. PAD PRIK KHING* (5)	11-95
38. SWEET & SOUR (5)	11-95
39. KRA TIEM PRIK TAI* (5)	11-95
40. BROCCOLI (5)	11-95
41. PAD WOONSEN (5)	11-95
42. PAD PAK (5)	11-95
43. PAD PRIK POW* (5)	11-95
44. PAD PED PAH** (5)	13-95
45. BEEF (5)	11-95
46. SHEW CHICKEN (5)	11-95
47. POAD LUN TAO (5)	13-95
48. MAH KUER* (5)	10-75

One Meat
One Seafood
Meat Combo
Seafood Combo
Vegetarian Choice

* Mild spicy

SPATIAL EXPLORATION OF DOCUMENTS AND OTHER SURFACES

CONCLUSIONS

AND FUTURE RESEARCH DIRECTIONS

SPATIAL EXPLORATION OF DOCUMENTS AND OTHER SURFACES

CONCLUSIONS

AND FUTURE RESEARCH DIRECTIONS



ALTERNATIVE FEEDBACK METHODS

TeslaTouch, Xu *et al.* 2011

CONCLUSIONS

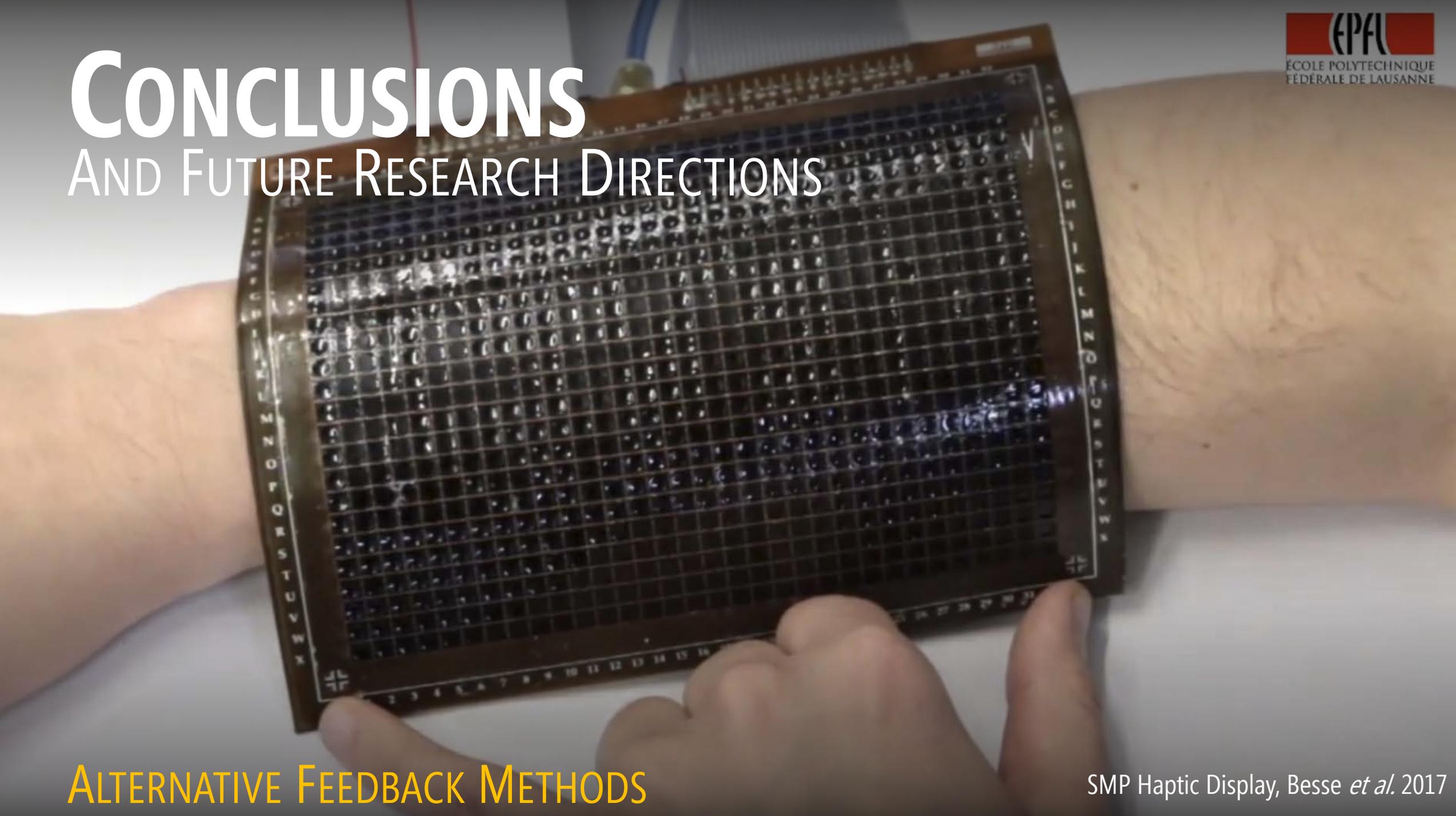
AND FUTURE RESEARCH DIRECTIONS



ALTERNATIVE FEEDBACK METHODS

Flexible Tactile Display, Choi *et al.* 2004

CONCLUSIONS AND FUTURE RESEARCH DIRECTIONS



A close-up photograph of a hand reaching into a closet to touch a piece of clothing. The hand is positioned in the center-right of the frame, with fingers gently touching a dark-colored garment with thin, light-colored horizontal stripes. The background is filled with various other clothes hanging on a rack, including a red garment, a blue and white striped garment, and a white garment. The lighting is warm and focused on the hand and the clothing it is touching.

CONCLUSIONS

AND FUTURE RESEARCH DIRECTIONS

EXTENSIONS TO OTHER USER POPULATIONS

CONCLUSIONS AND FUTURE RESEARCH DIRECTIONS

EXTENSIONS TO OTHER USER POPULATIONS

CONCLUSIONS AND FUTURE RESEARCH DIRECTIONS

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16. ... (5)	5-45
17. ... (5)	8-45
18. ... (5)	9-45
19. ... (5)	7-95
20. ... (5)	7-95
21. ... (5)	7-95
22. ... (5)	7-95
23. ... (5)	7-95
24. ... (5)	7-95
25. ... (5)	7-95
26. ... (5)	7-95
27. ... (5)	7-95
28. ... (5)	7-95
29. ... (5)	7-95
30. ... (5)	7-95
31. ... (5)	7-95
32. ... (5)	7-95
33. ... (5)	7-95

ENTREE	11-95
34. KRA POW*** (5)	11-95
35. PAD PED** (5)	11-95
36. GINGER & GINGER (5)	11-95
37. PAD PRIK KHING* (5)	11-95
38. SWEET & SOUR (5)	11-95
39. KRA TIEM PRIK TAI* (5)	11-95
40. BROCCOLI (5)	11-95
41. PAD WOONSEN (5)	11-95
42. PAD PAK (5)	11-95
43. PAD PRIK POW* (5)	11-95
44. PAD PED PAH** (5)	13-95
45. ... BEEF (5)	11-95
46. ... HEW CHICKEN (5)	11-95
47. ... POAD LUN TAO (5)	13-95
48. ... MAH KUER* (5)	10-75

EXTENSIONS TO OTHER USER POPULATIONS

CONCLUSIONS

AND FUTURE RESEARCH DIRECTIONS

A close-up photograph of a person's left hand held palm up. A second hand, likely belonging to a professional, is using the index finger to touch the center of the palm. The background is a dark, textured surface, possibly a wooden table. The lighting is soft, highlighting the skin tones and the texture of the palm.

EXTENSIONS TO OTHER USER POPULATIONS

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